



AHEAD OF WHAT'S POSSIBLE™

Connected Motion and Robotics: Systems, Platforms and Solutions for Industry 4.0

DARA O'SULLIVAN

ROGER YU

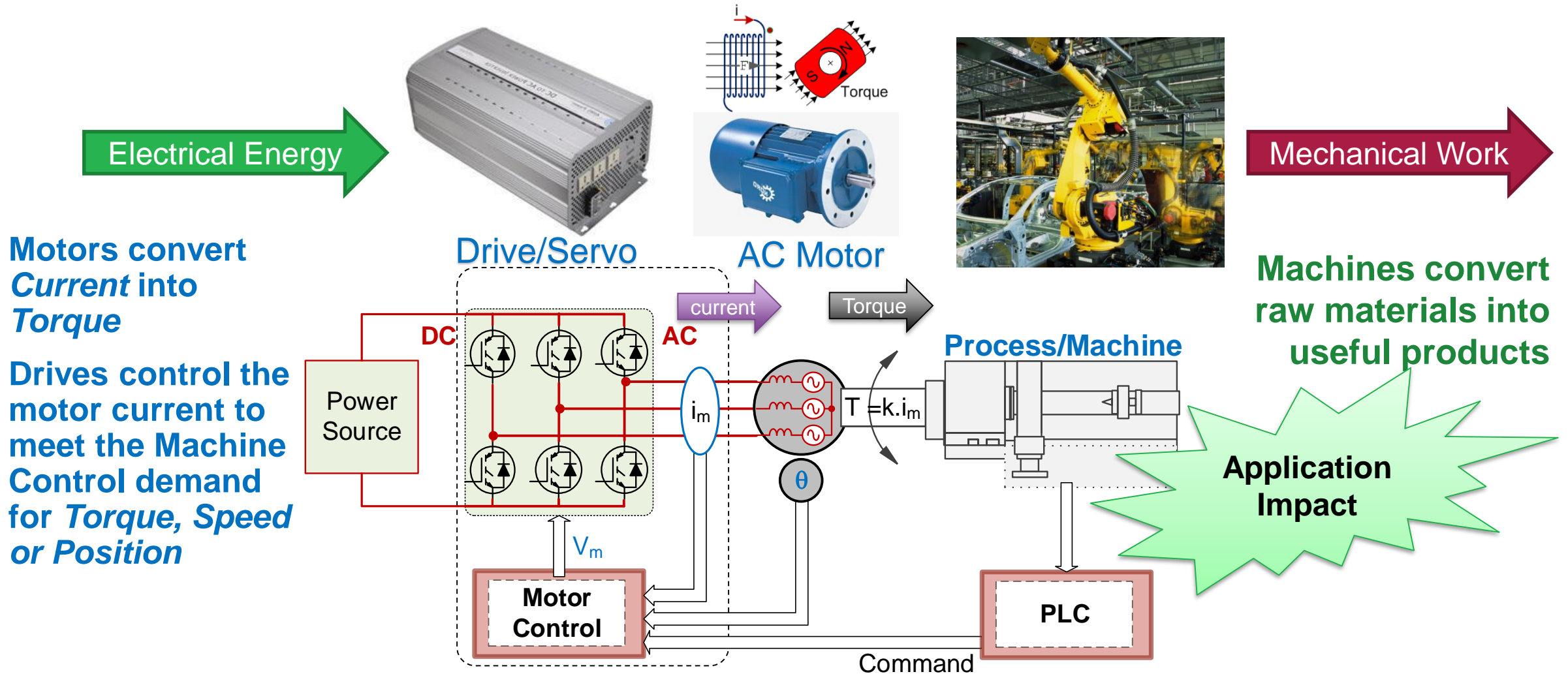
MOTOR CONTROL SHENZHEN CONFERENCE

NOV. 2019

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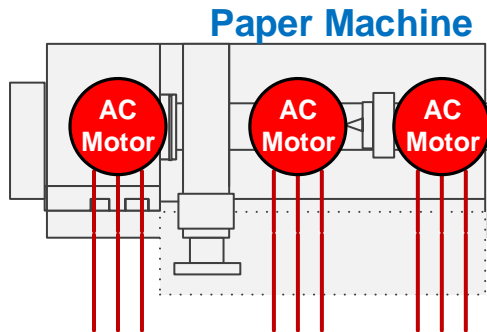


What is Motor Control?

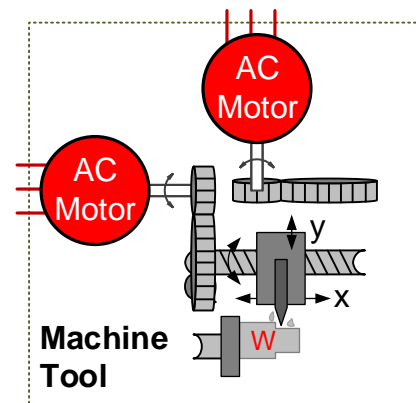


Multi-Axis *Synchronized* Motor Control

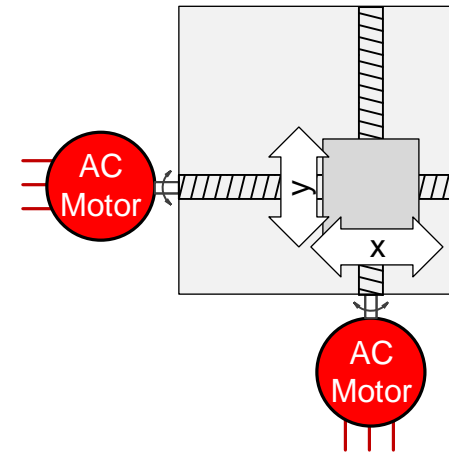
- ▶ Sheet or Wire Production (paper, steel, plastics, rope, cables etc.)
 - Synchronized speed of multiple rollers/drums.
 - Variable electronic gearing to maintain tension



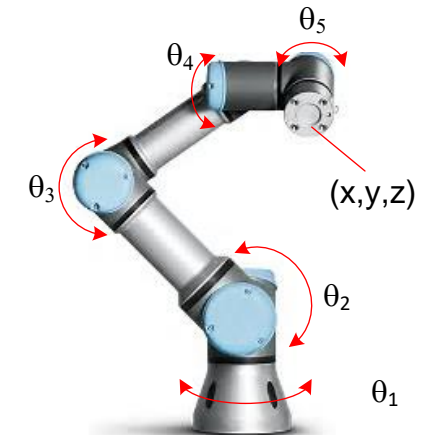
- ▶ Metal Processing (Turning, Milling, Grinding, Drilling)
 - Continuous motion of cutting tool relative to work piece
 - Synchronized control of tool position along multiple axes



- ▶ Electronic Assembly (Circuit boards/wire bonding)
 - Rapid motion of tool in Cartesian plane.
 - Precision control of tool (x,y) position and vertical force



- ▶ Automotive and general assembly (cars, consumer goods etc.)
 - Synchronized motion control of multiple axes
 - Flexible programming and fast response



Motor Drives and Servos in Industrial Automation

► Process Automation

- Oil and Gas; Mining; Cement; Chemicals; Steel; Paper; Food and Bev; HVAC etc.



Continuous Motion

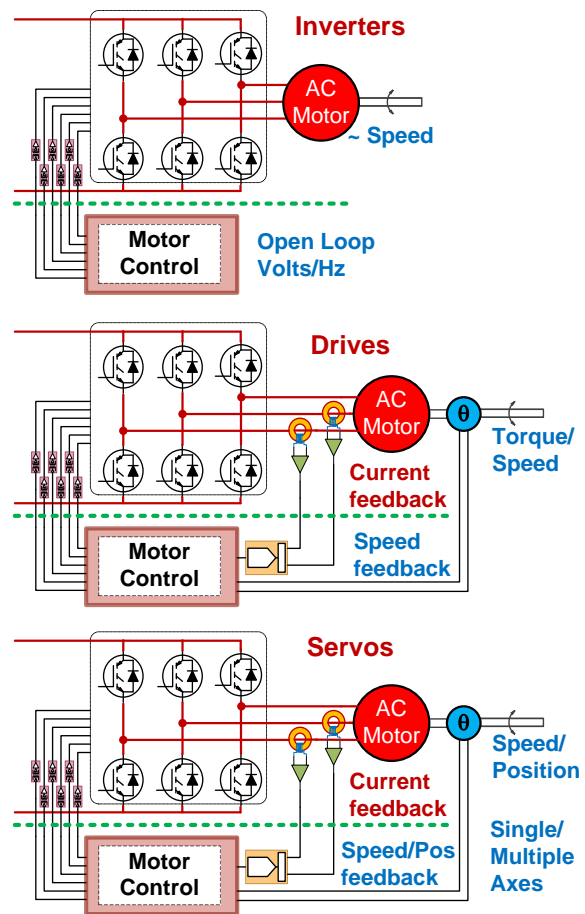
Assembly Automation

- Semiconductor; Automotive; Metal processing; Molding; Textiles; Packaging; etc.



Discontinuous Motion

► Motor Drive Types



- **Process Industry** focus on reducing **Energy consumption (\$\$)** by efficiently controlling fluid and material flow.

- Connectivity supports plant optimization.
- Acoustic noise and smooth operation in some applications

- **Assembly Industry** focus on **maximizing ROI** by increasing quality and throughput.

