# BRUSHLESS MOTORS WITH INTEGRAL CONTROL





- Industry
- Medical
- > Railway
- > Renewable energy





# **ABOUT CROUZET MOTORS**

All around the world for more than 50 years, Crouzet Motors has been providing engineering expertise, high quality support and a complete offer of standard and customized direct drive and geared motors for all applications where performance is the key issue

**Crouzet Motors is a brand of** InnoVista Sensors™.

With a long-term commitment to technological excellence, the engineering teams have mastered the following core technologies and know-how:

- > Electromagnetism
- > Thermal dynamics
- > Electromechanical systems
- > Electronic drives

Covering the power range 1 to 400 watts (1/100 to Pumps and Valves.



InnoVista Sensors™: your trusted partner of choice to face industrial challenges of today and tomorrow.

InnoVista Sensors™ is a worldwide industrial specialist of sensors, controllers and actuators for automated systems.

Through its brands, Crouzet Aerospace, **Crouzet Automation, Crouzet Control, Crouzet Motors, Crouzet Switches and Systron Donner Inertial,** 

InnoVista Sensors™ offers a wide range of reliable, efficient and customizable components dedicated to the Aerospace & Defense, Transportation and Industrial market and segments.

Thanks to the recognized expertise of its teams and a strong innovation policy, InnoVista Sensors™ brings performance enhancing solutions to its customers worldwide.

www.innovistasensors.com

#### **Designs & Manufactures**



Sensors



**Controls** 



Actuators

#### For



**Aerospace** & Defense



**Transportation** 



Industry

#### With commercial brands













# ADAPTATION WHEEL

To meet market expectations and provide customers with the right solutions within the shortest timeframes, Crouzet Motors has structured its processes around the different types of product available: standard products, adapted products or products specially developed for a customer. Introducing the adaptation wheel...





#### Sales service

A full range of motors, geared motors and associated controllers. You can create your automation control applications as quickly as possible

# PRODUCTS WITH ADDED VALUE

### **Customer Adaptation Centre**

All our standard products can have additional factory-mounted auxiliaries or accessories: connectors, leads, special terminals, customized shafts, adaptor plates, etc. Seamless integration in your equipment means you benefit from simpler logistics and optimum installation reliability.



### **Customer Adaptation Centre**

Defined in coordination between your project teams and our specialists, these adapted products have exactly the right levels of performance and functionality you need for your applications.

## 4 SPECIAL PRODUCTS

#### Engineers and teams Dedicated project

From the very start of a project, Crouzet Motors' experts work closely with your teams to develop the specification. All our design, industrialization and approval expertise goes into developing Motion Control solutions that are tailored to your requirements.

# **DCmind BRUSHLESS**

Crouzet Motors, a specialist in customized motorization solutions, now launches the new generation of High Performance Brushless motors with integrated electronics TNi21 and SMi21.

A pioneer on the European market in 2002 with the Motomate, a Brushless motor with integrated electronics incorporating an intuitive visual programming interface, Crouzet Motors is blazing a new trail for compact standalone applications.

Crouzet Motors, a company continually evolving to meet customer needs, has upgraded its ranges with accessories, gearboxes, new part numbers and now, thanks to these new electronic devices, has enhanced the performance of its products with:

- ) more power
- ) more accuracy
- more functions
- > simplicity of use and ease of integration.

### **TWO NEW ELECTRONIC PILOT** CONTROL DEVICES

- The TNi21 for simpler applications, dedicated to speed and torque control.
- The SMi21, dedicated to motion control for applications that require accuracy. Thanks to a 4096-point encoder, it offers all the following control functions: position, torque, speed, direction, braking, etc.

A micro-USB socket on the motor (SMi21) can be used to link this directly to a PC.

COMMUNICATING

#### **BRAKING AND HOLDING** With or without failsafe holding brake (active braking is performed by the motor electronics). Pilot control card **CONTROL** > TNi21: 4 inputs and 3 outputs, torque and speed control on analog inputs with 10-bit Brake resolution. > SMi21: 6 inputs and 4 outputs, the motor has a wide selection of programs which can be set via a PC (position, speed and torque) and can reach as many as 65,000 positions. EMC filter Sensors Brushless motor

#### **POWER SUPPLY**

Single supply voltage needed across the whole voltage range:

- > TNi21 (10 36 VDC)
- > SMi21 (9 56 VDC)

#### **FILTERING AND PROTECTING**

- > Short-circuits, undervoltages
- > EMC (received and transmitted)
- > Temperature
- Mechanical (vibrations, shocks, etc.)

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THE MOTOR'S INTEGRATED ELECTRONICS ALLOW YOU TO:

#### **PRODUCT ADVANTAGES**

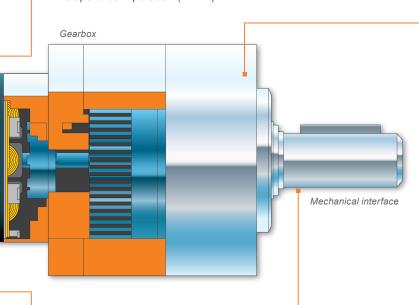
- > Easy and accurate control thanks to an optimized control loop
- Improved safety with internal thermal protection
- > Safe, reliable operation as a result of its excellent EMC characteristics, due to the shortest possible wiring and shielding with a metal cover

#### **USER ADVANTAGES**

- > Save time and improve reliability due to less wiring and fewer connections.
- **Control the logistic problem** better with fewer part numbers to manage
- Save space thanks to a more compact solution

#### **PILOT CONTROL**

Motor pilot control card for operation in 4 quadrants, sine operation (SMi21) or trapezoidal operation (TNi21).



#### **GEARBOXES**

Using Crouzet Motors gearboxes, the motor speed and torque can be adapted to your applications from 0.01 to 4000 rpm and 0.1 to 120 Nm (0.9 to 1062 in-lbs).

#### **INTEGRATION**

Crouzet Motors adapts the mechanical interfaces of its solutions for perfect integration in your equipment: fixing plate, transmission shafts, special pinions.

#### **SENSING**

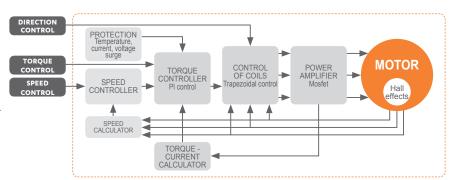
3 Hall effects for identifying the rotor position.

SMi21: plus 1 encoder (4096 pulses per motor revolution) for precision of regulation and sinusoidal power supply to the coils.

