LMK00338 8 输出差动时钟缓冲器/电平转换器

1 特性

- 3：1 输入多路复用器
  - 两个通用输入工作频率高达 400 MHz，并且接受低电压正射极耦合逻辑 (LVPECL)，低压差分信令 (LVDS)，电流模式逻辑 (CML)，短截线串联端接逻辑 (SSTL)，高速收发器逻辑 (HSTL)，主机时钟信号电平 (HCSL) 或单端时钟
  - 一个晶振输入可接受 10MHz 至 40MHz 的晶振或单端时钟
- 两组差分输出，每组 4 个
  - HCSL 或高阻抗 (Hi-Z)（每组可选）
  - 100MHz 时 PCIe Gen3 的附加相位抖动 (RMS)：
    - 30fs RMS（典型值）
- 156.25MHz 时为 -72 dBc
- 具有同步使能驶入的 LVCMOS 输出
- 由引脚控制的配置
- V_{CC}内核电源：3.3V ± 5%
- 3 个独立的 V_{CCO}输出电源：3.3V/2.5V ± 5%
- 工业温度范围：-40°C 至 +85°C
- 40 接线超薄型四方扁平无引线 (WQFN) 封装 (6mm x 6mm)

2 应用

- 针对模数转换器 (ADC)，数模转换器 (DAC)，多千兆以太网，XAUI，光纤通道，SATA/SAS，SONET/SDH，通用公共无线接口 (CPRI)，高频背板的时钟分配和电平转换
- 交换机、路由器、线路接口卡、定时卡
- 服务器，计算，快速 PCI (PCIe 3.0)
- 射频拉远单元和基站单元

3 说明

LMK00338 是一款 8 路输出 PCIe Gen1/Gen2/Gen3 扇出缓冲器，用于高频、低抖动时钟/数据分配和电平转换。 可从两个通用输入或一个晶振输入中选择输入时钟。 所选择的输入时钟被分配到两组 HCSL 输出（每组 4 个）和 1 个 LVCMOS 输出。 LVCMOS 输出具有同步使能输入，在使能或禁用后可实现无短脉冲运行。 LMK00338 由一个 3.3V 内核电源和 3 个独立的 3.3V/2.5V 输出电源供电运行。

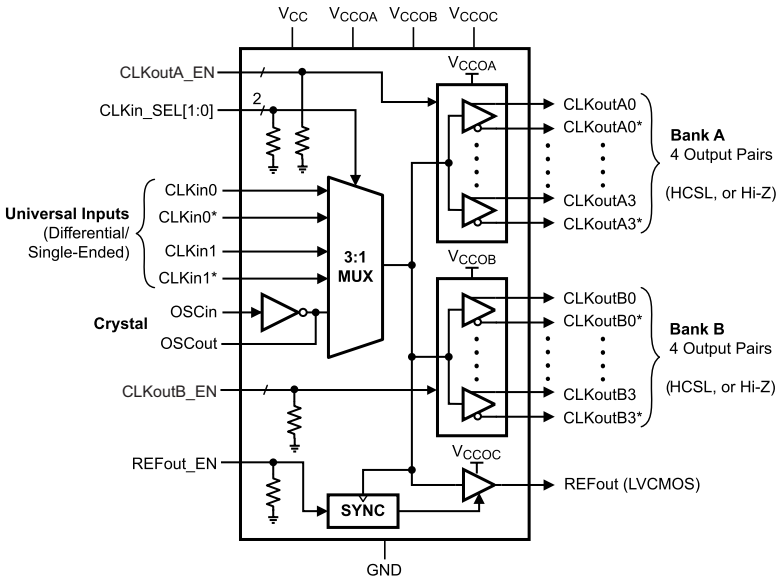
LMK00338 具有高性能、多用途和电源效率特性，这使得它成为替代固定输出缓冲器器件的理想选择，同时还能够增加系统中的时序余裕。

器件信息(1)

部件号	封装	封装尺寸（标称值）
LMK00338	WQFN (40)	6.00mm x 6.00mm

(1) 如需了解所有可用封装，请见数据表末尾的可订购产品附录。

LMK00338 功能方框图



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4 修订历史记录

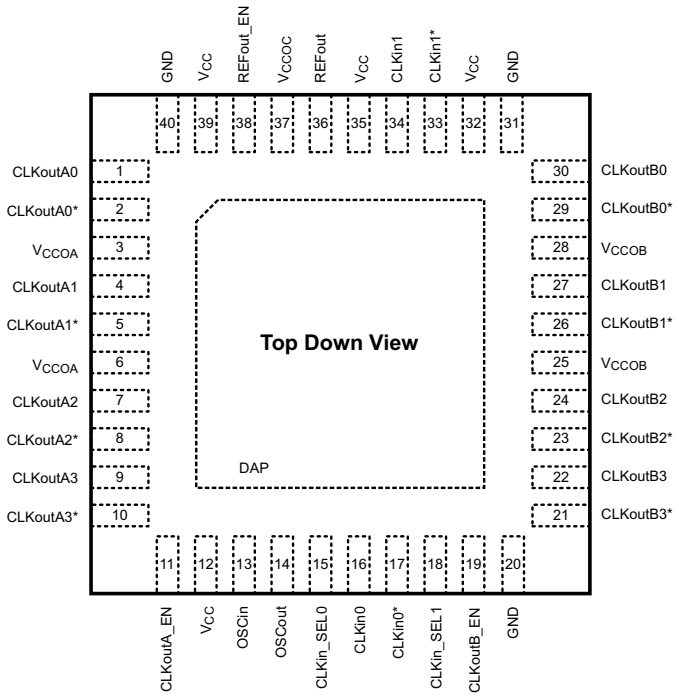
NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Original (December 2013) to Revision A **Page**

- 已添加、更新或重命名以下部分：器件信息表，*应用和实施*；*电源相关建议*；*布局*；*器件和文档支持*；*机械、封装和订购信息* ... 1
- Changed 1 MHz to 12 kHz ... 7
- Added Figure 24 ... 23

5 Pin Configuration and Functions

40-Pin
RTA0040A Package
Top View



Pin Functions[1]

PIN		TYPE	DESCRIPTION
NUMBER	NAME		
DAP	DAP	GND	Die Attach Pad. Connect to the PCB ground plane for heat dissipation.
1, 2	CLKoutA0, CLKoutA0*	O	Differential clock output A0.
3, 6	V_{CCOA}	PWR	Power supply for Bank A Output buffers. V_{CCOA} can operate from 3.3 V or 2.5 V. The V_{CCOA} pins are internally tied together. Bypass with a 0.1 uF low-ESR capacitor placed very close to each Vcco pin. [2]
4, 5	CLKoutA1, CLKoutA1*	O	Differential clock output A1.
7, 8	CLKoutA2, CLKoutA2*	O	Differential clock output A2.
9, 10	CLKoutA3, CLKoutA3*	O	Differential clock output A3.
11	CLKoutA_EN	I	Bank A low active output buffer enable[3]
12, 32, 35, 39	Vcc	PWR	Power supply for Core and Input buffer blocks. The Vcc supply operates from 3.3 V. Bypass with a 0.1 uF low-ESR capacitor placed very close to each Vcc pin.
13	OSCin	I	Input for crystal. Can also be driven by a XO, TCXO, or other external single-ended clock.
14	OSCout	O	Output for crystal. Leave OSCout floating if OSCin is driven by a single-ended clock.
15, 18	CLKin_SEL0, CLKin_SEL1	I	Clock input selection pins [3]
16, 17	CLKin0, CLKin0*	I	Universal clock input 0 (differential/single-ended)
19	CLKoutB_EN	I	Bank B low active output buffer enable[3]

(1) Any unused output pins should be left floating with minimum copper length (see note in *Clock Outputs*), or properly terminated if connected to a transmission line, or disabled/Hi-Z if possible. See *Clock Outputs* for output configuration or *Termination and Use of Clock Drivers* output interface and termination techniques.
(2) The output supply voltages/pins (V_{CCOA}, V_{CCOB}, and V_{CCOC}) will be referred to generally as V_{CCO} when no distinction is needed, or when the output supply can be inferred by the output bank/type.
(3) CMOS control input with internal pull-down resistor.

Pin Functions[1] (continued)

PIN		TYPE	DESCRIPTION
NUMBER	NAME		
20, 31, 40	GND	GND	Ground
21, 22	CLKoutB3*, CLKoutB3	O	Differential clock output B3.
23, 24	CLKoutB2*, CLKoutB2	O	Differential clock output B2.
25, 28	V_{CCOB}	PWR	Power supply for Bank B Output buffers. V_{CCOB} can operate from 3.3 V or 2.5 V. The V_{CCOB} pins are internally tied together. Bypass with a 0.1 uF low-ESR capacitor placed very close to each Vcco pin. [2]
26, 27	CLKoutB1*, CLKoutB1	O	Differential clock output B1.
29, 30	CLKoutB0*, CLKoutB0	O	Differential clock output B0.
33, 34	CLKin1*, CLKin1	I	Universal clock input 1 (differential/single-ended)
36	REFout	O	LVCMOS reference output. Enable output by pulling REFout_EN pin high.
37	V_{CCOC}	PWR	Power supply for REFout Output buffer. V_{CCOC} can operate from 3.3 V or 2.5 V. Bypass with a 0.1 uF low-ESR capacitor placed very close to each Vcco pin. [2]
38	REFout_EN	I	REFout enable input. Enable signal is internally synchronized to selected clock input. [3]

6 Specifications

6.1 Absolute Maximum Ratings(1)(2)

over operating free-air temperature range (unless otherwise noted) (3)

		MIN	MAX	UNIT
V_{CC}, V_{CCO}	Supply Voltages	-0.3	3.6	V
V_{IN}	Input Voltage	-0.3	(V_{CC} + 0.3)	V
T_{STG}	Storage Temperature Range			°C
T_L	Lead Temperature (solder 4 s)		+260	°C
T_J	Junction Temperature		+150	°C

(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but do not ensure specific performance limits. For ensured specifications and test conditions, see *Electrical Characteristics* . The ensured specifications apply only to the test conditions listed.
(2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.
(3) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

6.2 Handling Ratings

			MIN	MAX	UNIT
T_{stg}	Storage temperature range		-65	+150	°C
$V_{(ESD)}$	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all pins(1)		2000	V
		Machine model (MM)		150	
		Charged device model (CDM), per JEDEC specification JESD22-C101, all pins(2)		750	

(1) JEDEC document JEP155 states that 2000-V HBM allows safe manufacturing with a standard ESD control process.
(2) JEDEC document JEP157 states that 750-V CDM allows safe manufacturing with a standard ESD control process.