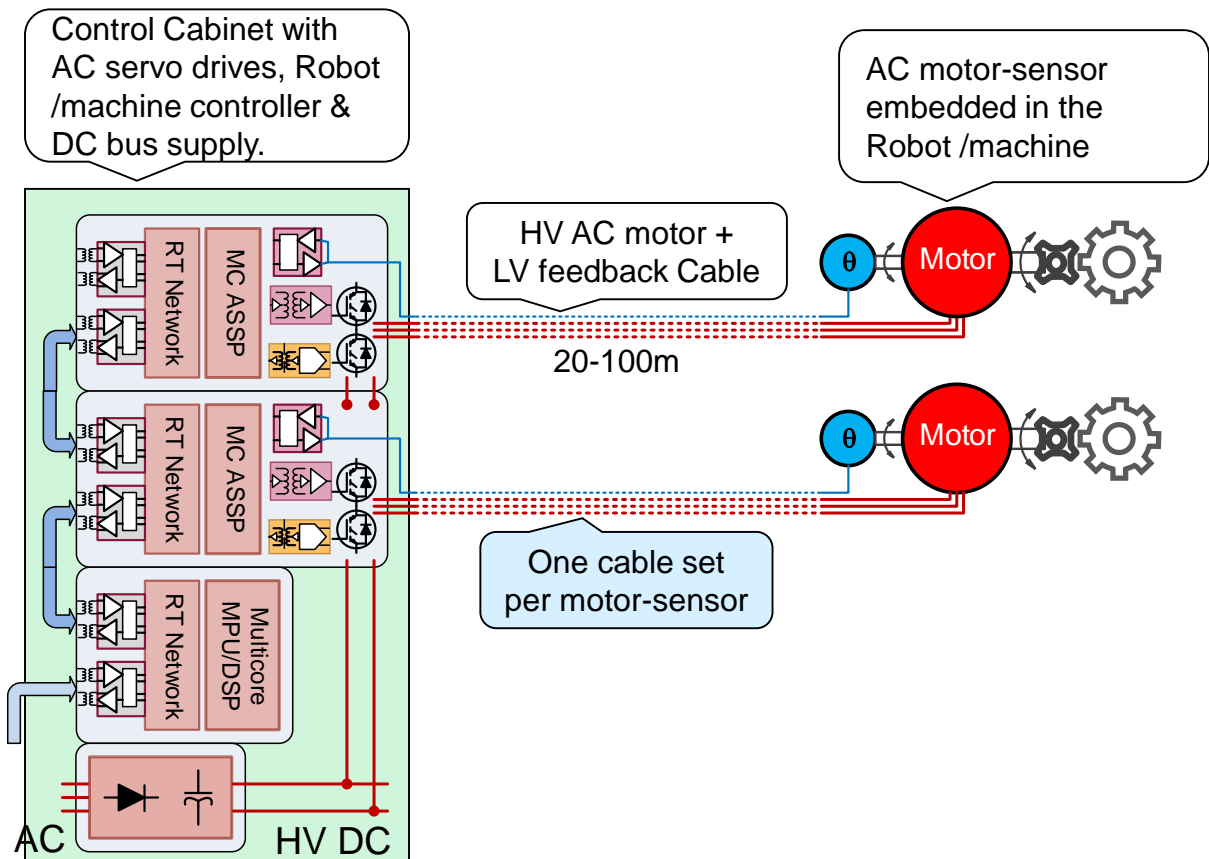
- Faster response and higher motion precision (in space & time)
 - Precise Machine synchronization
- Integrated safety functions for operational efficiency

► General trends

- Maximize plant uptime
- Minimize cabinet size
- Maximize product flexibility
- Minimize installation cost etc.

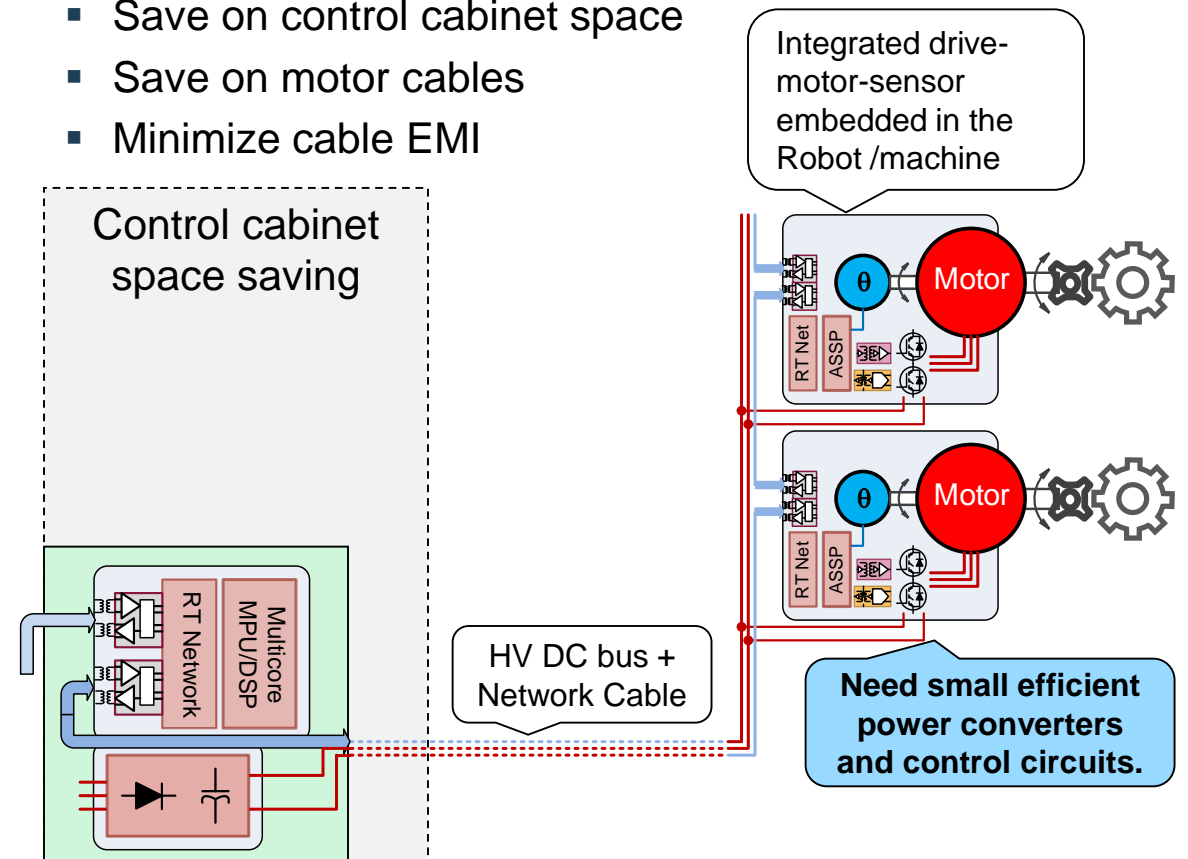
Architecture trend: Integration of drive and motor to simplify wiring.

▶ Traditional drive architecture



▶ Integrated Drive Motor (IDM)

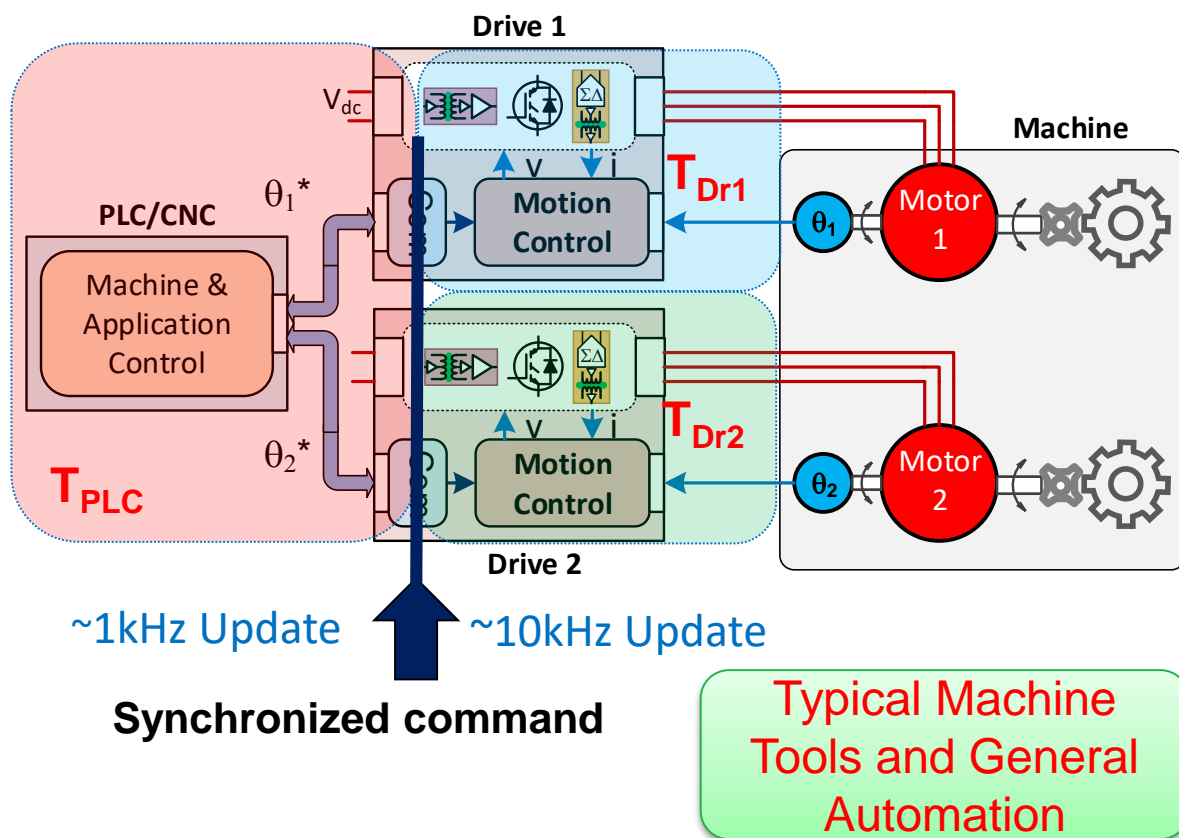
- Save on control cabinet space
- Save on motor cables
- Minimize cable EMI



Architecture Trend: Reference- vs. I/O Synchronization

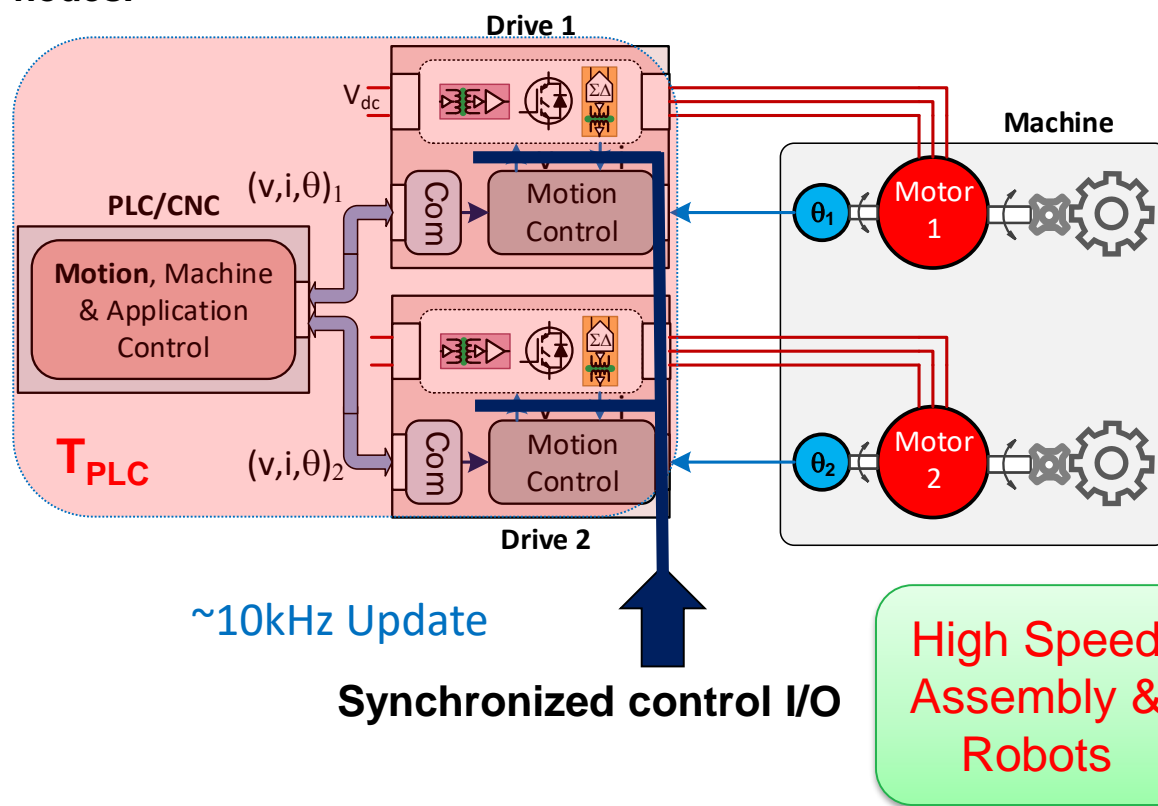
Deterministic Ethernet with synchronized commands only