### INTEGRATED ELECTRONICS

### **TNi21 SPEED AND TORQUE CONTROL:**

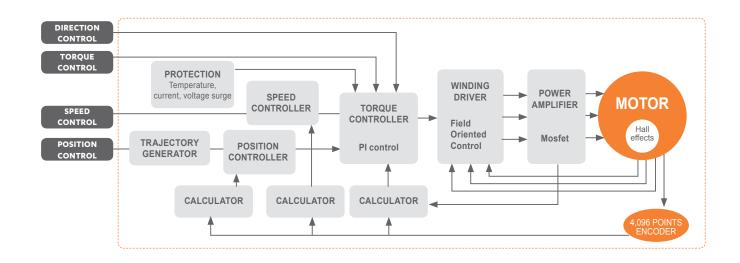
- > 4 inputs, 3 outputs.
- 2 x 10-bit analog inputs for fine-tuned speed and torque control.
- > 4 rejective quadrants.
- Use on its own or in combination with other motors or controlled by a PLC.
- Can be used in production immediately (without setup stage).
- Also suitable for a 12 V or 24 V battery power supply (voltage range between 10 and 36 volts).



### **SMi21 POSITION, SPEED AND TORQUE CONTROL:**

- > 6 inputs and 4 outputs, 2 of which are 10-bit analog inputs.
- Intuitive, easy-to-use setup software with application mode for quick start-up.
- Very flexible thanks to the various programs on offer. All the parameters are adjustable and can be used to optimise application operation.
- Also suitable for a 12 V, 24 V or 48 V battery power supply (voltage range between 9 and 56 volts).
- > Low power consumption when idling (1 W).

- > Rotor position controlled with 4096-point encoder and use of sinusoidal vector control.
- Reprogramming and re-use of motors as required by changing the application program or by modifying the configuration.
- > Firmware updating made easier with the "bootloader" function
- Use on its own, in combination with other motors or controlled by a PLC.



## THE NEW RANGE

						TYPE OF	GEARBOX	
	MOTOR TYPE		Nominal usable power at 24 VDC	Max. usable power	<b>P52</b> 25 Nm max.	<b>P62</b> 50 Nm max.	<b>P81</b> 120 Nm max.	<b>RAD10</b> 10 Nm max.
80140	C	TNi21	77 W	150 W	801495 TNi21	801496 TNi21	-	801410 TNi21
	C	SMi21	92 W	184 W	801495 SMi21	801496 SMi21	-	801410 SMi21
80180	Co	TNi21	100 W	211 W	-	801896 TNi21	801897 TNi21	801810 TNi21
	C	SMi21	105 W	314 W	-	801896 SMi21	801897 SMi21	801810 SMi21
80280	Co	TNi21	133 W	251 W	-	-	802897 TNi21	802810 TNi21
	C	SMi21	170 W	419 W	-	-	802897 SMi21	802810 SMi21

Nominal power ratings may vary according to the supply voltage.

Maximum power ratings are given for the maximum permissible motor voltage.

Example: the 80 280 SMi21 motor develops peak mechanical power of 419 W at 48 VDC.

#### **OPTIONS AND ACCESSORIES**

#### TNi21

- Motors available with or without mechanical brake for holding at breaking current.
- Supplied with 1 control cable and a power supply cable or with a M16 12-pin connector output including all the connections (motors 80140 and 80180).
- Accessory, shielded cable and 12-pin M16 connector.

#### SMi21

- Motors available with or without mechanical brake for holding at breaking current.
- Requires a standard commercially-available USB/ micro-USB cable and the setup software. This can be downloaded free of charge from the Crouzet website or ordered in the form of a "starter kit".

# SMi21: DCmind-SOFT SIMPLIFIED PROGRAMMING



#### SIMPLE AND INTUITIVE SOFTWARE

Available in several languages, with multiple possible uses, at any level of performance.

#### **2 PROGRAMMING MODES**

- Application approach: Select an application template, then set only those parameters that relate directly to your application. These programs use preset expert programs. You can fine-tune these settings by calling up the corresponding expert program.
- > Expert approach: for automation system programs and settings covering a wide range of parameters.



#### **DCmind-SOFT**

Available on our website **www.crouzet.com**, or can be supplied on a USB stick in the "starter kit".

## **APPLICATIONS**

Varied applications where position control, repeated movement and accuracy are key factors.



Stepper operation, detection of thrust and proportional adjustment of forces.



Performing cyclical operation, adjustment of speed and forces. Set to safety mode in the event of a fault.



Several motors combined, operation without a PLC, ease of assembly.



"Application" menu



"Expert" menu



"Parameter definition" mode

#### **CHARACTERISTICS**

#### 3 languages:

English, French, German.

#### Operating system:

XP Family, XP Pro, Vista, Windows 7.

#### **Application programs:**

Valve, conveyor belt, clamp, format adjustment, etc.

#### **Expert programs:**

Position, speed, torque with digital and analog inputs.

- > Numerous programs are available, offering:
  - 65,000 proportional positions which can be selected by two 0/10V inputs
  - 30 independent positions which can be selected by digital encoding
  - A variety of outputs which can be selected to suit your requirements
  - The option of setting inverted inputs, selecting 0/10V or PWM operation on the analog inputs, and even setting their operating limit stops
  - The option of modifying the control loop PID parameters for difficult applications
  - Automatic detection of the reference position for position control ("homing" function)
- Special programs created on request, firmware updating made easier with the "Bootloader" function
- > Loading programs simplified with a USB connection
- > Other programs to come, please visit our website

#### **SOME EXAMPLES OF APPLICATIONS**

Format adjustment, automatic feed, synchronization, flow control, accurate dosage.



Operation on 12 V battery, low consumption.



S curve pilot control and operation on 12 V backup battery.