6.3 Recommended Operating Conditions

		MIN	TYP	MAX	UNIT
T_A	Ambient Temperature Range	-40	25	85	°C
T_J	Junction Temperature			125	°C
V_{CC}	Core Supply Voltage Range	3.15	3.3	3.45	V
V_{CCO}	Output Supply Voltage Range(1) (2)	3.3 – 5% 2.5 – 5%	3.3 2.5	3.3 + 5% 2.5 + 5%	V

(1) The output supply voltages/pins (V_{CCOA}, V_{CCOB}, and V_{CCOC}) will be referred to generally as V_{CCO} when no distinction is needed, or when the output supply can be inferred by the output bank/type.
(2) Vcco should be less than or equal to Vcc (Vcco ≤ Vcc).

6.4 Thermal Information

THERMAL METRIC(1)		LMK00338 RTA0040A 40 PINS(2)	UNIT
$R_{\theta JA}$	Junction-to-ambient thermal resistance	31.4	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	7.2 (DAP)	

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.
(2) Specification assumes 9 thermal vias connect the die attach pad (DAP) to the embedded copper plane on the 4-layer JEDEC board. These vias play a key role in improving the thermal performance of the package. It is recommended that the maximum number of vias be used in the board layout.

6.5 Electrical Characteristics

Unless otherwise specified: Vcc = 3.3 V ± 5%, Vcco = 3.3 V ± 5%, 2.5 V ± 5%, -40 °C ≤ T_A ≤ 85 °C, CLKin driven differentially, input slew rate ≥ 3 V/ns. Typical values represent most likely parametric norms at Vcc = 3.3 V, Vcco = 3.3 V, T_A = 25 °C, and at the Recommended Operation Conditions at the time of product characterization and are not ensured.(1)(2)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
CURRENT CONSUMPTION (3)							
ICC_CORE	Core Supply Current, All Outputs Disabled	CLKinX selected			8.5	10.5	mA
		OSCin selected			10	13.5	mA
ICC_HCSL					31	38.5	mA
ICC_CMOS					3.5	5.5	mA
ICCO_HCSL	Additive Output Supply Current, HCSL Banks Enabled	Includes Output Bank Bias and Load Currents for both banks, RT = 50 Ω on all outputs in bank			68	84	mA
ICCO_CMOS	Additive Output Supply Current, LVCMOS Output Enabled	200 MHz, C_L = 5 pF	Vcco = 3.3 V ±5%		9	10	mA
			Vcco = 2.5V ± 5%		7	8	mA
POWER SUPPLY RIPPLE REJECTION (PSRR)							
$PSRR_{HCSL}$	Ripple-Induced Phase Spur Level(4) Differential HCSL Output		156.25 MHz		-72		dBc
			312.5 MHz		-63		
CMOS CONTROL INPUTS (CLKin_SELn, CLKout_TYPEn, REFout_EN)							
V_{IH}	High-Level Input Voltage			1.6		Vcc	V
V_{IL}	Low-Level Input Voltage			GND		0.4	V
I_{IH}	High-Level Input Current	V_{IH} = V_{cc}, Internal pull-down resistor				50	µA
I_{IL}	Low-Level Input Current	V_{IL} = 0 V, Internal pull-down resistor		-5	0.1		µA
CLOCK INPUTS (CLKin0/CLKin0*, CLKin1/CLKin1*)							
f_{CLKin}	Input Frequency Range(5)	Functional up to 400 MHz Output frequency range and timing specified per output type (refer to HCSL, LVCMOS output specifications)		DC		400	MHz
V_{IHD}	Differential Input High Voltage	CLKin driven differentially				Vcc	V
V_{ILD}	Differential Input Low Voltage			GND			V
V_{ID}	Differential Input Voltage Swing(6)			0.15		1.3	V
V_{CMD}	Differential Input CMD Common Mode Voltage	V_{ID} = 150 mV		0.25		Vcc - 1.2	V
		V_{ID} = 350 mV		0.25		Vcc - 1.1	
		V_{ID} = 800 mV		0.25		Vcc - 0.9	
V_{IH}	Single-Ended Input IH High Voltage	CLKinX driven single-ended (AC or DC coupled), CLKinX* AC coupled to GND or externally biased within V_{CM} range				VCC	V
V_{IL}	Single-Ended Input IL Low Voltage			GND			V
V_{I_SE}	Single-Ended Input Voltage Swing(7)			0.3		2	Vpp
V_{CM}	Single-Ended Input CM Common Mode Voltage			0.25		VCC - 1.2	V

(1) The output supply voltages/pins (V_{CCOA}, V_{CCOB}, and V_{CCOC}) will be referred to generally as V_{CCO} when no distinction is needed, or when the output supply can be inferred by the output bank/type.
(2) The Electrical Characteristics tables list ensured specifications under the listed Recommended Operating Conditions except as otherwise modified or specified by the Electrical Characteristics Conditions and/or Notes. Typical specifications are estimations only and are not ensured.
(3) See *Power Supply Recommendations* for more information on current consumption and power dissipation calculations.
(4) Power supply ripple rejection, or PSRR, is defined as the single-sideband phase spur level (in dBc) modulated onto the clock output when a single-tone sinusoidal signal (ripple) is injected onto the Vcco supply. Assuming no amplitude modulation effects and small index modulation, the peak-to-peak deterministic jitter (DJ) can be calculated using the measured single-sideband phase spur level (PSRR) as follows: DJ (ps pk-pk) = [(2 * $10^{(PSRR / 20)}$) / (π * f_{CLK})] * 1E12
(5) Specification is ensured by characterization and is not tested in production.
(6) See *Differential Voltage Measurement Terminology* for definition of V_{ID} and V_{OD} voltages.
(7) Parameter is specified by design, not tested in production.

Electrical Characteristics (continued)

Unless otherwise specified: Vcc = 3.3 V ± 5%, Vcco = 3.3 V ± 5%, 2.5 V ± 5%, -40 °C ≤ T_A ≤ 85 °C, CLKin driven differentially, input slew rate ≥ 3 V/ns. Typical values represent most likely parametric norms at Vcc = 3.3 V, Vcco = 3.3 V, T_A = 25 °C, and at the Recommended Operation Conditions at the time of product characterization and are not ensured.(1)(2)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
ISO_{MUX}	Mux Isolation, CLKin0 to CLKin1	f_{OFFSET} > 50 kHz, P_{CLKinX} = 0 dBm	f_{CLKin0} = 100 MHz		-84		dBc
			f_{CLKin0} = 200 MHz		-82		
			f_{CLKin0} = 500 MHz		-71		
			f_{CLKin0} = 1000 MHz		-65		
CRYSTAL INTERFACE (OSCin, OSCout)							
F_{CLK}	External Clock Frequency Range(5)	OSCin driven single-ended, OSCout floating				250	MHz
F_{XTAL}	Crystal Frequency Range	Fundamental mode crystal ESR ≤ 200 Ω (10 to 30 MHz) ESR ≤ 125 Ω (30 to 40 MHz)(8)		10		40	MHz
C_{IN}	OSCin Input Capacitance				1		pF
HCSL OUTPUTS (CLKoutAn/CLKoutAn*, CLKoutBn/CLKoutBn*)							
f_{CLKout}	Output Frequency Range(5)	R_L = 50 Ω to GND, C_L ≤ 5 pF		DC		400	MHz
$Jitter_{ADD\_PCIe}$	Additive RMS Phase Jitter for PCIe 3.0(5)	PCIe Gen 3, PLL BW = 2–5 MHz, CDR = 10 MHz	CLKin: 100 MHz, Slew rate ≥ 0.6 V/ns		0.03	0.15	ps
$Jitter_{ADD}$	Additive RMS Jitter Integration Bandwidth to 20 MHz(9)(10)	Vcco = 3.3 V, RT = 50 Ω to GND	CLKin: 100 MHz, Slew rate ≥ 3 V/ns		77		fs
			CLKin: 156.25 MHz, Slew rate ≥ 2.7 V/ns		86		
Noise Floor	Noise Floor f_{OFFSET} ≥ 10 MHz(9)(10)	Vcco = 3.3 V, RT = 50 Ω to GND	CLKin: 100 MHz, Slew rate ≥ 3 V/ns		-161.3		dBc/Hz
			CLKin: 156.25 MHz, Slew rate ≥ 2.7 V/ns		-156.3		
DUTY	Duty Cycle(5)	50% input clock duty cycle		45%		55%	
V_{OH}	Output High Voltage	T_A = 25 °C, DC Measurement, R_T = 50 Ω to GND		520	810	920	mV
V_{OL}	Output Low Voltage			-150	0.5	150	mV
V_{CROSS}	Absolute Crossing Voltage(5)(11)	R_L = 50 Ω to GND, C_L ≤ 5 pF		160	350	460	mV
ΔV_{CROSS}	Total Variation of V_{CROSS}					140	mV
t_R	Output Rise Time 20% to 80%(11)(7)	250 MHz, Uniform transmission line up to 10 in. with 50-Ω characteristic impedance, RL = 50 Ω to GND, C_L ≤ 5 pF			300	500	ps
t_F	Output Fall Time 80% to 20%(11)(7)				300	500	ps

(8) The ESR requirements stated must be met to ensure that the oscillator circuitry has no startup issues. However, lower ESR values for the crystal may be necessary to stay below the maximum power dissipation (drive level) specification of the crystal. Refer to *Crystal Interface* for crystal drive level considerations.
(9) The noise floor of the output buffer is measured as the far-out phase noise of the buffer. Typically this offset is ≥ 10 MHz, but for lower frequencies this measurement offset can be as low as 5 MHz due to measurement equipment limitations.
(10) Phase noise floor will degrade as the clock input slew rate is reduced. Compared to a single-ended clock, a differential clock input (LVPECL, LVDS) will be less susceptible to degradation in noise floor at lower slew rates due to its common mode noise rejection. However, it is recommended to use the highest possible input slew rate for differential clocks to achieve optimal noise floor performance at the device outputs.
(11) AC timing parameters for HCSL or CMOS are dependent on output capacitive loading.