Independent processing and clock domains



Deterministic Ethernet with synchronized I/O

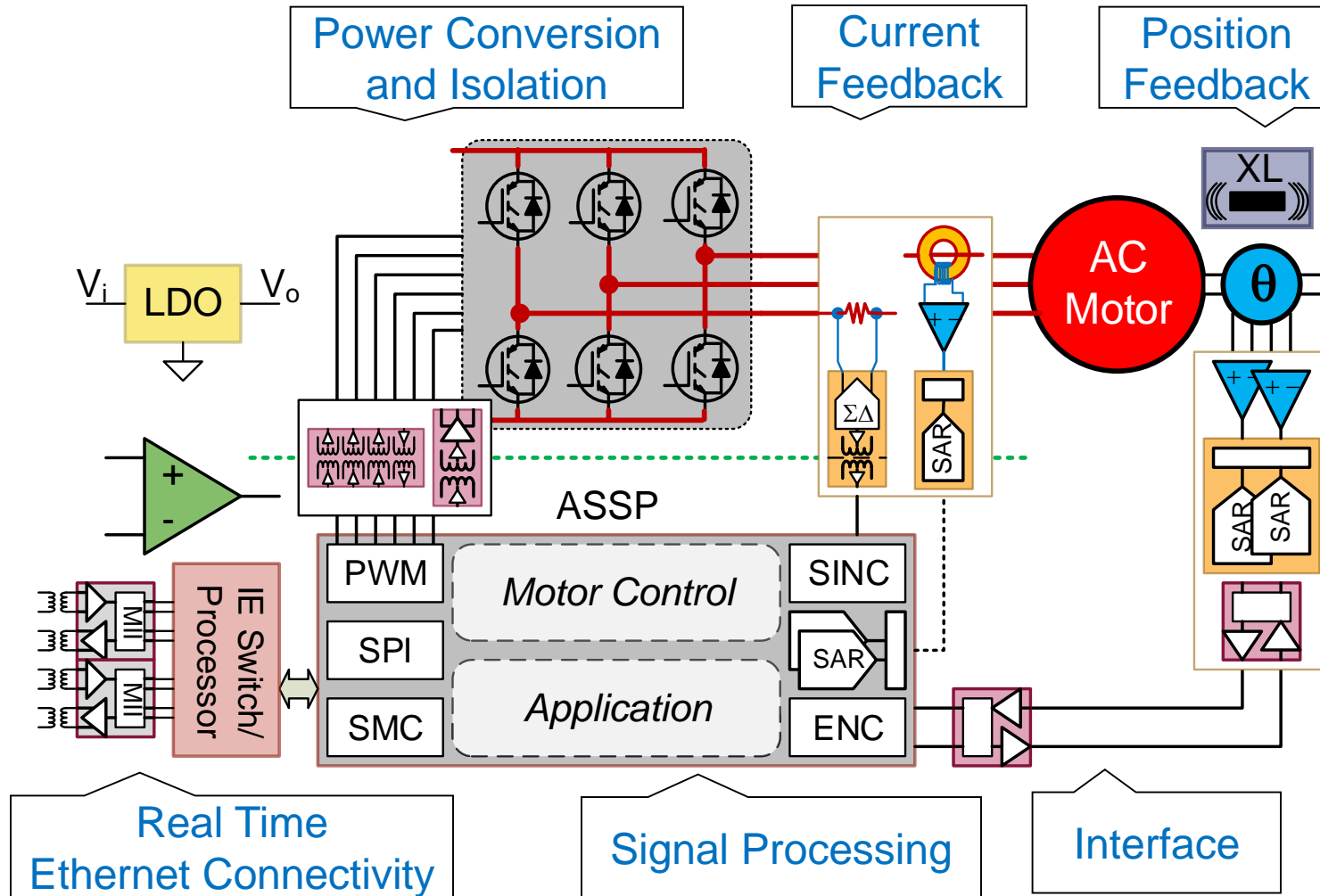
Common clock domain. Scalable processing within PLC or drive nodes.



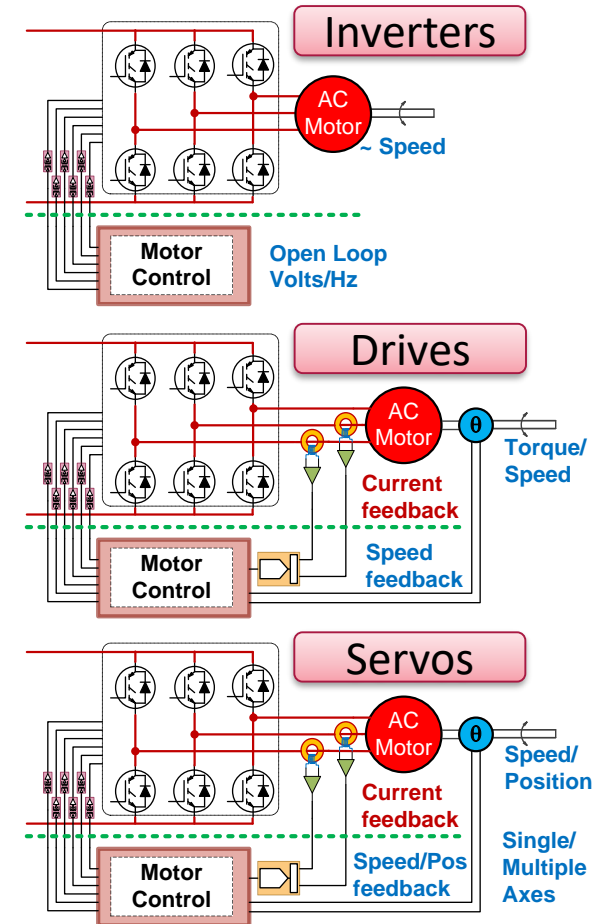


ADI Solutions for the CMR Market

Drives and Servos Signal Chain



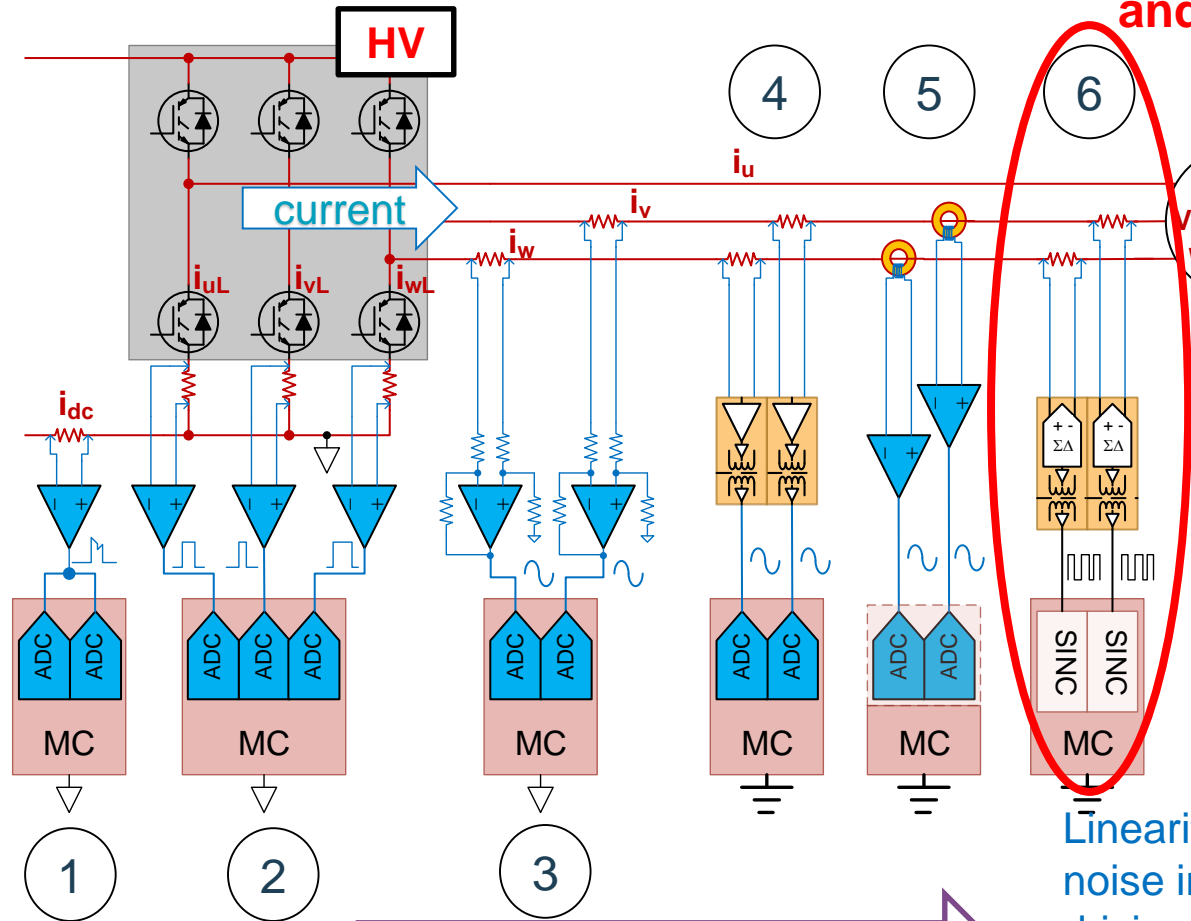
► Motor Drive Types



Isolated and non Isolated Current Feedback Architectures

Non isolated current feedback:

1. dc link shunt
2. inverter leg shunts
3. HV current diff amps

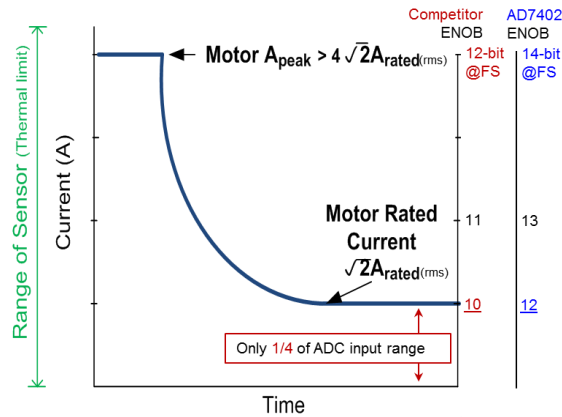


Current feedback for Torque control and inverter switch protection

- ### Isolated current feedback:
4. Current shunt with isolation amplifier
 5. Isolating magnetic current sensor
 6. Current shunt with isolating sigma delta modulator

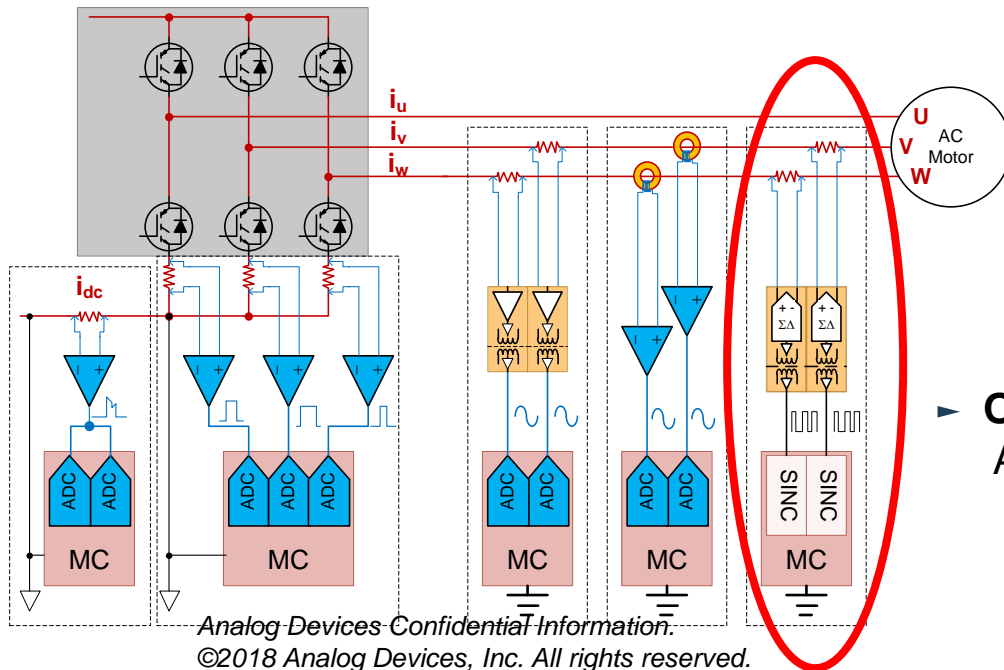
Linearity, gain match, offset [esp.drift] and noise immunity are critical parameters driving Torque quality

Feedback Signal Scaling requires Dynamic Range



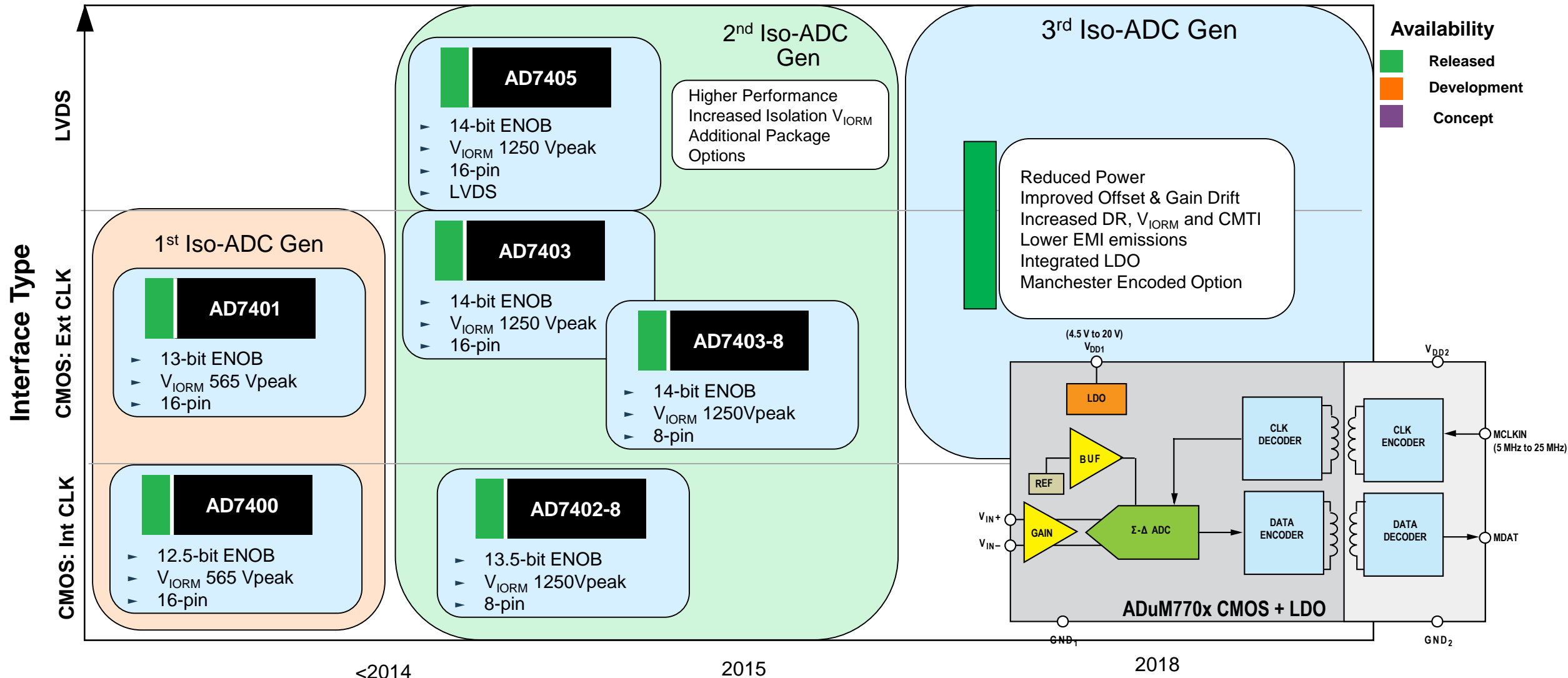
- ▶ Significant trend towards Shunt current measurement vs. CT/Hall.
 - **Dynamic range** required to measure both Peak and Nominal currents. Rated currents may be fraction of ADC dynamic range.
 - Same drive services range of motor sizes. Dynamic range lost in lowest rated motor.
- ▶ Demand for lower shunt values requires even higher DR. $\sim \pm 250\text{mV} \rightarrow \pm 50\text{mV}$

- Thermal losses
- Power transfer efficiency
- Integration densities
- Self heating effects and solder joint stress
- Desire to extend power rating of shunt based systems, further reducing CT usage.



- ▶ **Offset Drift** and **Gain Drift** contribute directly to torque ripple on the motor shaft. Affects many applications, surface effect on milling/etching; vibration effects etc.

Isolated $\Sigma\Delta$ Modulator Roadmap



<2014

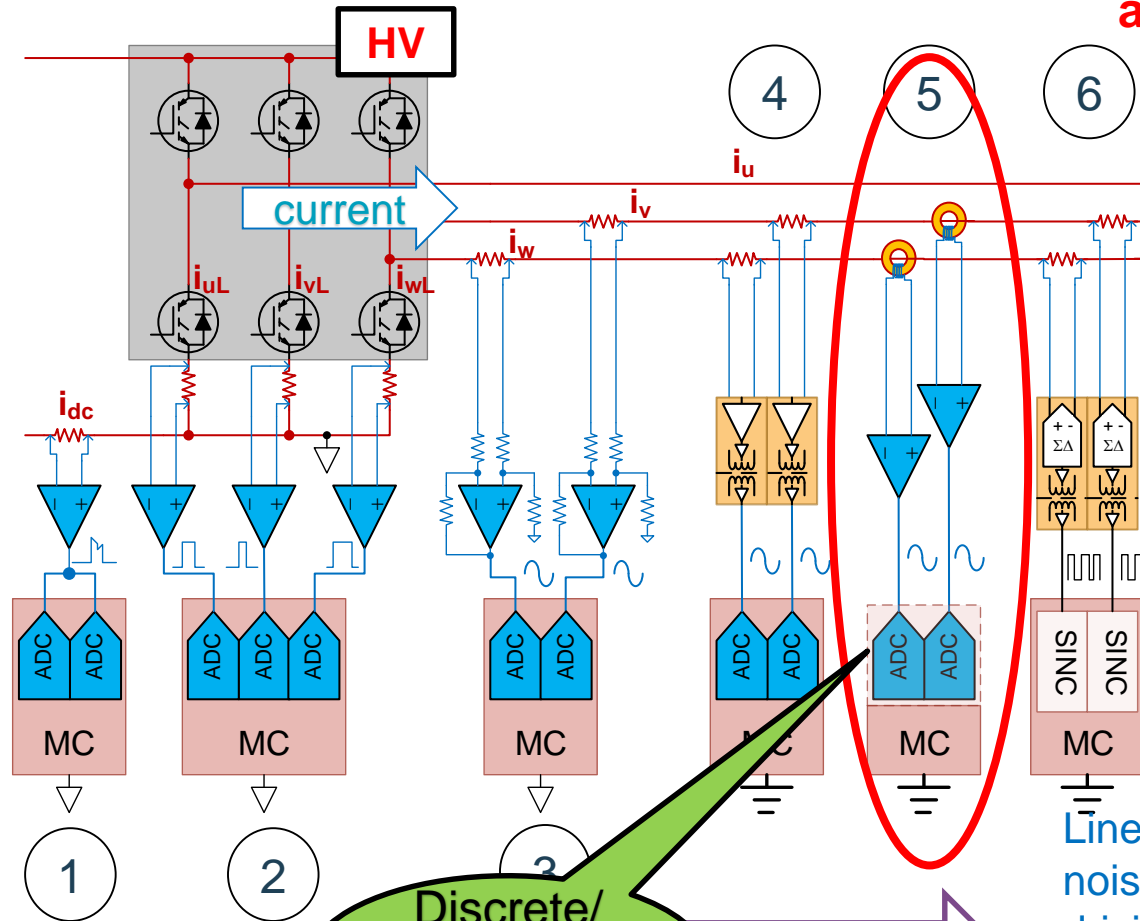
2015

2018

Isolated and non Isolated Current Feedback Architectures

Non isolated current feedback:

1. dc link shunt
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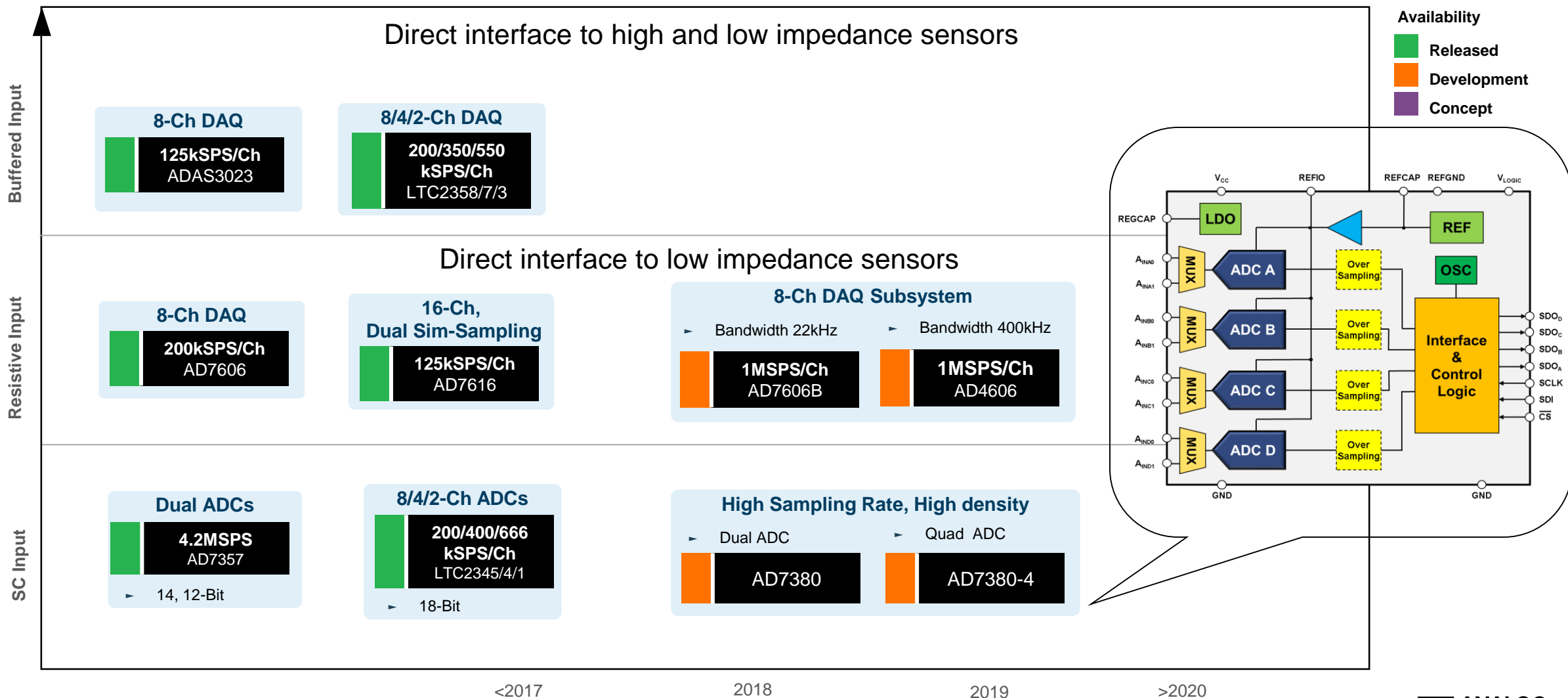
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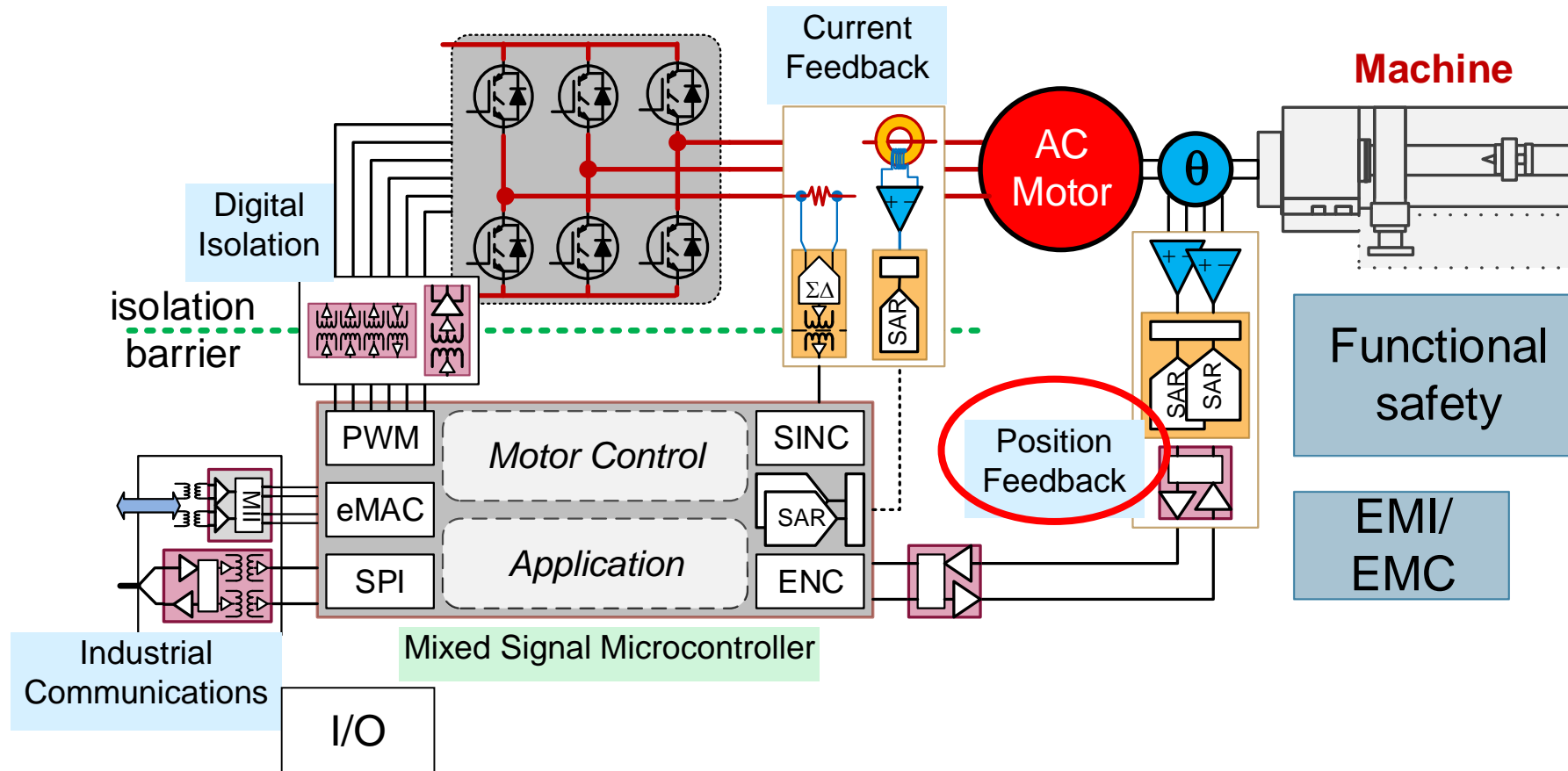
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Discrete/Embedded ADC

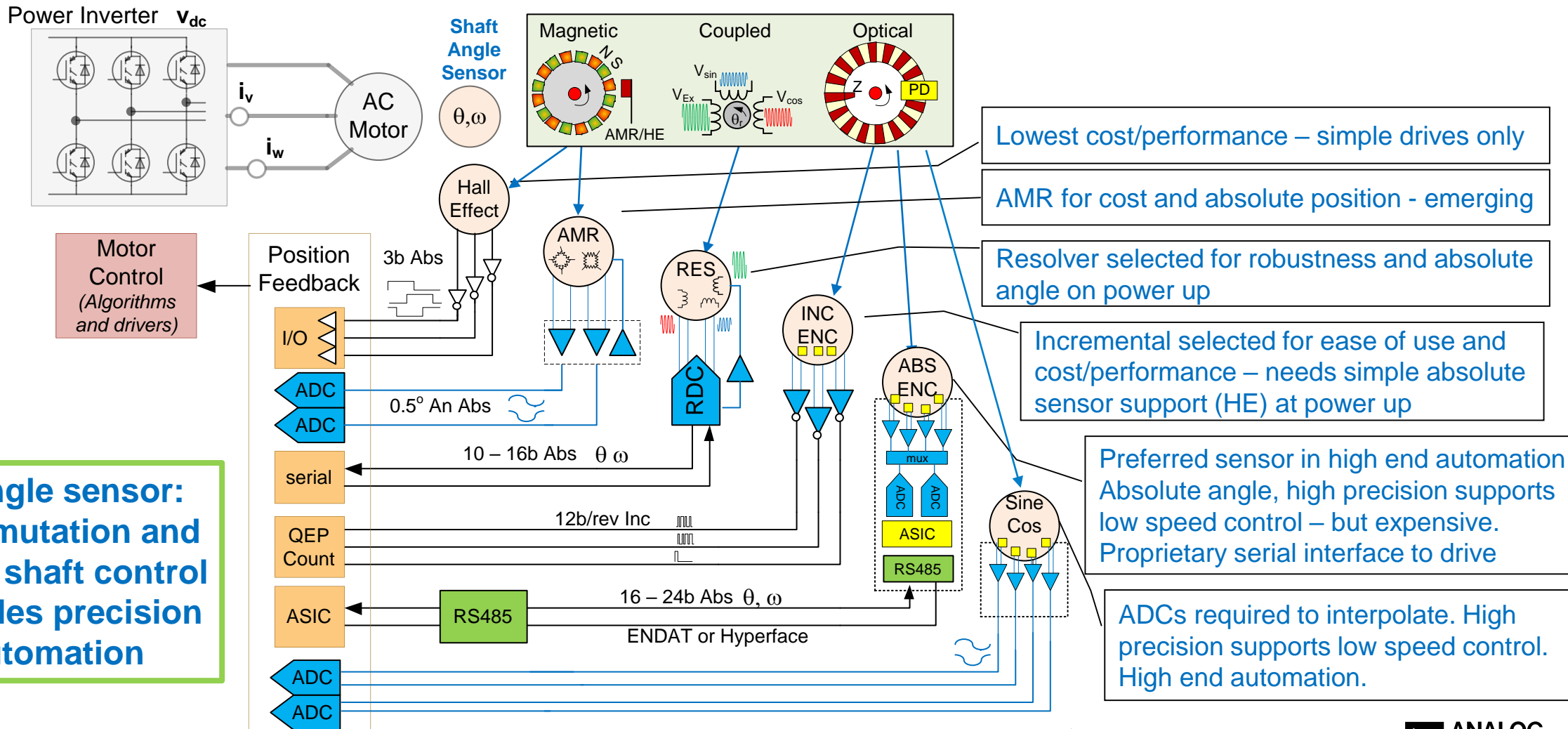
Simultaneous Sampling, SAR ADC Roadmap (18 to 12-Bits)