Speed pilot control

### **DCmind: BRUSHLESS MOTORS**

# Motors 38 to 145 W nominal output power range with TNi21 Speed and Torque Control

- > For control speed and torque applications
- > Very high power density
- 4 inputs (where 2 of them analog) / 3 outputs integrated electronic controls
- > Holding torque function
- ) Battery supply compatible 12 V and 24 V

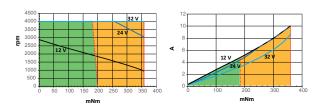


	38 to 75 W		45 to	102 W		<b>72 to 145 W</b> 80280 TNi21				
Type	80140 TNi2	]	80180	TNi21						
Part numbers										
PWM speed mode, cable output	80140059		80180	056		80280	013			
0-10 V speed mode, cable output	80140051		80180	050		80280	007			
PWM speed mode, connector M16 - 12 pins	80140079		80180	072						
0-10 V speed mode, connector M16 - 12 pins	80140071		80180							
Nominal power supply range (V===)	12 - 32		12 - 3			12 - 32				
Min. max. power supply (V===)	10 - 36		10 - 3			10 - 36 12 V== 24 V== 32				
No-load characteristics	12 V== 24 V			24 V						
Speed of rotation (rpm)	2900 400		2100	4000	3950	2000	3950	3950		
Absorbed current (A)	0.34 0.29		0.35	0.39	0.34	0.5	0.7	0.6		
Nominal characteristics	12 V== 24 V							32 V=		
Speed (rpm)	1900 400		1250	3350	3900	1400	3250	3900		
Absorbed current (A)	5.2 4.4	3.2	6.7	5.4	4	8.5	6.9	6		
Torque (mNm)	193 184	178	340	285	250	490	390	355		
Output power (W)	38 77	75	45	100	102	72	133	145		
Maximal characteristics	12 V== 24 V							32 V		
Speed (rpm)	1600 305		1040	2160	3100	800	1900	2400		
Absorbed current (A)	6.5 10	10	7.2	11	12	15	15	12.5		
Torque (mNm)	250 358	358	400	600	650	1000	1000	1000		
Output power (W)	42 114	150	44	136	211	84	199	251		
General characteristics										
Regulation (quadrants)	4		4			4				
Conformity to EMC Directive in accordance with (EN 55022)	Class B		Class			Class				
Insulation conforming to IEC60085	Class E		Class	E		Class	В			
Thermal time constant (mn)	20		30			30				
Noise level (dBA)	40		40			50				
Inertia (g.cm²)		75			115			120		
Number of rotor poles	4		4 -30 →			8				
Ambient operating temperature (°C)		-30 → +70								
Service life (h)		20000			20000					
Ball bearing		<u> </u>			1.24					
Weight (kg)	0.95		1.34			1.44				
0-10 V or PWM Speed input characteristics	00		00			00				
Input impedance (kΩ)	69		69	4000		69	4000			
Speed control (rpm)	120 → 4000		120 →	4000		120 →	4000			
Level 0 input voltage (V)	0 → 2		0 → 2	00		0 → 2	00			
Level 1 input voltage (V)	7.5 → 39		7.5 →			7.5 →				
Frequency range (Hz)	100 → 2000		100 →	2000		100 →	<b>2000</b>			
0-10 V or PWM Torque input characteristics Input impedance (kΩ)	69		69			69				
Torque limit (mNm)	360 → 35		700 →	20		1000 -	. 10			
Holding limit (mNm)	150 → 35		230 →			310 →				
Level 0 input voltage (V)	$\frac{150 \rightarrow 35}{0 \rightarrow 2}$		$0 \rightarrow 2$	30		$\frac{310}{0}$	40			
Level 1 input voltage (V)	7.5 → 39		7.5 →	30		7.5 →	30			
Frequency range (Hz)	100 → 2000		100 →			100 →				
On/Off and Direction digital input characteristics	100 → 2000		100 →	2000		100 →	2000			
Input impedance ( $k\Omega$ )	57		57			57				
Level 0 input voltage (V===)	0 → 2		0 → 2			0 → 2		-		
Level 1 input voltage (V==)	4 → 39		4 → 39	)		4 → 39	)			
			4 → 38	,		4 → 38	,			
Torque alarm, Encoder and Direction output characterist			DND			DND				
Type of output-Maximum admissible current (mA)	PNP		PNP			PNP				
Maximum admissible current (mA)	50	100	50			50				
IP65 over the whole motor apart from the shaft output. Versic	ons with brake are IF	20								
Accessory										
2 metre shielded cable with 12-pin female M16 connector						15275	800			

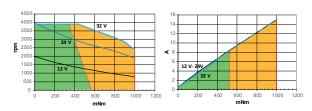


#### Speed / Torque 80140 TNi21 - Current / Torque 80140 TNi21

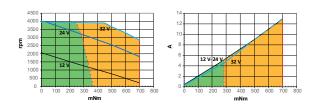
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#### Speed / Torque 80280 TNi21 - Current / Torque 80280 TNi21



#### Speed / Torque 80180 TNi21 - Current / Torque 80180 TNi21



Continuous running area

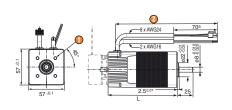
Cycling running area

--- Maximum continuous torque

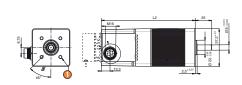
— Maximum peack torque

#### **Dimensions (mm)**

#### Cable output versions



#### M16 connector version - 12 pins



L: 80140: 92 max

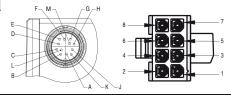
L: 80180 / 80280: 112 max

L2: 80140: 123 max L2: 80180 / 80280: 143 max

More information: see page 16

#### **Connections**

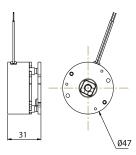
	Connector	Cable	
	M16	color	
Power ground	G+M	AWG16 Blue	
Power supply +12 to +32 V DC	E+F	AWG16 Brown	F→ M→
Logic ground	Н	AWG24 Black (5)	. \"
Input 1: On/Off	С	AWG24 Green (1)	E-
Input 2: Direction	В	AWG24 Yellow (2)	D- 1000
Input 3: Speed	J	AWG24 Orange (4)	0 00
Output 1: Tachometer*	Α	AWG24 Brown (6)	0
Output 2: Real direction	L	AWG24 Red (8)	
Input 4: Torque	D	AWG24 Blue (3)	B-LLL
Output 3: Torque at max.	K	AWG24 Purple (7)	



#### **Options**

#### **Product adaptations**

#### Holding brake 0.5 Nm - 24 V==





- Shaft, pinion, pulley dimensions Cable wire length Powerful controlled brake (directed)

- Programs evolution

#### **User information**

Notice available on website, please read it before use.