Electrical Characteristics (continued)

Unless otherwise specified: Vcc = 3.3 V ± 5%, Vcco = 3.3 V ± 5%, 2.5 V ± 5%, -40 °C ≤ T_A ≤ 85 °C, CLKin driven differentially, input slew rate ≥ 3 V/ns. Typical values represent most likely parametric norms at Vcc = 3.3 V, Vcco = 3.3 V, T_A = 25 °C, and at the Recommended Operation Conditions at the time of product characterization and are not ensured.(1)(2)

PARAMETER		TEST CONDITIONS		MIN	TYP	MAX	UNIT
LVCMOS OUTPUT (REFout)							
f_{CLKout}	Output Frequency Range(5)	CL ≤ 5 pF		DC		250	MHz
$Jitter_{ADD}$	Additive RMS Jitter Integration Bandwidth 1 MHz to 20 MHz(12)	Vcco = 3.3 V, CL ≤ 5 pF	100 MHz, Input Slew rate ≥ 3 V/ns		95		fs
Noise Floor	Noise Floor f_{OFFSET} ≥ 10 MHz(9)(10)	Vcco = 3.3 V, CL ≤ 5 pF	100 MHz, Input Slew rate ≥ 3 V/ns		-159.3		dBc/Hz
DUTY	Duty Cycle(5)	50% input clock duty cycle		45%		55%	
V_{OH}	Output High Voltage	1 mA load		Vcco - 0.1			V
V_{OL}	Output Low Voltage					0.1	V
I_{OH}	Output High Current (Source)	Vo = Vcco / 2	Vcco = 3.3 V		28		mA
			Vcco = 2.5 V		20		
			Vcco = 3.3 V		28		mA
I_{OL}	Output Low Current (Sink)		Vcco = 2.5 V		20		
t_R	Output Rise Time 20% to 80%(11)(7)	250 MHz, Uniform transmission line up to 10 in. with 50-Ω characteristic impedance, RL = 50 Ω to GND, CL ≤ 5 pF			225	400	ps
t_F	Output Fall Time 80% to 20%(11)(7)				225	400	ps
t_{EN}	Output Enable Time(13)	C_L ≤ 5 pF				3	cycles
t_{DIS}	Output Disable Time(13)					3	cycles
PROPAGATION DELAY and OUTPUT SKEW							
t_{PD_HCSL}	Propagation Delay CLKin-to-HCSL(11)(7)	R_T = 50 Ω to GND, C_L ≤ 5 pF		295	590	885	ps
t_{PD_CMOS}	Propagation Delay CLKin-to-LVCMOS(11)(7)	CL ≤ 5 pF	Vcco = 3.3 V	900	1475	2300	ps
			Vcco = 2.5 V	1000	1550	2700	
$t_{SK(O)}$	Output Skew(5)(11)(14)	Skew specified between any two CLKouts. Load conditions are the same as propagation delay specifications.			30	50	ps
$t_{SK(PP)}$	Part-to-Part Output Skew LVPECL/LVDS/HCSL(11)(7)(14)				80	120	ps

(12) For the 100 MHz and 156.25 MHz clock input conditions, Additive RMS Jitter (J_{ADD}) is calculated using Method #1: $J_{ADD} = SQRT(J_{OUT}^2 - J_{SOURCE}^2)$, where J_{OUT} is the total RMS jitter measured at the output driver and J_{SOURCE} is the RMS jitter of the clock source applied to CLKin. For the 625 MHz clock input condition, Additive RMS Jitter is approximated using Method #2: $J_{ADD} = SQRT(2*10^{dBc/10}) / (2*\pi*f_{CLK})$, where dBc is the phase noise power of the Output Noise Floor integrated from 1 to 20 MHz bandwidth. The phase noise power can be calculated as: dBc = Noise Floor + $10*\log_{10}$(20 MHz - 1 MHz). The additive RMS jitter was approximated for 625 MHz using Method #2 because the RMS jitter of the clock source was not sufficiently low enough to allow practical use of Method #1. Refer to the “Noise Floor vs. CLKin Slew Rate” and “RMS Jitter vs. CLKin Slew Rate” plots in *Typical Characteristics*.

(13) Output Enable Time is the number of input clock cycles it takes for the output to be enabled after REFout_EN is pulled high. Similarly, Output Disable Time is the number of input clock cycles it takes for the output to be disabled after REFout_EN is pulled low. The REFout_EN signal should have an edge transition much faster than that of the input clock period for accurate measurement.

(14) Output skew is the propagation delay difference between any two outputs with identical output buffer type and equal loading while operating at the same supply voltage and temperature conditions.

6.6 Typical Characteristics

Unless otherwise specified: Vcc = 3.3 V, Vcco = 3.3 V, T_A = 25 °C, CLKin driven differentially, input slew rate ≥ 3 V/ns.

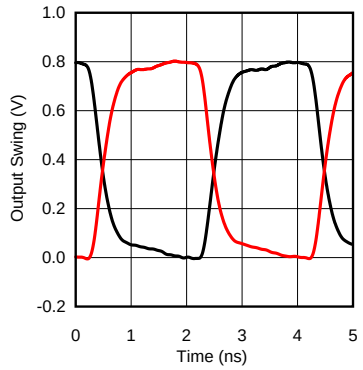


Figure 1. HCSL Output Swing @ 250 MHz

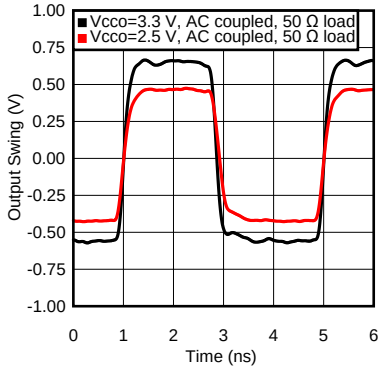
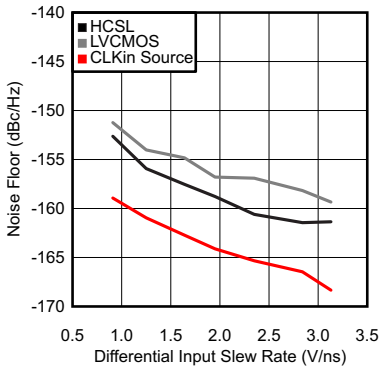
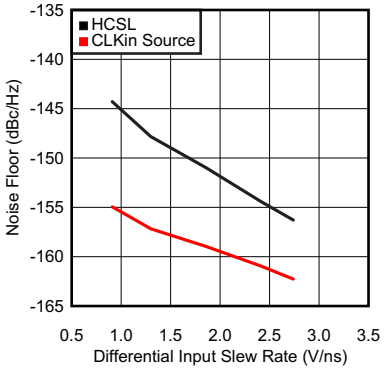


Figure 2. LVCMOS Output Swing @ 250 MHz



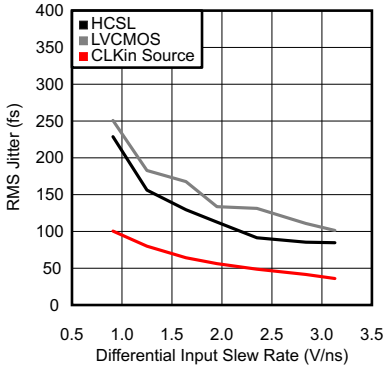
Fclk = 100 MHz F_{offset} = 20 MHz

Figure 3. Noise Floor vs. CLKin Slew Rate @ 100 MHz



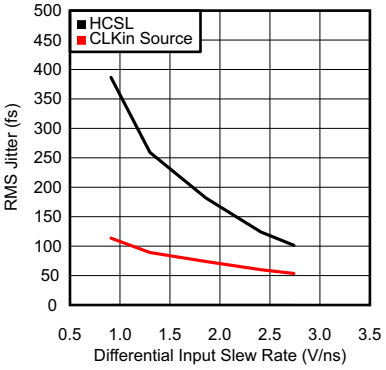
Fclk = 156.25 MHz F_{offset} = 20 MHz

Figure 4. Noise Floor vs. CLKin Slew Rate @ 156.25 MHz



Fclk = 100 MHz Int. BW = 1 to 20 MHz

Figure 5. RMS Jitter vs. CLKin Slew Rate @ 100 MHz

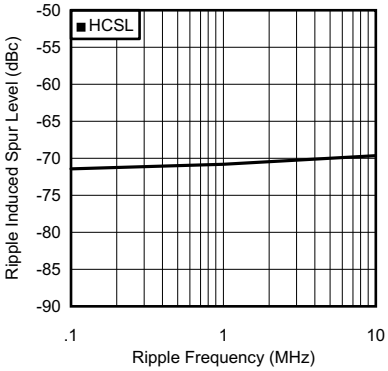


Fclk = 156.25 MHz Int. BW = 1 to 20 MHz

Figure 6. RMS Jitter vs. CLKin Slew Rate @ 156.25 MHz

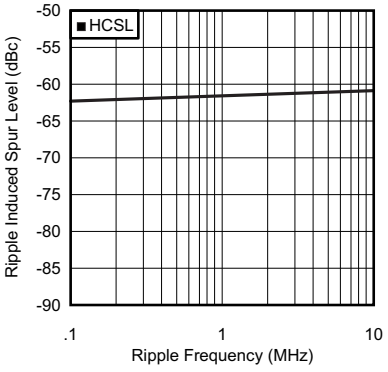
Typical Characteristics (continued)

Unless otherwise specified: Vcc = 3.3 V, Vcco = 3.3 V, T_A = 25 °C, CLKin driven differentially, input slew rate ≥ 3 V/ns.