Motion Control High Level Signal Chain



Position Feedback Architectures and sensors



Lowest cost/performance – simple drives only

AMR for cost and absolute position - emerging

Resolver selected for robustness and absolute angle on power up

Incremental selected for ease of use and cost/performance – needs simple absolute sensor support (HE) at power up

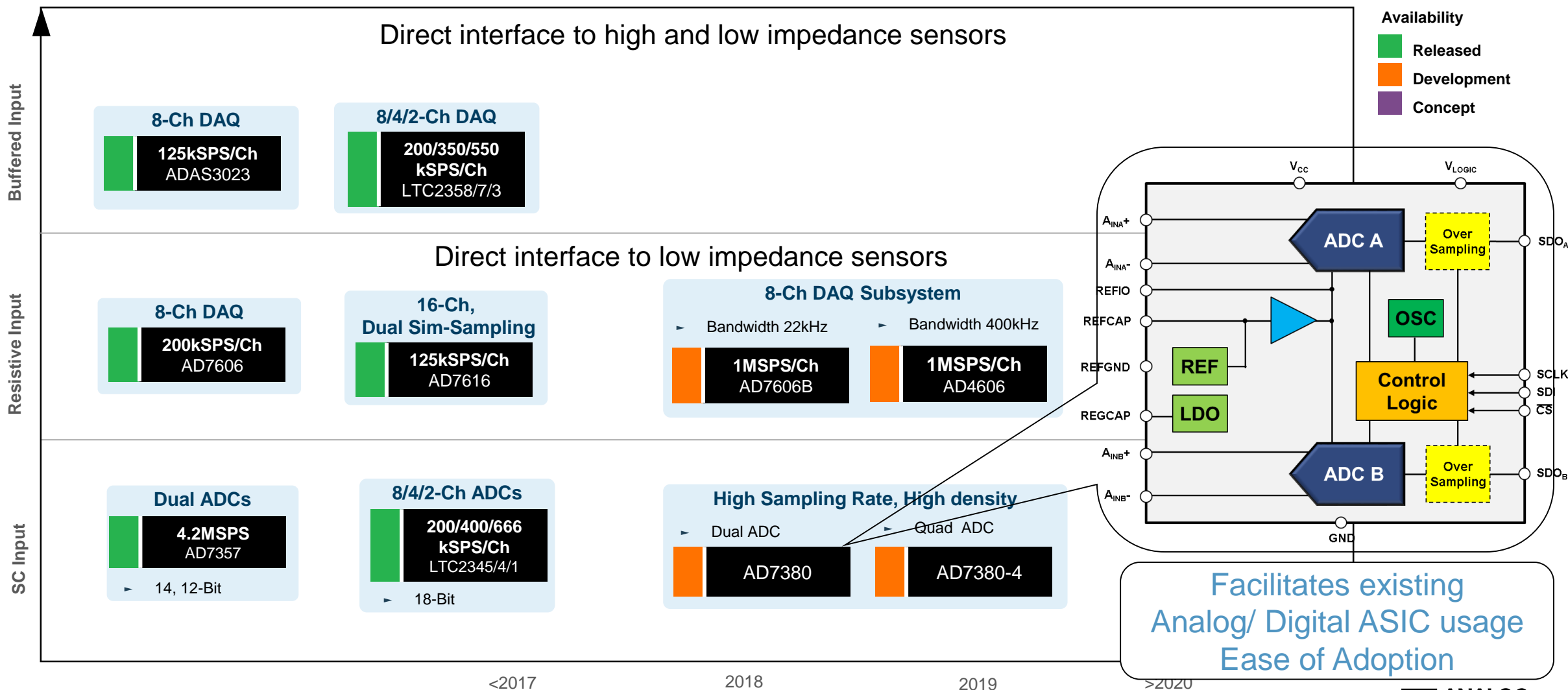
Preferred sensor in high end automation Absolute angle, high precision supports low speed control – but expensive. Proprietary serial interface to drive

ADCs required to interpolate. High precision supports low speed control. High end automation.

Shaft angle sensor:

- **Commutation and drive shaft control**
- **Enables precision in automation**

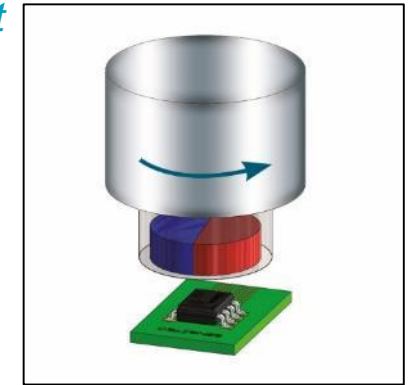
Simultaneous Sampling, SAR ADC Roadmap (18 to 12-Bits)



xMR Sensors for Position Feedback

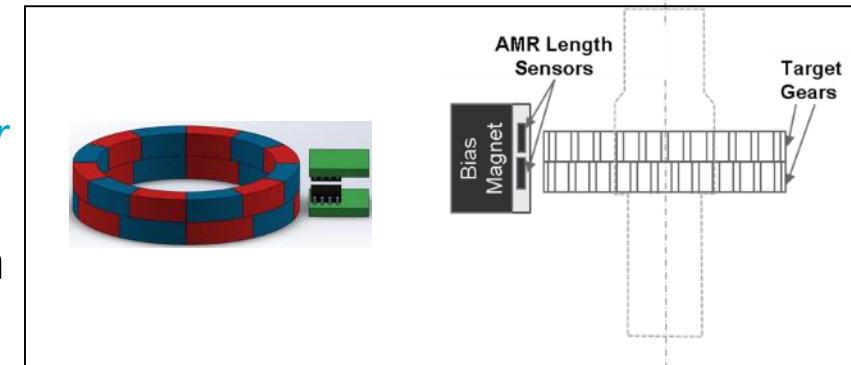
- ▶ AMR with 180° absolute position is a released product (ADA4571)
- ▶ GMR and TMR (both 360° absolute) are being qualified and sampled
 - 0.1°-0.5° accuracy
- ▶ AMR off-shaft length sensor for industrial applications
- ▶ Accuracies of 0.05° and lower achievable -> mechanical construction tolerance
 - Different measurement principle to standard AMR
- ▶ Zero power multiturn sensor

End of shaft

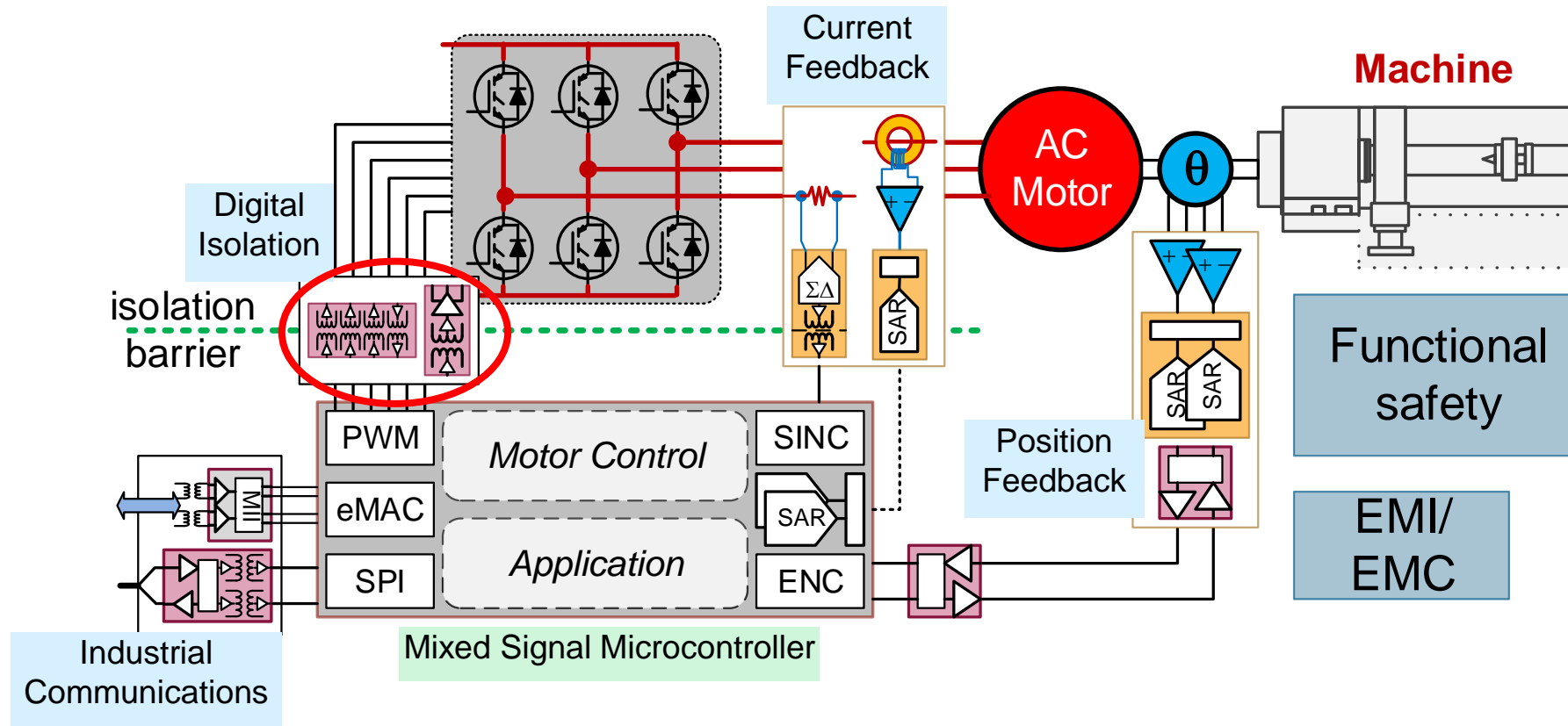


Off-shaft length sensor

- ▶ Potential fit for mid-precision machines, collaborative robots, high speed machines such as spindles
 - Robust, high speed, 10-14bit precision
 - Zero power multi-turn for shutdown position awareness
 - Will customers be willing to design and integrate position sensing?