<sup>\* 12</sup> p/rev. and 24 for 80280 motor

# Motors 34 to 192 W nominal output power range with SMi21 Position, Speed and Torque Control

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- Servomotor for position, speed and torque control applications
- Very high power density
- Built-in electronics with 6 inputs (2 of which are analog) and 4 outputs
- > Built-in 4096-pulse encoder
- With application programs already preset and saved in the motor
- Expert programs can be used to adapt to the requirements of difficult applications
- Parameters set on the PC via USB connection
- Integrated bootloader for embedding special customer firmware



Part numbers           IP65 option         80°           Holding torque brake 0.5 Nm option         80°           Nominal operating range (V)         12           Min. max. operating range (V)         9 -           No-load characteristics         12           Speed of rotation (rpm)         240°           Absorbed current (A)         0.3           Nominal characteristics         12           Speed (rpm)         146°           Torque (mNm)         225°           Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12           Speed of rotation (rpm)         110°           Torque (mNm)         30°           Absorbed current (A)         7           Output power (W)         34           General characteristics         8           Rotor inertia (gcm²)         75           Number of rotor poles         4	1004 1004 48 6 6 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	24 V 4000 0.3 24 V 3900 225 5.2 92 24 V 3000 400 9.5 125	48 V= 4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1 184	80180 80180 801800 12 - 48 9 - 56 12 V= 1700 0.3 12 V= 1100 350 5.65 40 12 V= 1000 400 6.4 42	044 045 3 3500 0.33 24 V= 2900 350 5.40 105	48 V 4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1 314	80280 80280 802800 12 - 48 9 - 56 12 V== 1500 0.38 12 V== 1100 685 10 82 12 V== 740 1000 14 77	001 002 3 3050 0.44 24 V== 2863 565 8 170	4000 0.35 48 V= 4000 5 192 48 V= 4000 1000
P65 option	6004 48 6 	24 V 4000 0.3 24 V 3900 225 5.2 92 24 V 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	801800 12 - 48 9 - 56 12 V 1700 0.3 12 V 1100 350 5.65 40 12 V 1000 400 6.4 42	24 V = 3500 0.33 24 V = 2900 350 5.40 105 24 V = 2400 600 10	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	802800 12 - 48 9 - 56 12 V= 1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	24 V 3050 0.44 24 V 2863 565 8 170 24 V 2250 1000	4000 0.35 48 V= 4000 5 192 48 V= 4000 1000
Holding torque brake 0.5 Nm option	6004 48 6 	24 V 4000 0.3 24 V 3900 225 5.2 92 24 V 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	801800 12 - 48 9 - 56 12 V 1700 0.3 12 V 1100 350 5.65 40 12 V 1000 400 6.4 42	24 V = 3500 0.33 24 V = 2900 350 5.40 105 24 V = 2400 600 10	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	802800 12 - 48 9 - 56 12 V= 1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	24 V 3050 0.44 24 V 2863 565 8 170 24 V 2250 1000	4000 0.35 48 V 4000 460 5 192 48 V 4000
Nominal operating range (V)   12	448 66 	24 V 4000 0.3 24 V 3900 225 5.2 92 24 V 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	12 - 48 9 - 56 12 V 1700 0.3 12 V 1100 350 5.65 40 12 V 1000 400 6.4 42	3500 0.33 24 V = 2900 350 5.40 105 24 V = 2400 600	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	12 - 48 9 - 56 12 V= 1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	3050 0.44 24 V=- 2863 565 8 170 24 V=- 2250 1000 14	4000 0.35 48 V= 4000 5 192 48 V= 4000 1000
Min. max. operating range (V==)       9 -         No-load characteristics       12         Speed of rotation (rpm)       240         Absorbed current (A)       0.3         Nominal characteristics       12 / 12         Speed (rpm)       140         Torque (mNm)       225         Absorbed current (A)       5.2         Output power (W)       34         Maximal characteristics       12         Speed of rotation (rpm)       111         Torque (mNm)       300         Absorbed current (A)       7         Output power (W)       34         General characteristics       7         Rotor inertia (gcm²)       75         Number of rotor poles       4         Ambient operating temperature (°C)       -30         Service life (h)       200         Ball bearing       V         Weight (kg)       1.1         Integrated software       1	66	4000 0.3 24 V== 3900 225 5.2 92 24 V== 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	9 - 56 12 V= 1700 0.3 12 V= 1100 350 5.65 40 12 V= 1000 400 6.4 42	24 V= 3500 0.33 24 V= 2900 350 5.40 105 24 V= 2400 600 10	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	9 - 56 12 V= 1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	24 V== 3050 0.44 24 V== 2863 565 8 170 24 V== 2250 1000 14	48 V= 4000 460 5 192 48 V= 4000 1000
No-load characteristics         12           Speed of rotation (rpm)         240           Absorbed current (A)         0.3           Nominal characteristics         12           Speed (rpm)         146           Torque (mNm)         225           Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12           Speed of rotation (rpm)         111           Torque (mNm)         30           Absorbed current (A)         7           Output power (W)         34           General characteristics         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software		4000 0.3 24 V== 3900 225 5.2 92 24 V== 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	12 V= 1700 0.3 12 V= 1100 350 5.65 40 12 V= 1000 400 6.4 42	3500 0.33 24 V== 2900 350 5.40 105 24 V== 2400 600 10	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	12 V= 1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	3050 0.44 24 V== 2863 565 8 170 24 V== 2250 1000 14	4000 0.35 48 V= 4000 5 192 48 V= 4000 1000
Speed of rotation (rpm)         240           Absorbed current (A)         0.3           Nominal characteristics         12           Speed (rpm)         146           Torque (mNm)         226           Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12           Speed of rotation (rpm)         110           Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software		4000 0.3 24 V== 3900 225 5.2 92 24 V== 3000 400 9.5 125	4000 0.2 48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	1700 0.3 12 V 1100 350 5.65 40 12 V 1000 400 6.4 42	3500 0.33 24 V== 2900 350 5.40 105 24 V== 2400 600 10	4000 0.2 48 V 4000 350 3.65 145 48 V 4000 750 10.1	1500 0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	3050 0.44 24 V== 2863 565 8 170 24 V== 2250 1000 14	4000 0.35 48 V= 4000 5 192 48 V= 4000 1000