Fclk = 156.25 MHz Vcco Ripple = 100

Figure 7. PSRR vs. Ripple Frequency @ 156.25 MHz



F_{clk} = 312.5 MHz Vcco Ripple = 100 mVpp

Figure 8. PSRR vs. Ripple Frequency @ 312.5 MHz

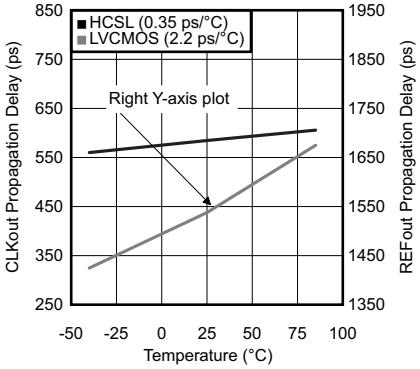


Figure 9. Propagation Delay vs. Temperature

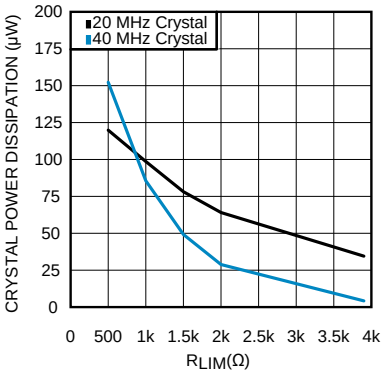


Figure 10. Crystal Power Dissipation vs. R_{LIM}

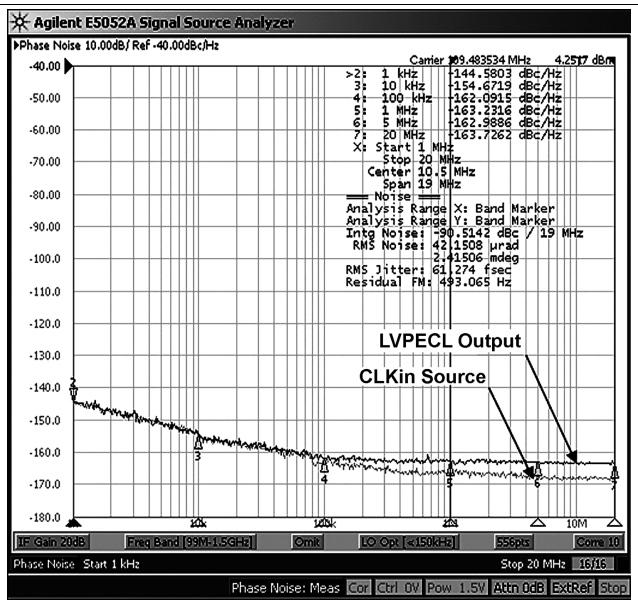


Figure 11. LVPECL Phase Noise @ 100 MHz

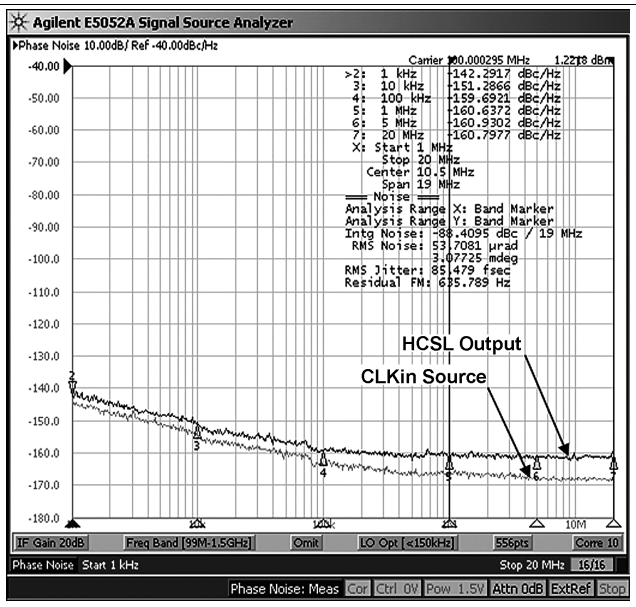


Figure 12. HCSL Phase Noise @ 100 MHz

7 Parameter Measurement Information

7.1 Differential Voltage Measurement Terminology

The differential voltage of a differential signal can be described by two different definitions causing confusion when reading datasheets or communicating with other engineers. This section will address the measurement and description of a differential signal so that the reader will be able to understand and discern between the two different definitions when used.

The first definition used to describe a differential signal is the absolute value of the voltage potential between the inverting and non-inverting signal. The symbol for this first measurement is typically V_{ID} or V_{OD} depending on if an input or output voltage is being described.

The second definition used to describe a differential signal is to measure the potential of the non-inverting signal with respect to the inverting signal. The symbol for this second measurement is V_{SS} and is a calculated parameter. Nowhere in the IC does this signal exist with respect to ground; it only exists in reference to its differential pair. V_{SS} can be measured directly by oscilloscopes with floating references, otherwise this value can be calculated as twice the value of V_{OD} as described above.

Figure 13 illustrates the two different definitions side-by-side for inputs and Figure 14 illustrates the two different definitions side-by-side for outputs. The V_{ID} (or V_{OD}) definition show the DC levels, V_{IH} and V_{OL} (or V_{OH} and V_{OL}), that the non-inverting and inverting signals toggle between with respect to ground. V_{SS} input and output definitions show that if the inverting signal is considered the voltage potential reference, the non-inverting signal voltage potential is now increasing and decreasing above and below the non-inverting reference. Thus the peak-to-peak voltage of the differential signal can be measured.

V_{ID} and V_{OD} are often defined as volts (V) and V_{SS} is often defined as volts peak-to-peak (V_{PP}).

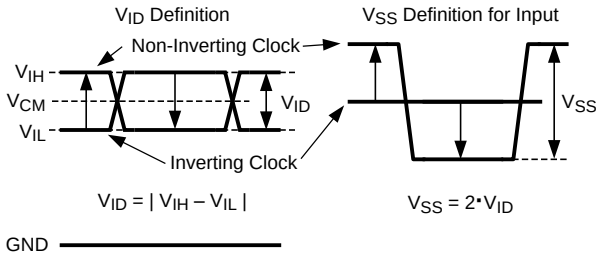


Figure 13. Two Different Definitions for Differential Input Signals

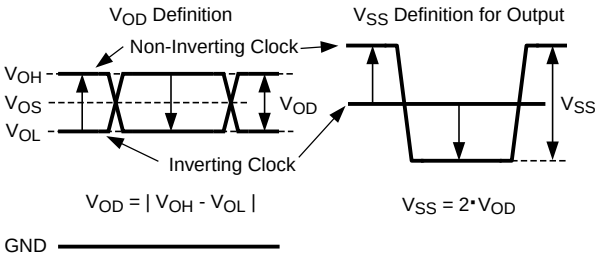


Figure 14. Two Different Definitions for Differential Output Signals

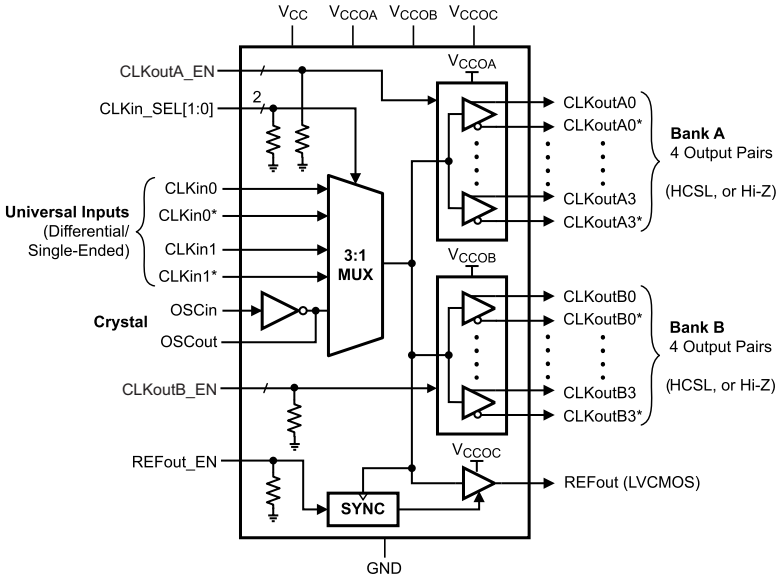
Refer to "Common Data Transmission Parameters and their Definitions", Application Note AN-912 (SNLA036), for more information.

8 Detailed Description

8.1 Overview

The LMK00338 is an 8-output PCIe Gen1/Gen2/Gen3 clock fanout buffer with low additive jitter that can operate up to 400 MHz. It features a 3:1 input multiplexer with an optional crystal oscillator input, two banks of 4 HCSL outputs, one LVCMOS output, and 3 independent output buffer supplies. The input selection and output buffer modes are controlled via pin strapping. The device is offered in a 40-pin WQFN package and leverages much of the high-speed, low-noise circuit design employed in the LMK04800 family of clock conditioners.