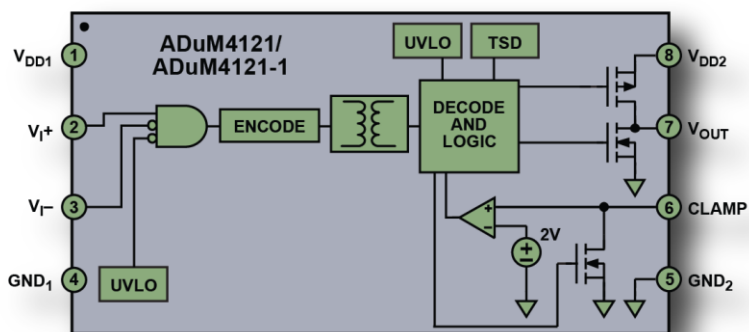


Motion Control High Level Signal Chain



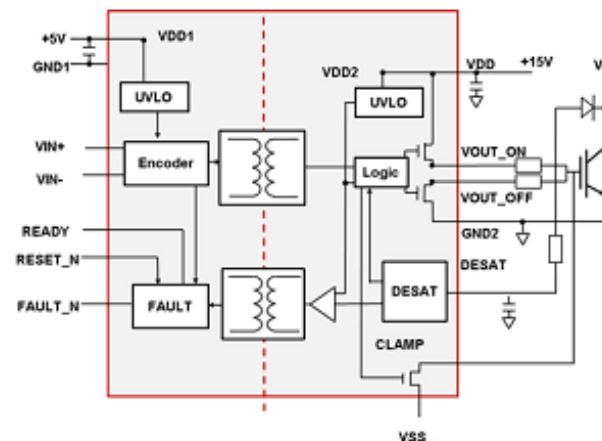
Isolated Gate Driver for Industrial Motor drives

- ▶ Basic Gate Drivers (ADuM4120/4121)
 - Support the most common industrial working voltage and power range (400V <50kW)
 - Miller clamp to prevent spurious turn on
 - 5 kV isolation, working voltage 600 V rms
 - 6 and 8 pin version with 8 mm creepage
 - Very suited to driving new & faster GaN/SiC switches
 - CMTI: 150 kV/μs
 - Prop delay 38 ns typical, prop delay skew <15 ns



- Roadmap
 - Slew rate selection to manage EMI/efficiency trade-off
 - Insulation and packages for 690V and higher power
 - Integrated Gate drive supply for GaN switches

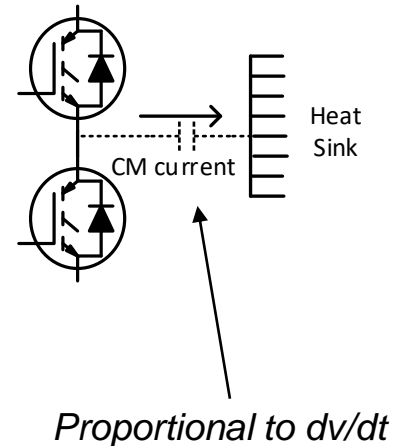
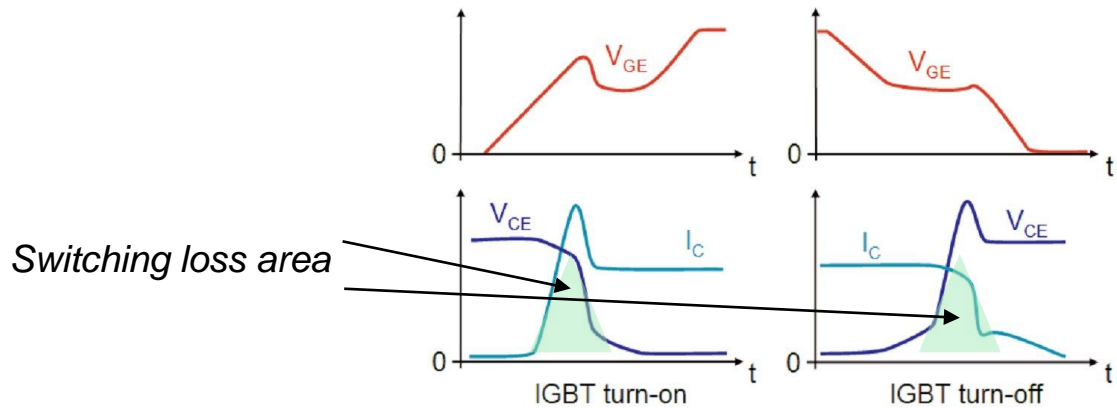
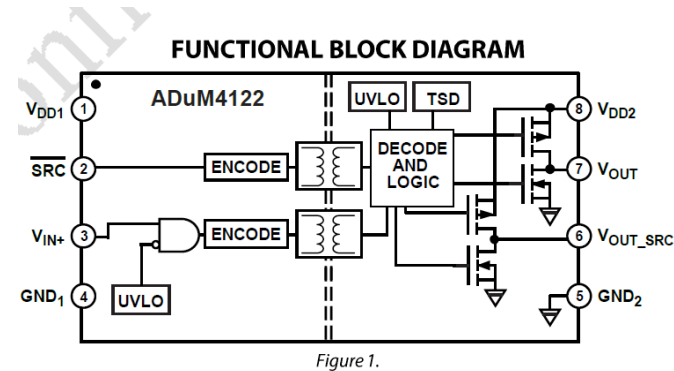
- ▶ Advanced Gate drivers (ADuM4135/4136)
 - Support the most common industrial working voltage and higher power range (<100kW)
 - Also very suited to driving new & faster GaN/SiC switches
 - Includes embedded SC protection and other features
 - DESAT function detects short circuit fault without current measurement
 - Fault reporting and reset pins



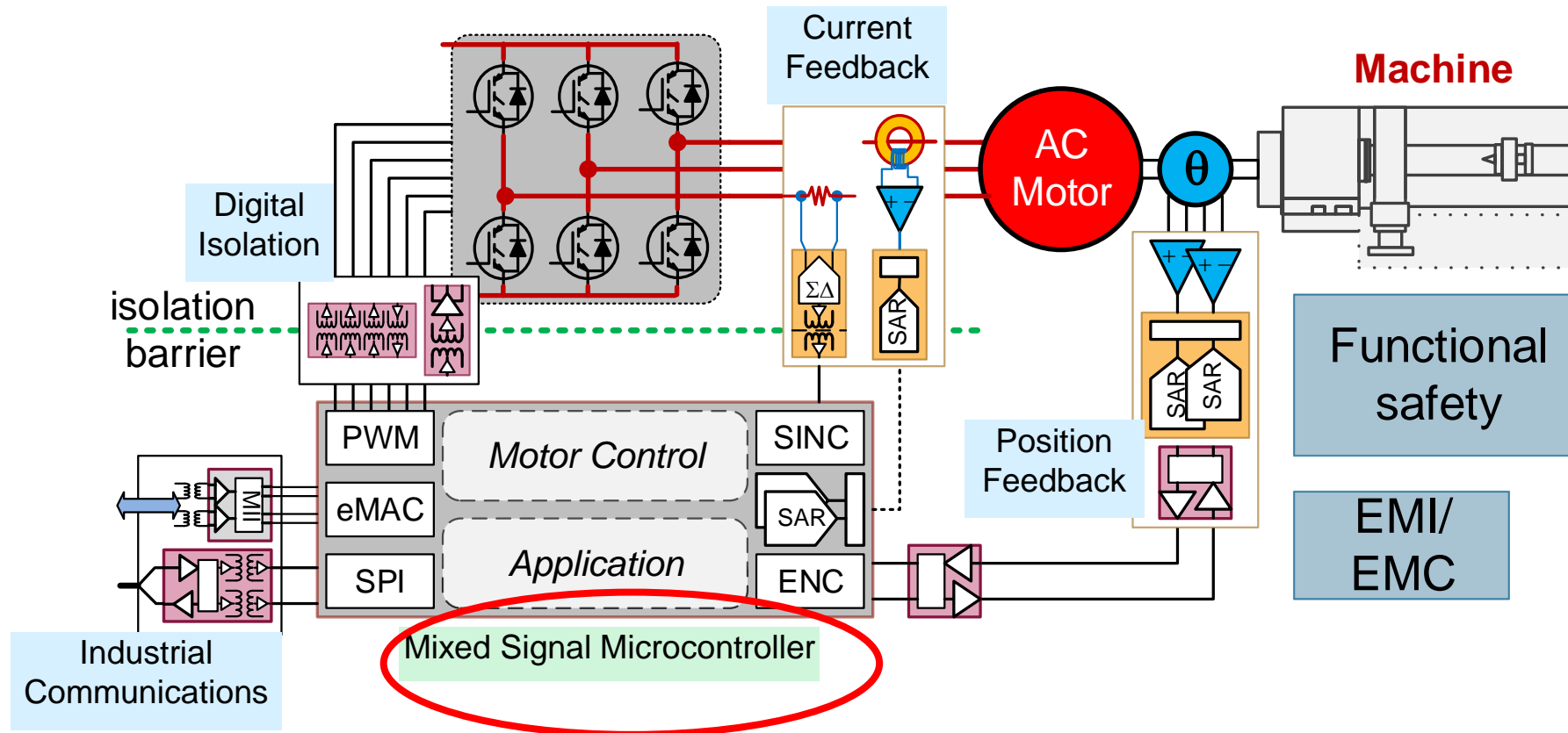
- Roadmap
 - Over temperature monitor of the power switch
 - Flyback controller for gate drive power supply
 - Full gate power supply integration for IGBT/SiC
 - Fast short circuit fault detection for GaN/SiC
 - Programmable slew rate