Absorbed current (A)  Nominal characteristics  Speed (rpm)  Torque (mNm)  Absorbed current (A)  Output power (W)  Maximal characteristics  Speed of rotation (rpm)  Torque (mNm)  Absorbed current (A)  7  Output power (W)  Absorbed current (A)  7  Output power (W)  Absorbed current (A)  7  Output power (W)  34  General characteristics  Rotor inertia (gcm²)  Number of rotor poles  4  Ambient operating temperature (°C)  Service life (h)  Ball bearing  V  Weight (kg)  Integrated software		0.3 3900 225 5.2 92 24 V= 3000 400 9.5 125	0.2 48 V== 4000 225 2.6 94 48 V== 4000 440 6.1	0.3 12 V= 1100 350 5.65 40 12 V= 1000 400 6.4 42	0.33 24 V==2900 350 5.40 105 24 V==2400 600	0.2 48 V== 4000 350 3.65 145 48 V== 4000 750 10.1	0.38 12 V= 1100 685 10 82 12 V= 740 1000 14	0.44 24 V== 2863 565 8 170 24 V== 2250 1000 14	0.35 48 V= 4000 460 5 192 48 V= 4000 1000
Absorbed current (A)         0.3           Nominal characteristics         12 Nominal characteristics           Speed (rpm)         144           Torque (mNm)         225           Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12 Nominal characteristics           Speed of rotation (rpm)         111           Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         8           Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software	) ;	24 V 3900 225 5.2 92 24 V 3000 400 9.5 125	48 V= 4000 225 2.6 94 48 V= 4000 440 6.1	12 V= 1100 350 5.65 40 12 V= 1000 400 6.4 42	24 V== 2900 350 5.40 105 24 V== 2400 600 10	48 V 4000 350 3.65 145 48 V 4000 750	1100 685 10 82 12 V= 740 1000 14	24 V== 2863 565 8 170 24 V== 2250 1000 14	48 V= 4000 460 5 192 48 V= 4000 1000
Nominal characteristics	) ;	3900 225 5.2 92 24 V= 3000 400 9.5 125	4000 225 2.6 94 48 V 4000 440 6.1	1100 350 5.65 40 12 V 1000 400 6.4 42	2900 350 5.40 105 24 V== 2400 600 10	4000 350 3.65 145 48 V== 4000 750 10.1	1100 685 10 82 12 V=- 740 1000	2863 565 8 170 24 V== 2250 1000 14	4000 460 5 192 48 V= 4000 1000
Speed (rpm)         146           Torque (mNm)         225           Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12           Speed of rotation (rpm)         110           Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         7           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software         1.1	) ;	3900 225 5.2 92 24 V= 3000 400 9.5 125	4000 225 2.6 94 48 V 4000 440 6.1	1100 350 5.65 40 12 V 1000 400 6.4 42	2900 350 5.40 105 24 V== 2400 600 10	4000 350 3.65 145 48 V== 4000 750 10.1	1100 685 10 82 12 V=- 740 1000	2863 565 8 170 24 V== 2250 1000 14	4000 460 5 192 48 V= 4000 1000
Absorbed current (A)         5.2           Output power (W)         34           Maximal characteristics         12           Speed of rotation (rpm)         111           Torque (mNm)         30           Absorbed current (A)         7           Output power (W)         34           General characteristics         Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software         1.1	)	5.2 92 24 V== 3000 400 9.5 125	2.6 94 48 V 4000 440 6.1	5.65 40 12 V== 1000 400 6.4 42	5.40 105 24 V== 2400 600 10	3.65 145 48 V 4000 750 10.1	10 82 12 V 740 1000 14	8 170 24 V== 2250 1000 14	5 192 48 V= 4000 1000
Output power (W)         34           Maximal characteristics         12 No. 12 No	) ;	92 24 V== 3000 400 9.5 125	94 48 V== 4000 440 6.1	40 12 V== 1000 400 6.4 42	105 24 V 2400 600 10	145 48 V== 4000 750 10.1	82 12 V= 740 1000 14	170 24 V== 2250 1000 14	192 48 V= 4000 1000
Maximal characteristics         12           Speed of rotation (rpm)         110           Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         8           Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software         1.1	) :	24 V= 3000 400 9.5 125	48 V== 4000 440 6.1	12 V 1000 400 6.4 42	24 V== 2400 600 10	48 V== 4000 750 10.1	740 1000 14	24 V= 2250 1000 14	48 V= 4000 1000
Speed of rotation (rpm)         110           Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software	) ;	3000 400 9.5 125	4000 440 6.1	1000 400 6.4 42	2400 600 10	4000 750 10.1	740 1000 14	2250 1000 14	1000
Torque (mNm)         300           Absorbed current (A)         7           Output power (W)         34           General characteristics         Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software		400 9.5 125	440 6.1	400 6.4 42	600	750 10.1	1000	1000 14	1000
Absorbed current (A)         7           Output power (W)         34           General characteristics         75           Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software		9.5	6.1	6.4	10	10.1	14	14	
Output power (W)         34           General characteristics         75           Rotor inertia (gcm²)         75           Number of rotor poles         4           Ambient operating temperature (°C)         -30           Service life (h)         200           Ball bearing         ✓           Weight (kg)         1.1           Integrated software         1.1		125		42					11.5
General characteristics  Rotor inertia (gcm²) 75  Number of rotor poles 4  Ambient operating temperature (°C) -30  Service life (h) 200  Ball bearing ✓  Weight (kg) 1.1  Integrated software			184		151	314	77	235	
Rotor inertia (gcm²) 75 Number of rotor poles 4 Ambient operating temperature (°C) -30 Service life (h) 200 Ball bearing ✓ Weight (kg) 1.1 Integrated software	<b>→</b> +7			115					419
Number of rotor poles  Ambient operating temperature (°C)  Service life (h)  Ball bearing  Weight (kg)  Integrated software	→ +7			115					
Ambient operating temperature (°C) -30 Service life (h) 200 Ball bearing ✓ Weight (kg) 1.1 Integrated software	→ +7						120		
Service life (h) 200 Ball bearing ✓ Weight (kg) 1.1 Integrated software	<del>→</del> +7			4			8		
Ball bearing  Weight (kg)  Integrated software	_	70		-30 → 7	-		-30 → -		
Weight (kg) 1.1 Integrated software	00			20000			20000		
Integrated software				✓			✓		
				1.52			1.62		
Applications software ✓									
				✓			✓		
Positioning mode   ✓				✓			✓		
Speed mode   ✓				✓			✓		
Torque mode ✓				✓			<b>√</b>		
Inputs / Outputs									
Analog inputs (PWM and 0-10 V) 2				2			2		
Digital inputs 4				4			4		
(PWM) output 2				2			2		
Digital output 2				2			2		
IP65 over the whole motor apart from the shaft output. Versions with bra	e ar	re IP20							