8.2 Functional Block Diagram



8.3 Feature Description

8.3.1 Crystal Power Dissipation vs. R_{LIM}

For Figure 10, the following applies:

- The typical RMS jitter values in the plots show the total output RMS jitter (J_{OUT}) for each output buffer type and the source clock RMS jitter (J_{SOURCE}). From these values, the Additive RMS Jitter can be calculated as: $J_{ADD} = SQRT(J_{OUT}^2 - J_{SOURCE}^2)$
- 20 MHz crystal characteristics: Abracon ABL series, AT cut, C_L = 18 pF , C_0 = 4.4 pF measured (7 pF max), ESR = 8.5 Ω measured (40 Ω max), and Drive Level = 1 mW max (100 µW typical).

  40 MHz crystal characteristics: Abracon ABLS2 series, AT cut, C_L = 18 pF , C_0 = 5 pF measured (7 pF max), ESR = 5 Ω measured (40 Ω max), and Drive Level = 1 mW max (100 µW typical).

Feature Description (continued)

8.3.2 Clock Inputs

The input clock can be selected from CLKin0/CLKin0*, CLKin1/CLKin1*, or OSCin. Clock input selection is controlled using the CLKin_SEL[1:0] inputs as shown in Table 1. Refer to *Driving the Clock Inputs* for clock input requirements. When CLKin0 or CLKin1 is selected, the crystal circuit is powered down. When OSCin is selected, the crystal oscillator circuit will start-up and its clock will be distributed to all outputs. Refer to *Crystal Interface* for more information. Alternatively, OSCin may be be driven by a single-ended clock (up to 250 MHz) instead of a crystal.

Table 1. Input Selection

CLKin_SEL1	CLKin_SEL0	SELECTED INPUT
0	0	CLKin0, CLKin0*
0	1	CLKin1, CLKin1*
1	X	OSCin

Table 2 shows the output logic state vs. input state when either CLKin0/CLKin0* or CLKin1/CLKin1* is selected. When OSCin is selected, the output state will be an inverted copy of the OSCin input state.

Table 2. CLKin Input vs. Output States

STATE of SELECTED CLKin	STATE of ENABLED OUTPUTS
CLKinX and CLKinX* inputs floating	Logic low
CLKinX and CLKinX* inputs shorted together	Logic low
CLKin logic low	Logic low
CLKin logic high	Logic high

8.3.3 Clock Outputs

The HCSL output buffer for Bank A and Bank B outputs can be separately disabled to Hi-Z using the CLKoutA_EN and CLKoutB_EN inputs, respectively, as shown in Table 3. For applications where all differential outputs are not needed, any unused output pin should be left floating with a minimum copper length (see note below) to minimize capacitance and potential coupling and reduce power consumption. If an entire output bank will not be used, it is recommended to disable/Hi-Z the bank to reduce power. Refer to *Termination and Use of Clock Drivers* for more information on output interface and termination techniques.

NOTE

For best soldering practices, the minimum trace length for any unused output pin should extend to include the pin solder mask. This way during reflow, the solder has the same copper area as connected pins. This allows for good, uniform fillet solder joints helping to keep the IC level during reflow.

Table 3. Differential Output Buffer Type Selection

CLKoutX_EN	CLKoutX BUFFER TYPE (BANK A or B)
0	HCSL
1	Disabled (Hi-Z)

8.3.3.1 Reference Output

The reference output (REFout) provides a LVCMOS copy of the selected input clock. The LVCMOS output high level is referenced to the Vcco voltage. REFout can be enabled or disabled using the enable input pin, REFout_EN, as shown in Table 4.

Table 4. Reference Output Enable

REFout_EN	REFout STATE
0	Disabled (Hi-Z)
1	Enabled

The REFout_EN input is internally synchronized with the selected input clock by the SYNC block. This synchronizing function prevents glitches and runt pulses from occurring on the REFout clock when enabled or disabled. REFout will be enabled within 3 cycles (t_{EN}) of the input clock after REFout_EN is toggled high. REFout will be disabled within 3 cycles (t_{DIS}) of the input clock after REFout_EN is toggled low.

When REFout is disabled, the use of a resistive loading can be used to set the output to a predetermined level. For example, if REFout is configured with a 1 kΩ load to ground, then the output will be pulled to low when disabled.

8.4 Device Functional Modes

8.4.1 V_{CC} and V_{CCO} Power Supplies

The LMK00338 has a 3.3 V core power supply (V_{CC}) and 3 independent 3.3 V/2.5 V output power supplies (V_{CCOA}, V_{CCOB}, V_{CCOC}). Output supply operation at 2.5 V enables lower power consumption and output-level compatibility with 2.5 V receiver devices. The output levels for HCSL are relatively constant over the specified Vcco range. Refer to *Power Supply Recommendations* for additional supply related considerations, such as power dissipation, power supply bypassing, and power supply ripple rejection (PSRR).

NOTE

Care should be taken to ensure the Vcco voltages do not exceed the Vcc voltage to prevent turning-on the internal ESD protection circuitry.

9 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

9.1 Application Information

A common PCIe application, such as a server card, consists of several building blocks, which all need a reference clock. In the mostly used Common RefClk architecture, the clock is distributed from a single source to both RX and TX. This requires either a Clock generator with high output count or a buffer like the LMK00338. The buffer simplifies the clocking tree and provides a cost and space optimized solution. While using a buffer to distribute the clock, the additive jitter needs to be considered. The LMK00338 is an ultra-low additive jitter PCIe clock buffer suitable for all current and future PCIe Generations.

9.2 Typical Applications

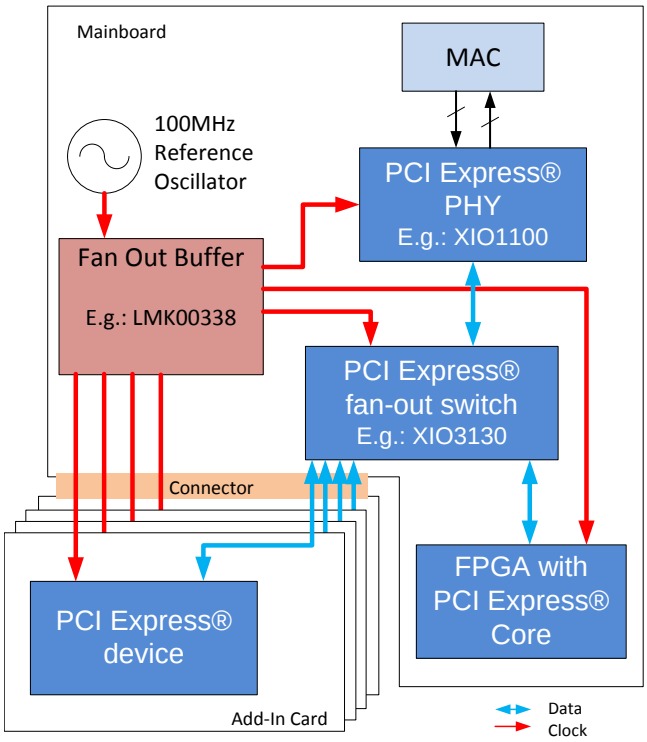


Figure 15. Example PCI Express Application Diagram

9.2.1 Design Requirements

9.2.1.1 Driving the Clock Inputs

The LMK00338 has two universal inputs (CLKin0/CLKin0* and CLKin1/CLKin1*) that can accept AC- or DC-coupled 3.3V/2.5V LVPECL, LVDS, CML, SSTL, and other differential and single-ended signals that meet the input requirements specified in the *Electrical Characteristics*. The device can accept a wide range of signals due to its wide input common mode voltage range (V_{CM}) and input voltage swing (V_{ID}) / dynamic range. For 50% duty cycle and DC-balanced signals, AC coupling may also be employed to shift the input signal to within the V_{CM} range. Refer to *Termination and Use of Clock Drivers* for signal interfacing and termination techniques.

Typical Applications (continued)

To achieve the best possible phase noise and jitter performance, it is mandatory for the input to have high slew rate of 3 V/ns (differential) or higher. Driving the input with a lower slew rate will degrade the noise floor and jitter. For this reason, a differential signal input is recommended over single-ended because it typically provides higher slew rate and common-mode-rejection. Refer to the Noise Floor vs. CLKin Slew Rate and RMS Jitter vs. CLKin Slew Rate plots in *Typical Characteristics*.

While it is recommended to drive the CLKin/CLKin* pair with a differential signal input, it is possible to drive it with a single-ended clock provided it conforms to the Single-Ended Input specifications for CLKin pins listed in the *Electrical Characteristics*. For large single-ended input signals, such as 3.3V or 2.5V LVCMOS, a 50-Ω load resistor should be placed near the input for signal attenuation to prevent input overdrive as well as for line termination to minimize reflections. Again, the single-ended input slew rate should be as high as possible to minimize performance degradation. The CLKin input has an internal bias voltage of about 1.4 V, so the input can be AC coupled as shown in Figure 16. The output impedance of the LVCMOS driver plus Rs should be close to 50 Ω to match the characteristic impedance of the transmission line and load termination.

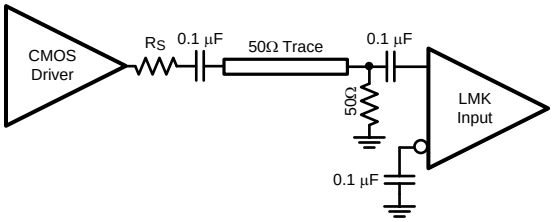


Figure 16. Single-Ended LVCMOS Input, AC Coupling

A single-ended clock may also be DC coupled to CLKinX as shown in Figure 17. A 50-Ω load resistor should be placed near the CLKinX input for signal attenuation and line termination. Because half of the single-ended swing of the driver ($V_{O,PP}$ / 2) drives CLKinX, CLKinX* should be externally biased to the midpoint voltage of the attenuated input swing (($V_{O,PP}$ / 2) × 0.5). The external bias voltage should be within the specified input common voltage (V_{CM}) range. This can be achieved using external biasing resistors in the kΩ range (R_{B1} and R_{B2}) or another low-noise voltage reference. This will ensure the input swing crosses the threshold voltage at a point where the input slew rate is the highest.