#### **Product adaptations**

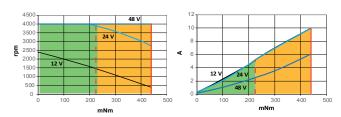


- Other specific applications software
- Specific PC interface
- Special cable lenght
  Special shaft
- Other connectors



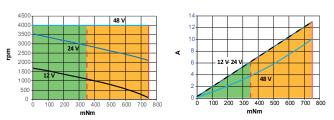
#### **Curves**

#### Speed / Torque 80140 SMi21- Current / Torque 80140 SMi21

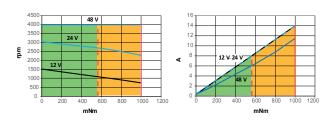


| 13

#### Speed / Torque 80180 SMi21 - Current / Torque 80180 SMi21



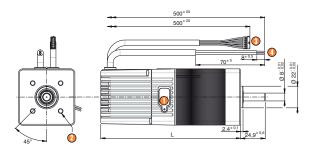
#### Speed / Torque 80280 SMi21- Current / Torque 80280 SMi21



Continuous running area
Cycling running area
Maximum continuous torque
Maximum peack torque

#### **Dimensions (mm)**

#### 80140 - 80180 - 80280 SMi21



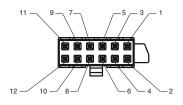
- USB connection type B
- ② 4 x M5 over Ø 40 depth 4.5
- 10 Command cable 12 x AWG26
- O Power cable 2 x AWG16

L: 80140: 123 max L: 80180 / 80280: 143 max

More information: see page 16

#### Connection

#### Connector (Molex 0430251200)



PIN	Logic cable				
	Description	Wires			
		color			
4		Green			
1	Input 1 - logic	Green			
2	Input 2 - logic	Yellow			
3	Input 3 - logic	White			
4	Input 4 - logic	White-brown			
5	Input 5 - analog	Blue			
6	Input 6 - analog	Orange			
7	0 V===	Black			
8	0 V===	White-black			
9	Output 1 - PWM	Brown			
10	Output 2 - PWM	Purple			
11	Output 3 - logic	Reed			
12	Output 4 - logic	Grey			

Power cable								
Description	Wires							
	color							
+12 V== → 48 V==	Brown							
0 V===	Blue							

#### **User information**

Notice available on website, please read it before use.

#### **GEARBOXES FOR DCmind BRUSHLESS RANGE**

#### 4 to 120 Nm

- > Planetary and worm gearboxes
- > Shafts on ball bearings
- ) Long service life
- ) IP65









#### Part numbers

Gearboxes	Planetary Ø 52		Planetary Ø 62			Planeta	ry Ø 81		Worm	
Type	810495			810496	810496					810410
	Part number			Part nu	Part number			mber		Part number
80140 TNi21	801495 TNi21		801496 TNi21						801410 TNi21	
80180 TNi21					801896 TNi21			TNi21		801810 TNi21
80280 TNi21								TNi21		802810 TNi21
80140 SMi21	801495	801495 SMi21			801496 SMi21					801410 SMi21
80180 SMi21					801896 SMi21			SMi21		801810 SMi21
80280 SMi21							802897 SMi21			802810 SMi21
Gearbox characteristics										
Number of stages	1	2	3	1	2	3	1	2	3	1
Maximum permitted torque (Nm)	4	12	25	8	25	50	20	60	120	10
Efficiency	0.8	0.75	0.7	0.9	0.8	0.7	0.9	0.8	0.7	0.6 → 0.3
Axial dynamic load (daN)	<u> </u>	10	15	7	10	15	8	12	20	10
Radial dynamic load (daN)	20	32	45	24	36	52	40	60	100	15
Operating temperature	-2	0 <del>→</del> +70	°C	-20 → +70°C			-20 → +70°C			-20 → +70°C
Weight (kg)	0.7	0.8	1.1	0.8	1.2	1.6	1.8	2.5	3.2	0.7
Standard reduction ratios	6.75	25	93	5.16	19	100	5	19	100	5 - 10 - 20 - 30 - 50
		46	169	6.75	27	139		27	139	
			308		46	236			236	
						308				
Other ratios possible										15 - 100
Comments										

Ø 52 planetary gearbox: Metal gears on all stages. IP65 apart from the output shaft.

Ø 62 planetary gearbox: On the first stage, the planet gears are made of composite materials which improve efficiency and service life. On the other stages, the metal gears turn on needle bearings. IP65 apart from the output shaft.

Ø 81 planetary gearbox: All gears are metal and turn on needle bearings, resulting in excellent robustness and a very long service life. IP65 apart from the output shaft.

**Worm gearbox:** This gearbox combines a tempered steel worm and a hard bronze helical gear wheel, thus ensuring a long service life. The wheel is coated with grease, ensuring an excellent slip coefficient and good heat dissipation. O-rings and lipseals are used in combination with a compression spring to create a tight seal at the gearbox output shaft and the motor input shaft. IP65 gearbox.

The casing is made of aluminium to maximise heat exchanges with its supporting surface on the machine.

However, due to the high power that can be transmitted by this gearbox and the low efficiency inherent in large worm gearbox reduction ratios, make sure that the gearbox casing temperature does not exceed 75°C during operation.

The output shaft can be placed on the right or left, or can be a double shaft (shaft output on both sides).

#### Made to order products, available on request

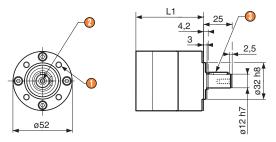


- Special shafts
- ) Other reduction ratios
- ) Other fixing holes
- Special mounting flange

Product made to order

#### **Dimensions (mm)**

#### Planetary gearbox Ø 52 (810495)



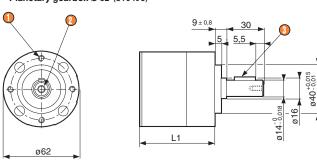
① 4 x M5 at 90°, depth 10 over Ø 40

**2** M4 x 10

O Parallel key 4 x 4 x 16 DIN 6885 A

L1 1 stage: 55.3 ± 0.5 L1 2 stages: 69.5 ± 0.5 L1 3 stages: 83.7 ± 0.5

#### Planetary gearbox Ø 62 (810496)



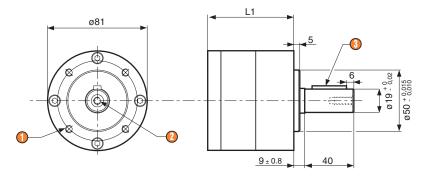
#### 10 4 x M5 at 90°, depth 10 over Ø 52