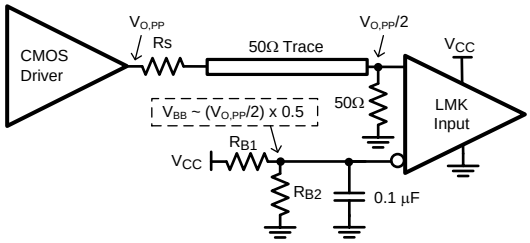


Figure 17. Single-Ended LVCMOS Input, DC Coupling with Common Mode Biasing

Typical Applications (continued)

If the crystal oscillator circuit is not used, it is possible to drive the OSCin input with an single-ended external clock as shown in Figure 18. The input clock should be AC coupled to the OSCin pin, which has an internally-generated input bias voltage, and the OSCout pin should be left floating. While OSCin provides an alternative input to multiplex an external clock, it is recommended to use either differential input (CLKinX) since it offers higher operating frequency, better common mode and power supply noise rejection, and greater performance over supply voltage and temperature variations.

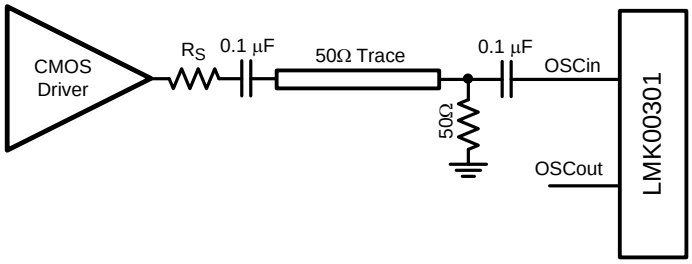


Figure 18. Driving OSCin with a Single-Ended Input

9.2.1.2 Crystal Interface

The LMK00338 has an integrated crystal oscillator circuit that supports a fundamental mode, AT-cut crystal. The crystal interface is shown in Figure 19.

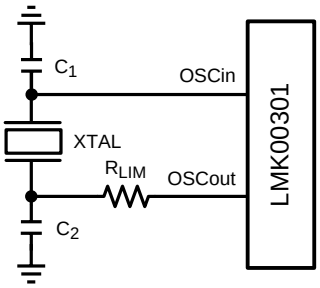


Figure 19. Crystal Interface

The load capacitance (C_L) is specific to the crystal, but usually on the order of 18 - 20 pF. While C_L is specified for the crystal, the OSCin input capacitance (C_{IN} = 1 pF typical) of the device and PCB stray capacitance (C_{STRAY} ~ 1~3 pF) can affect the discrete load capacitor values, C_1 and C_2.

For the parallel resonant circuit, the discrete capacitor values can be calculated as follows:

$$C_L = (C_1 * C_2) / (C_1 + C_2) + C_{IN} + C_{STRAY} \quad (1)$$

Typically, $C_1 = C_2$ for optimum symmetry, so Equation 1 can be rewritten in terms of C_1 only:

$$C_L = C_1^2 / (2 * C_1) + C_{IN} + C_{STRAY} \quad (2)$$

Finally, solve for C_1:

$$C_1 = (C_L - C_{IN} - C_{STRAY})*2 \quad (3)$$

Typical Applications (continued)

Electrical Characteristics provides crystal interface specifications with conditions that ensure start-up of the crystal, but it does not specify crystal power dissipation. The designer will need to ensure the crystal power dissipation does not exceed the maximum drive level specified by the crystal manufacturer. Overdriving the crystal can cause premature aging, frequency shift, and eventual failure. Drive level should be held at a sufficient level necessary to start-up and maintain steady-state operation.

The power dissipated in the crystal, P_{XTAL}, can be computed by:

$$P_{XTAL} = I_{RMS}^2 * R_{ESR}*(1 + C_0/C_L)^2 \quad (4)$$

where

- I_{RMS} is the RMS current through the crystal.
- R_{ESR} is the max. equivalent series resistance specified for the crystal
- C_L is the load capacitance specified for the crystal
- C_0 is the min. shunt capacitance specified for the crystal

I_{RMS} can be measured using a current probe (for example, Tektronix CT-6 or equivalent) placed on the leg of the crystal connected to OSCout with the oscillation circuit active.

As shown in Figure 19, an external resistor, R_{LIM}, can be used to limit the crystal drive level, if necessary. If the power dissipated in the selected crystal is higher than the drive level specified for the crystal with R_{LIM} shorted, then a larger resistor value is mandatory to avoid overdriving the crystal. However, if the power dissipated in the crystal is less than the drive level with R_{LIM} shorted, then a zero value for R_{LIM} can be used. As a starting point, a suggested value for R_{LIM} is 1.5 kΩ.

9.2.2 Detailed Design Procedure

9.2.2.1 Termination and Use of Clock Drivers

When terminating clock drivers keep in mind these guidelines for optimum phase noise and jitter performance:

- Transmission line theory should be followed for good impedance matching to prevent reflections.
- Clock drivers should be presented with the proper loads.
  - HCSL drivers are switched current outputs and require a DC path to ground via 50 Ω termination.
- Receivers should be presented with a signal biased to their specified DC bias level (common mode voltage) for proper operation. Some receivers have self-biasing inputs that automatically bias to the proper voltage level; in this case, the signal should normally be AC coupled.

9.2.2.2 Termination for DC Coupled Differential Operation

For DC coupled operation of an HCSL driver, terminate with 50 Ω to ground near the driver output as shown in Figure 20. Series resistors, Rs, may be used to limit overshoot due to the fast transient current. Because HCSL drivers require a DC path to ground, AC coupling is not allowed between the output drivers and the 50 Ω termination resistors.

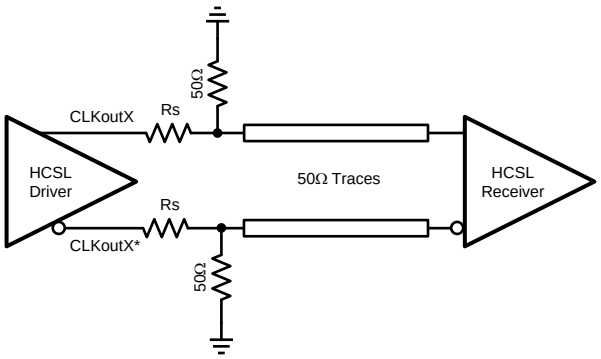


Figure 20. HCSL Operation, DC Coupling

Typical Applications (continued)

9.2.2.3 Termination for AC Coupled Differential Operation

AC coupling allows for shifting the DC bias level (common mode voltage) when driving different receiver standards. Since AC coupling prevents the driver from providing a DC bias voltage at the receiver, it is important to ensure the receiver is biased to its ideal DC level.

9.2.3 Application Curves

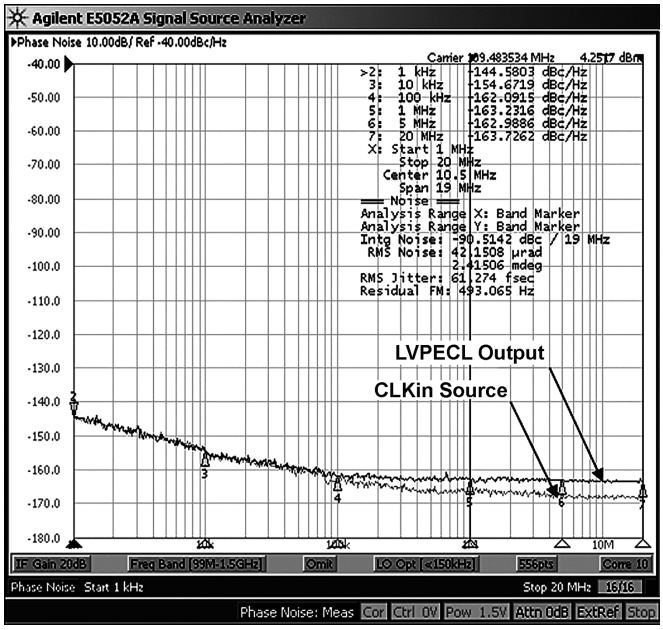


Figure 21. LVPECL Phase Noise @ 100 MHz

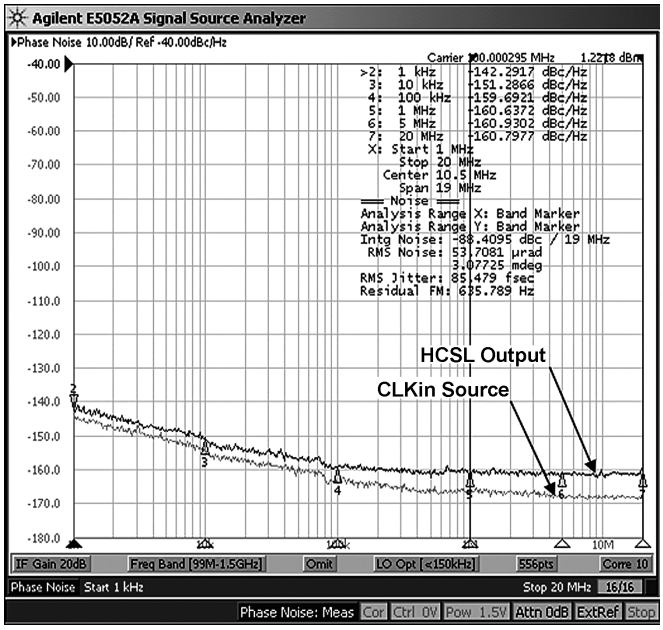


Figure 22. HCSL Phase Noise @ 100 MHz

10 Power Supply Recommendations

10.1 Current Consumption and Power Dissipation Calculations

The current consumption values specified in *Electrical Characteristics* can be used to calculate the total power dissipation and IC power dissipation for any device configuration. The total V_{CC} core supply current (I_{CC_TOTAL}) can be calculated using Equation 5:

$$\mathbf{I_{CC\_TOTAL} = I_{CC\_CORE} + I_{CC\_BANK\_A} + I_{CC\_BANK\_B} + I_{CC\_CMOS}}$$

where

- I_{CC_CORE} is the current for core logic and input blocks and depends on selected input (CLKinX or OSCin).
- $I_{CC\_BANK\_A}$ is the current for Bank A.
- $I_{CC\_BANK\_B}$ is the current for Bank B.
- I_{CC_CMOS} is the current for the LVCMOS output (or 0 mA if REFout is disabled). (5)

Since the output supplies (V_{CCOA}, V_{CCOB}, V_{CCOC}) can be powered from 3 independent voltages, the respective output supply currents ($I_{CCO\_BANK\_A}$, $I_{CCO\_BANK\_B}$, and I_{CCO_CMOS}) should be calculated separately. I_{CCO_BANK} for either Bank A or B can be directly taken from the corresponding output supply current spec (I_{CCO_HCSL}) **provided the output loading matches the specified conditions**. Otherwise, I_{CCO_BANK} should be calculated as follows:

$$I_{CCO\_BANK} = I_{BANK\_BIAS} + (N * I_{OUT\_LOAD})$$

where

- I_{BANK_BIAS} is the output bank bias current (fixed value).
- I_{OUT_LOAD} is the DC load current per loaded output pair.
- N is the number of loaded output pairs per bank (N = 0 to 4). (6)

Table 5 shows the typical I_{BANK_BIAS} values and I_{OUT_LOAD} expressions for HCSL.