2 M5, depth 12.5

O Parallel key 5 x 5 x 18 DIN 6885 A

L1 1 stage: 52.1 ± 0.7 L1 2 stages: 67.9 ± 0.7 L1 3 stages: 83.8 ± 0.7

#### Planetary gearbox Ø 81 (810497)



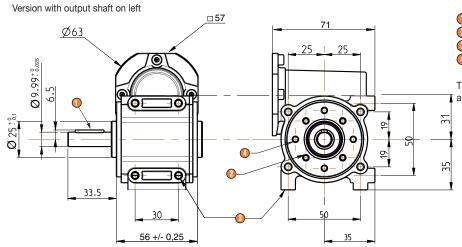
0 4 x M6, depth 12 over Ø 65

**2** M6 x 16

3 Parallel key 6 x 6 x 28 DIN 6885 A

L1 1 stage:  $70.5 \pm 0.6$ L1 2 stages:  $92.2 \pm 0.6$ L1 3 stages:  $113.8 \pm 0.6$ 

#### Worm gearbox RAD10 (810410)



Parallel key 4 x 4 x 20 DIN6885

2 4 x M4, depth 8 over Ø 36

3 8 x M5, depth 8

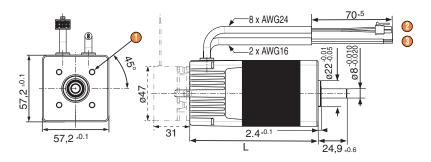
0 4 x Ø 3.8 depth 10 over Ø 40

The left-hand and right-hand sides of the gearbox are identical.

# DCmind BRUSHLESS DIRECT MOTOR TNi21 & SMi21 CABLE OUTPUT OR WITH CONNECTOR M16

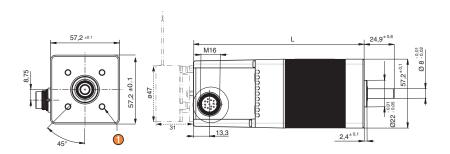
#### **Dimensions (mm)**

80140 - 80180 - 80280 - TNi21 version output cable with or without brake



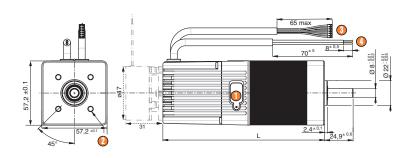
- L 80140: 92 max. L 80180: 112 max. L 80280: 112 max.
- ① 4 x M5 at 90°, depth 6 over Ø 40 ② Command cable 8 x AWG24 / 500 mm
- O Power cable 2 x AWG16 / 500 mm

80140 - 80180 - TNi21 version connector M16 - 12 pins with or without brake



- L 80140: 123 max. L 80180: 143 max.
- 10 4 x M5 at 90°, depth 6 over Ø 40

80140 - 80180 - 80280 - SMi21 with or without brake

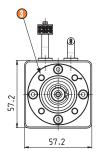


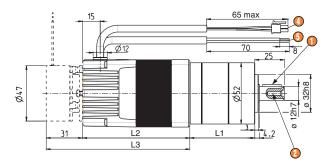
- L 80140: 123 max.
- L 80180: 143 max.
- L 80280: 143 max.
- USB connection type B
- 2 4 x M5 at 90°, depth 6 over Ø 40
- Ommand cable 10 x AWG24 / 500 mm
- O Power cable 2 x AWG16 / 500 mm

# DCmind BRUSHLESS GEARED MOTOR TNi21 CABLE OUTPUT

#### **Dimensions (mm)**

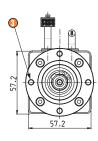
#### 801495 - TNi21 + P52 with or without brake

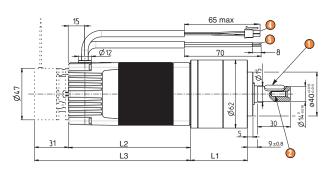




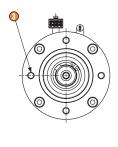
- L1 1 stage: 55.3 ±0.5
- L1 2 stages: 69.5 ±0.5
- L1 3 stages: 83.7 ±0.5
- L2 80140: 92 max.
- L3 80140: 123 max.
- O Parallel key 4 x 4 x 16 DIN 6885 A
- **2** M4 x 10
- 3 4 x M5 at 90°, depth 10 over Ø 40
- Ocommand cable 8 x AWG24 / 500 mm
- 1 Power cable 2 x AWG16 / 500 mm

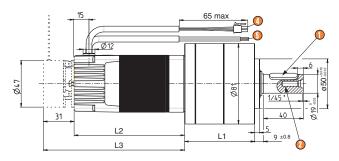
801496 - 801896 - TNi21 + P62 with or without brake





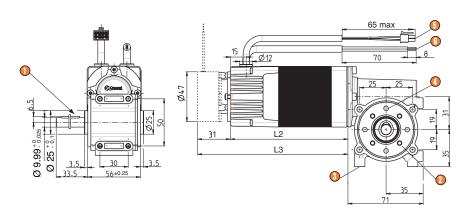
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801897 - 802897 - TNi21 + P81 with or without brake

801410 - 801810 - 802810 - TNi21 + RAD10 with or without brake



- L1 1 stage: 52.1 ±0.7
- L1 2 stages: 67.9 ±0.7
- L1 3 stages: 83.8 ±0.7
- L2 80140: 92 max.
- L2 80180: 112 max.
- L3 80140: 123 max.
- L3 80180: 143 max.
- O Parallel key 5 x 5 x 18 DIN 6885 A
- **2** M5 x 12
- 3 4 x M5 at 90°, depth 10 over Ø 52
- O Command cable 8 x AWG24 / 500 mm
- 1 Power cable 2 x AWG16 / 500 mm
- L1 1 stage: 70.5 ±0.6
- L1 2 stages: 92.2 ±0.6
- L1 3 stages: 113.8 ±0.6
- L2 80180-80280: 112 max.
- L3 80180-80280: 143 max.
- Parallel key 6 x 6 x 28 DIN 6885 A
- **2** M6 x 16
- 3 4 x M6 at 90°, depth 12 over Ø 65
- Ocommand cable 8 x AWG24 / 500 mm
- Power cable 2 x AWG16 / 500 mm

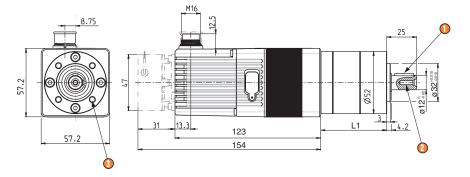
L2 80140: 92 max.