Table 5. Typical Output Bank Bias and Load Currents

CURRENT PARAMETER	HCSL
I_{BANK_BIAS}	4.8 mA
I_{OUT_LOAD}	V_{OH}/R_T

Once the current consumption is calculated for each supply, the total power dissipation (P_{TOTAL}) can be calculated as:

$$\mathbf{P_{TOTAL} = (V_{CC}*I_{CC\_TOTAL}) + (V_{CCOA}*I_{CCO\_BANK\_A}) + (V_{CCOB}*I_{CCO\_BANK\_B}) + (V_{CCOC}*I_{CCO\_CMOS})} \quad (7)$$

If the device configuration is configured with HCSL outputs, then it is also necessary to calculate the power dissipated in any termination resistors (P_{RT_HCSL}). The external power dissipation values can be calculated as follows:

$$\mathbf{P_{RT\_HCSL}\ (per\ HCSL\ pair) = V_{OH}^2 / R_T} \quad (8)$$

Finally, the IC power dissipation (P_{DEVICE}) can be computed by subtracting the external power dissipation values from P_{TOTAL} as follows:

$$\mathbf{P_{DEVICE} = P_{TOTAL} - N*P_{RT\_HCSL}}$$

where

- N_2 is the number of HCSL output pairs with termination resistors to GND. (9)

10.1.1 Power Dissipation Example: Worst-Case Dissipation

This example shows how to calculate IC power dissipation for a configuration to estimate worst-case power dissipation. In this case, the maximum supply voltage and supply current values specified in *Electrical Characteristics* are used.

- $V_{CC} = V_{CCO} = 3.465$ V. Max I_{CC} and I_{CCO} values.
- CLKin0/CLKin0* input is selected.
- Banks A and B are enabled: all outputs terminated with 50 Ω to GND.
- REFout is enabled with 5 pF load.
- $T_A = 85$ °C

Using the power calculations from the previous section and *maximum* supply current specifications, we can compute P_{TOTAL} and P_{DEVICE}.

- From Equation 5: I_{CC_TOTAL} = 10.5 mA + 38.5 mA + 38.5 mA + 5.5 mA = 93 mA
- From I_{CCO_HCSL} max spec: $I_{CCO\_BANK\_A} = I_{CCO\_BANK\_B}$ = 84 mA
- From Equation 7: P_{TOTAL} = 3.465 V * (93 mA + 84 mA + 84 mA + 10 mA) = 939 mW
- From Equation 8: P_{RT_HCSL} = (0.92V)2/50Ω = 16.9 mW (per output pair)
- From Equation 9: P_{DEVICE} = 939 mW - (8 * 16.9 mW) = 803.8 mW

In this worst-case example, the IC device will dissipate about 803.8 mW or 85.6 of the total power (939 mW), while the remaining 14.4% will be dissipated in the termination resistors (135.2 mW for 8 pairs). Based on θ_{JA} of 31.4 °C/W, the estimated die junction temperature would be about 25.2 °C above ambient, or 110.2 °C when T_A = 85 °C.

10.2 Power Supply Bypassing

The Vcc and Vcco power supplies should have a high-frequency bypass capacitor, such as 0.1 uF or 0.01 uF, placed very close to each supply pin. 1 uF to 10 uF decoupling capacitors should also be placed nearby the device between the supply and ground planes. All bypass and decoupling capacitors should have short connections to the supply and ground plane through a short trace or via to minimize series inductance.

10.2.1 Power Supply Ripple Rejection

In practical system applications, power supply noise (ripple) can be generated from switching power supplies, digital ASICs or FPGAs, and so on. While power supply bypassing will help filter out some of this noise, it is important to understand the effect of power supply ripple on the device performance. When a single-tone sinusoidal signal is applied to the power supply of a clock distribution device, such as LMK00338, it can produce narrow-band phase modulation as well as amplitude modulation on the clock output (carrier). In the single-side band phase noise spectrum, the ripple-induced phase modulation appears as a phase spur level relative to the carrier (measured in dBc).

For the LMK00338, power supply ripple rejection, or PSRR, was measured as the single-sideband phase spur level (in dBc) modulated onto the clock output when a ripple signal was injected onto the Vcco supply. The PSRR test setup is shown in Figure 23.

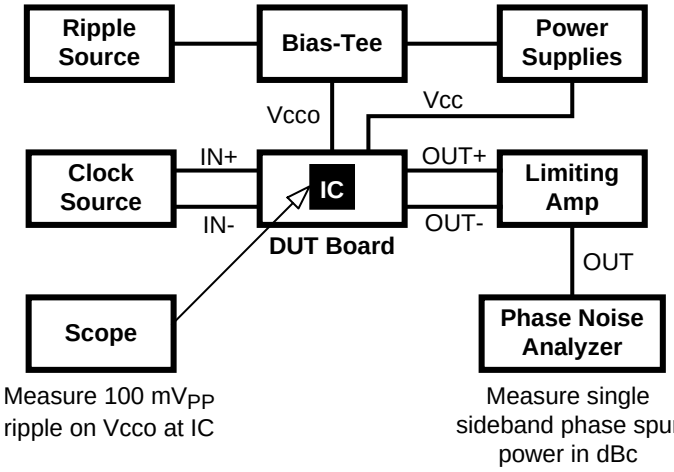


Figure 23. PSRR Test Setup

A signal generator was used to inject a sinusoidal signal onto the Vcco supply of the DUT board, and the peak-to-peak ripple amplitude was measured at the Vcco pins of the device. A limiting amplifier was used to remove amplitude modulation on the differential output clock and convert it to a single-ended signal for the phase noise analyzer. The phase spur level measurements were taken for clock frequencies of 156.25 MHz and 312.5 MHz under the following power supply ripple conditions:

- Ripple amplitude: 100 mVpp on Vcco = 2.5 V
- Ripple frequencies: 100 kHz, 1 MHz, and 10 MHz

Power Supply Bypassing (continued)

Assuming no amplitude modulation effects and small index modulation, the peak-to-peak deterministic jitter (DJ) can be calculated using the measured single-sideband phase spur level (PSRR) as follows:

$$DJ\ (ps\ pk\text{-}pk) = [(2*10^{(PSRR\ /\ 20)}) / (\pi*f_{CLK})] * 10^{12} \quad (10)$$

The PSRR vs. Ripple Frequency plots in *Typical Characteristics* show the ripple-induced phase spur levels at 156.25 MHz and 312.5 MHz. The LMK00338 exhibits very good and well-behaved PSRR characteristics across the ripple frequency range. The phase spur levels for HCSL are below -72 dBc at 156.25 MHz and below -63 dBc at 312.5 MHz. Using Equation 10, these phase spur levels translate to Deterministic Jitter values of 1.02 ps pk-pk at 156.25 MHz and 1.44 ps pk-pk at 312.5 MHz. Testing has shown that the PSRR performance of the device improves for Vcco = 3.3 V under the same ripple amplitude and frequency conditions.

11 Layout

11.1 Layout Guidelines

- For DC coupled operation of an HCSL driver, terminate with 50 Ω to ground near the driver output as shown in Figure 24.
- Keep the connections between the bypass capacitors and the power supply on the device as short as possible
- Ground the other side of the capacitor using a low impedance connection to the ground plane
- If the capacitors are mounted on the back side, 0402 components can be employed; however, soldering to the Thermal Dissipation Pad can be difficult
- For component side mounting, use 0201 body size capacitors to facilitate signal routing

11.2 Layout Example

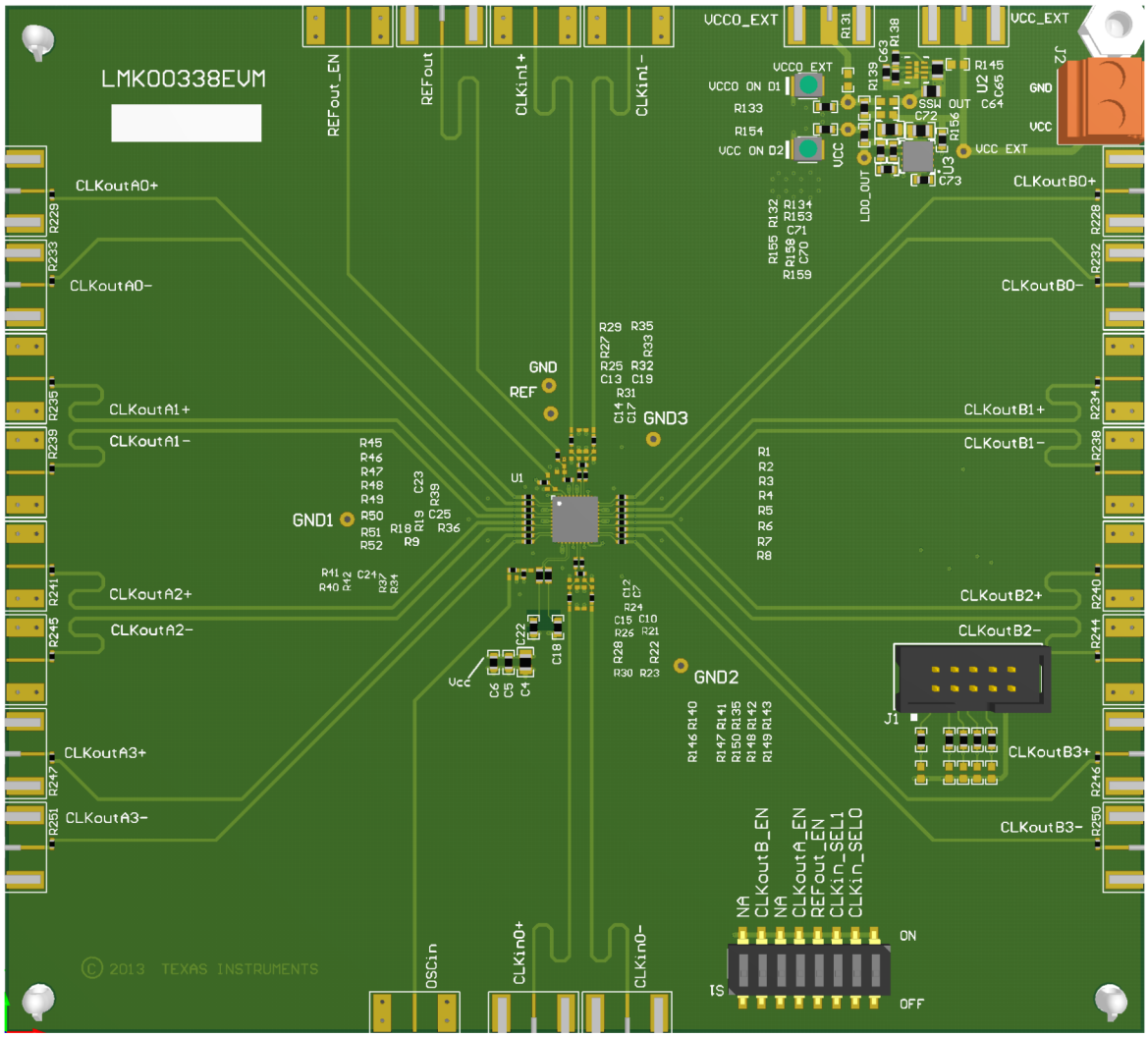


Figure 24. LMK00338 Layout Example

11.3 Thermal Management

Power dissipation in the LMK00338 device can be high enough to require attention to thermal management. For reliability and performance reasons the die temperature should be limited to a maximum of 125 °C. That is, as an estimate, T_A (ambient temperature) plus device power dissipation times $R_{\theta JA}$ should not exceed 125 °C.

The package of the device has an exposed pad that provides the primary heat removal path as well as excellent electrical grounding to the printed circuit board. To maximize the removal of heat from the package a thermal land pattern including multiple vias to a ground plane must be incorporated on the PCB within the footprint of the package. The exposed pad must be soldered down to ensure adequate heat conduction out of the package.

A recommended land and via pattern is shown in Figure 25. More information on soldering WQFN packages can be obtained at: http://www.ti.com/packaging.

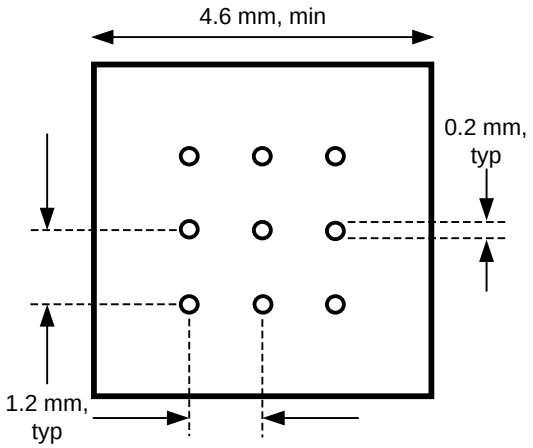


Figure 25. Recommended Land and Via Pattern

To minimize junction temperature it is recommended that a simple heat sink be built into the PCB (if the ground plane layer is not exposed). This is done by including a copper area of about 2 square inches on the opposite side of the PCB from the device. This copper area may be plated or solder coated to prevent corrosion but should not have conformal coating (if possible), which could provide thermal insulation. The vias shown in Figure 25 should connect these top and bottom copper layers and to the ground layer. These vias act as “heat pipes” to carry the thermal energy away from the device side of the board to where it can be more effectively dissipated.

12 器件和文档支持

12.1 文档支持

12.1.1 相关文档

如需相关文档，请参见以下内容：

- 《焊接相关的最大绝对额定值》(SNOA549)。
- 应用手册 AN-912《通用数据传输参数及其定义》(SNLA036)
- “如何优化 PCIe 应用中的时钟分配”，德州仪器 (TI) E2E 社区论坛。
- 《LMK00338EVM 用户指南》(SNAU155)。
- 《半导体和 IC 封装热指标》(SPRA953)。

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12.4 术语表

SLYZ022 — *TI 术语表*。

这份术语表列出并解释术语、首字母缩略词和定义。

13 机械封装和可订购信息

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LMK00338RTAR	ACTIVE	WQFN	RTA	40	1000	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	K00338	Samples
LMK00338RTAT	ACTIVE	WQFN	RTA	40	250	Green (RoHS & no Sb/Br)	CU SN	Level-3-260C-168 HR	-40 to 85	K00338	Samples

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PREVIEW: Device has been announced but is not in production. Samples may or may not be available.
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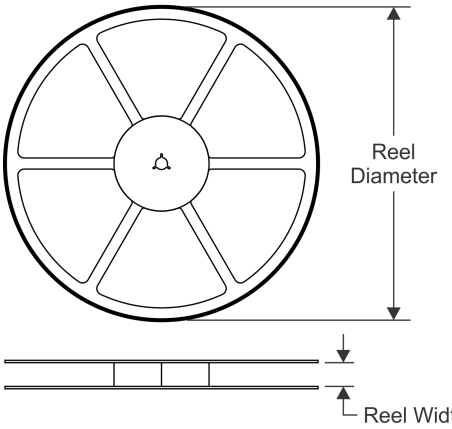

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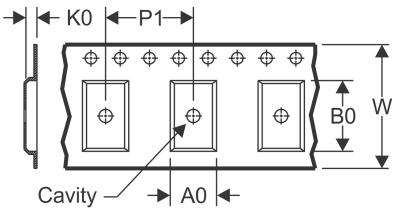
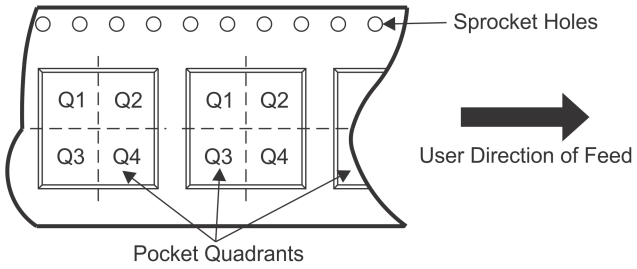


A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

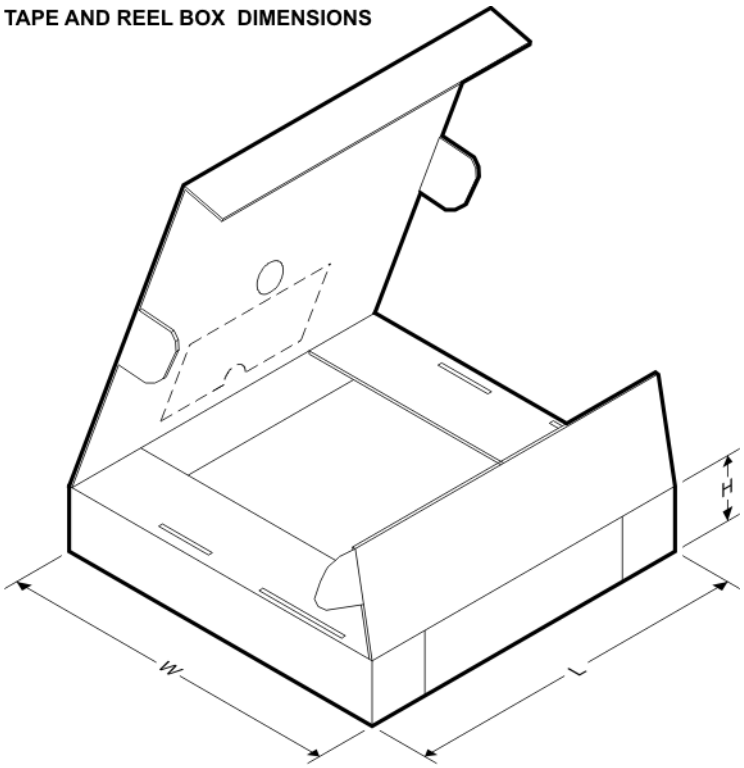
QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMK00338RTAR	WQFN	RTA	40	1000	330.0	16.4	6.3	6.3	1.5	12.0	16.0	Q1
LMK00338RTAT	WQFN	RTA	40	250	178.0	16.4	6.3	6.3	1.5	12.0	16.0	Q1

TAPE AND REEL BOX DIMENSIONS



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
LMK00338RTAR	WQFN	RTA	40	1000	367.0	367.0	38.0
LMK00338RTAT	WQFN	RTA	40	250	210.0	185.0	35.0

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