- L2 80180-80280: 112 max.
- L3 80140: 123 max.
- L3 80180-80280: 143 max.
- Parallele key 4 x 4 x 20 DIN 6885 A
- 4 x M4, depth 8 over Ø 36
- 3 8 x M5 depth 8
- 0 4 x Ø 3,8, depth 10 over Ø 40
- Command cable 8 x AWG24 / 500 mm
- 1 Power cable 2 x AWG16 / 500 mm

### **DCmind BRUSHLESS GEARED MOTOR TNi21 WITH CONNECTOR M16**

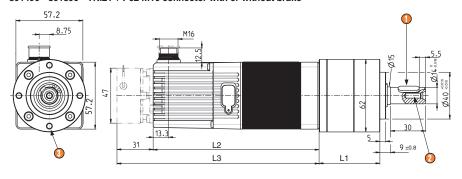
#### Dimensions (mm)

#### 801495 - TNi21 + P52 M16 connector with or without brake



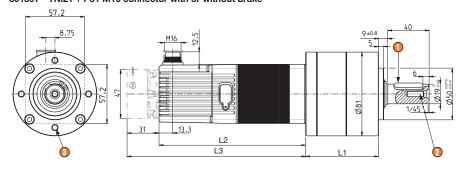
- L1 1 stage: 55.3 ±0.5
- L1 2 stages: 69.5 ±0.5
- L1 3 stages: 83.7 ±0.5
- Parallel key 4 x 4 x 16 DIN 6885 A
- **2** M4 x 10
- 3 4 x M5 at 90°, depth 10 over Ø 40

801496 - 801896 - TNi21 + P62 M16 connector with or without brake



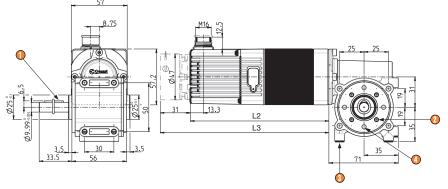
- L1 1 stage: 52.1 ±0.7
- L1 2 stages: 67.9 ±0.7
- L1 3 stages: 83.8 ±0.7
- L2 80140: 123 max.
- L2 80180: 143 max.
- L3 80140: 154 max. L3 80180: 174 max.
- O Parallel key 5 x 5 x 18 DIN 6885 A
- **2** M5 x 12
- 3 4 x M5 at 90°, depth 10 over Ø 52

801897 - TNi21 + P81 M16 connector with or without brake



- L1 1 stage: 70.5 ±0.6
- L1 2 stages: 92.2 ±0.6
- L1 3 stages: 113.8 ±0.6
- L2 80180: 143 max.
- L3 80180: 174 max.
- Parallel key 6 x 6 x 28 DIN 6885 A
- **2** M6 x 16
- 12 over Ø 65 4 x M6, depth 12 over Ø 65

801410 - 801810 - TNi21 + RAD10 M16 connector with or without brake

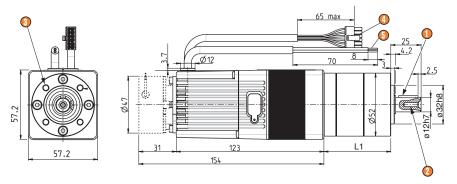


- L2 80140: 123 max.
- L2 80180-80280: 143 max.
- L3 80140: 154 max.
- L3 80180-80280: 174 max.
- Parallel key 4 x 4 x 20 DIN 6885 A
- ② 4 x M4, depth 8 over Ø 36
- 3 8 x M5, depth 8
- 4 x 3.8, depth 10 over Ø 40

# DCmind BRUSHLESS GEARED MOTOR SMi21 CABLE OUTPUT

#### **Dimensions (mm)**

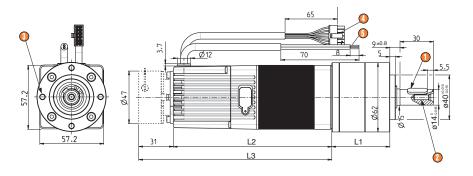
#### 801495 - SMi21 + P52 with or without brake



L1 1 stage: 55.3 ±0.5 L1 2 stages: 69.5 ±0.5 L1 3 stages: 83.7 ±0.5

- Parallel key 4 x 4 x 16 DIN 6885 A
- **2** M4 x 10
- 3 4 x M5 at 90°, depth 10 over Ø 40
- O Command cable 12 x AWG26 / 500 mm
- 1 Power cable 2 x AWG16 / 500 mm

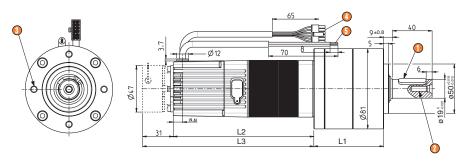
801496 - 801896 - SMi21 + P62 with or without brake



L1 1 stage: 52.1 ±0.7 L1 2 stages: 67.9 ±0.7 L1 3 stages: 83.8 ±0.7

- L2 80140: 123 max.
- L2 80180: 143 max.
- L3 80140: 154 max.
- L3 80180: 174 max.
- Parallel key 5 x 5 x 18 DIN 6885 A
- **2** M5 x 12
- 3 4 x M5 at 90°, depth 10 over Ø 52
- Ocommand cable 12 x AWG26 / 500 mm
- Power cable 2 x AWG16 / 500 mm

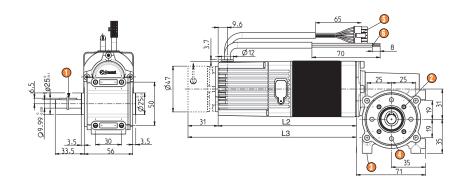
801897 - 802897 - SMi21 + P81 with or without brake



L1 1 stage: 70.5 ±0.6 L1 2 stages: 92.2 ±0.6 L1 3 stages: 113.8 ±0.6

- L2 80180 80280: 143 max. L3 80180 - 80280: 174 max.
- ① Parallel key 6 x 6 x 28 DIN 6885 A ② M6 x 16
- 3 4 x M6 at 90°, depth 12 over Ø 65
- O Command cable 12 x AWG26 / 500 mm
- 1 Power cable 2 x AWG16 / 500 mm

801410 - 801810 - 802810 - SMi21 + RAD10 with or without brake



L2 80140: 123 max.

L2 80180 - 80280: 143 max.

L3 80140: 154 max.

L3 80180 - 80280: 174 max.

#### Parallel key 4 x 4 x 20 DIN 6885 A

- 4 x M4, depth 8 over Ø 36
- 3 8 x M5, depth 8
- 4 x Ø 3.8, depth 10 over Ø 40
- Command cable 12 x AWG26 / 500 mm
- O Power cable 2 x AWG16 / 500 mm

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