Slew Rate Controlled Gate Drive

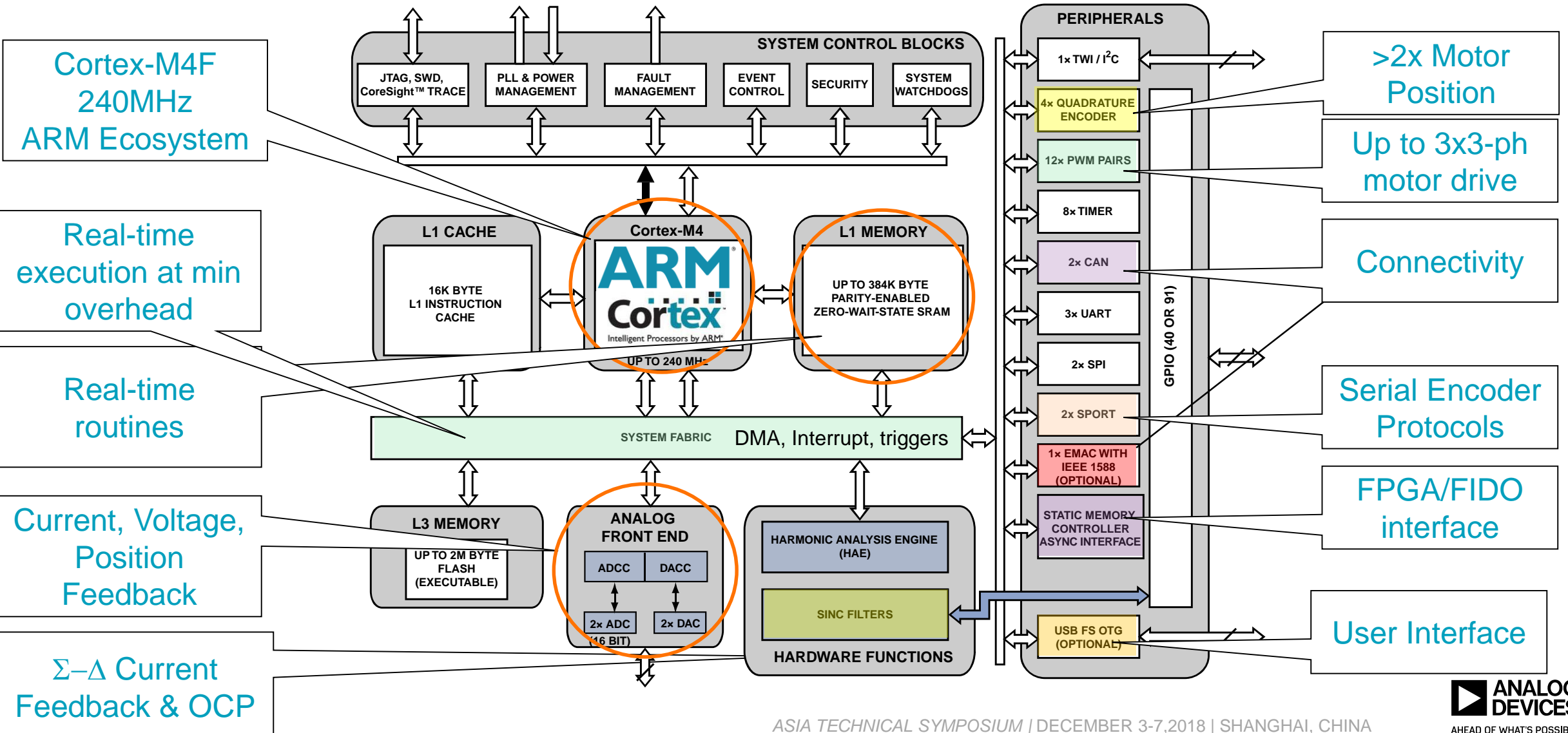
- ▶ Some customers looking to use faster IGBTs in new designs
 - Faster switching transitions -> reduced switching loss -> **smaller heat sink size**
 - Faster switching transitions -> increased EMI problems -> **larger EMI filter**
- ▶ EMI worst-case is at light load/motor standstill
- ▶ Lower Gate Drive Impedance **minimises losses**
- ▶ Higher Gate Drive Impedance **slows the switching transitions reducing emissions**



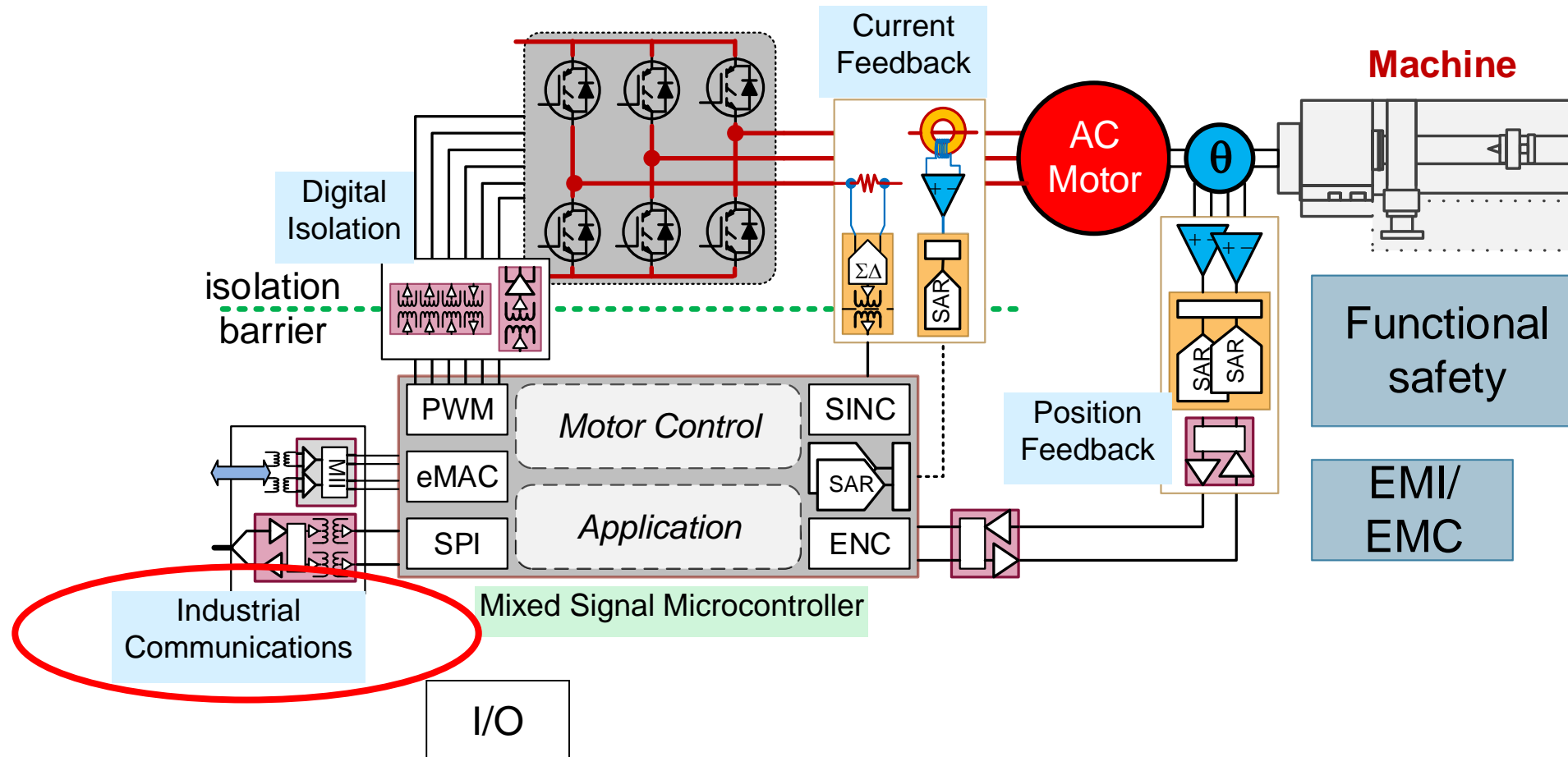
Motion Control High Level Signal Chain



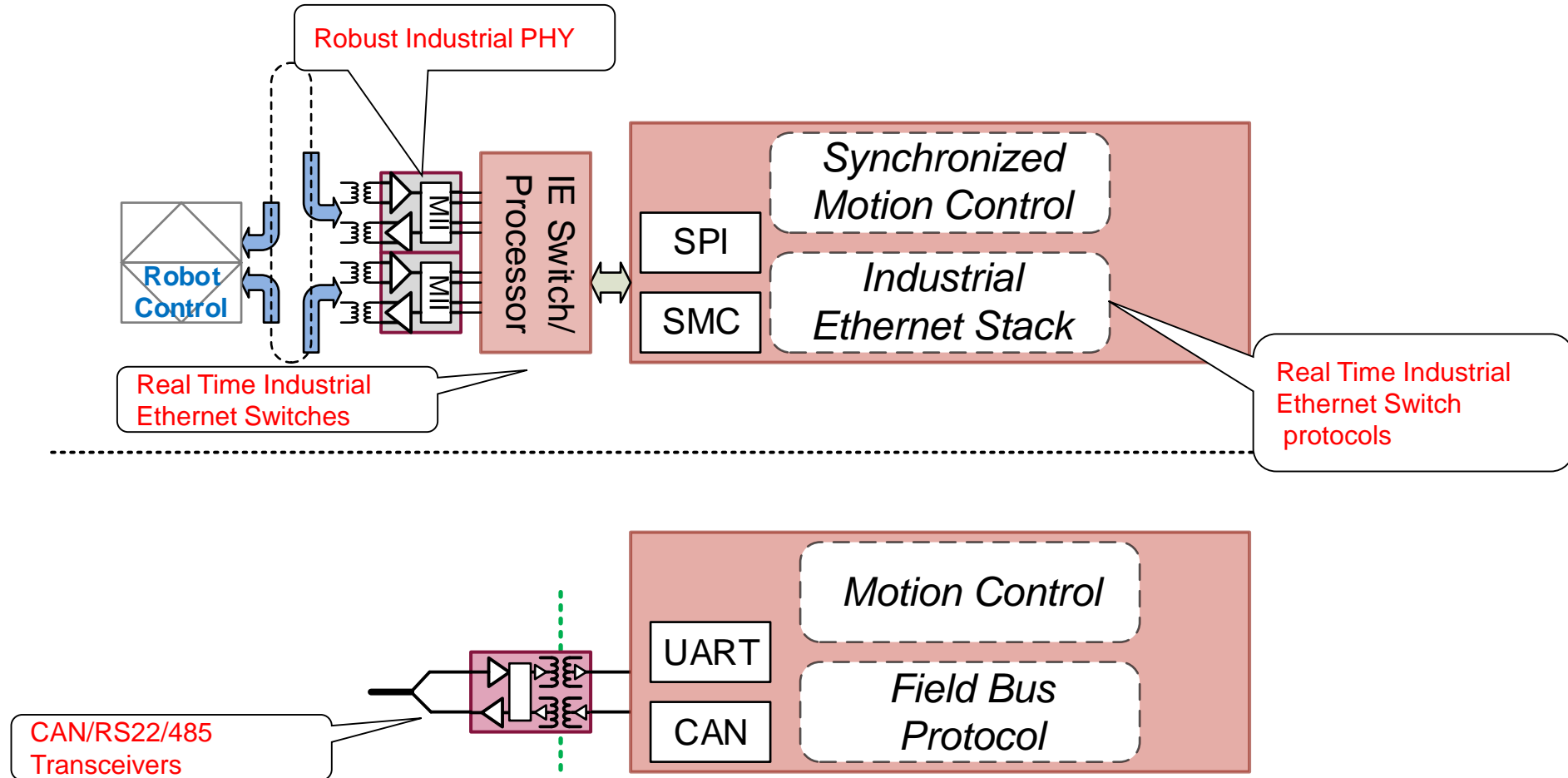
ADSP-CM40x Overview: 'Slater'



Motion Control High Level Signal Chain

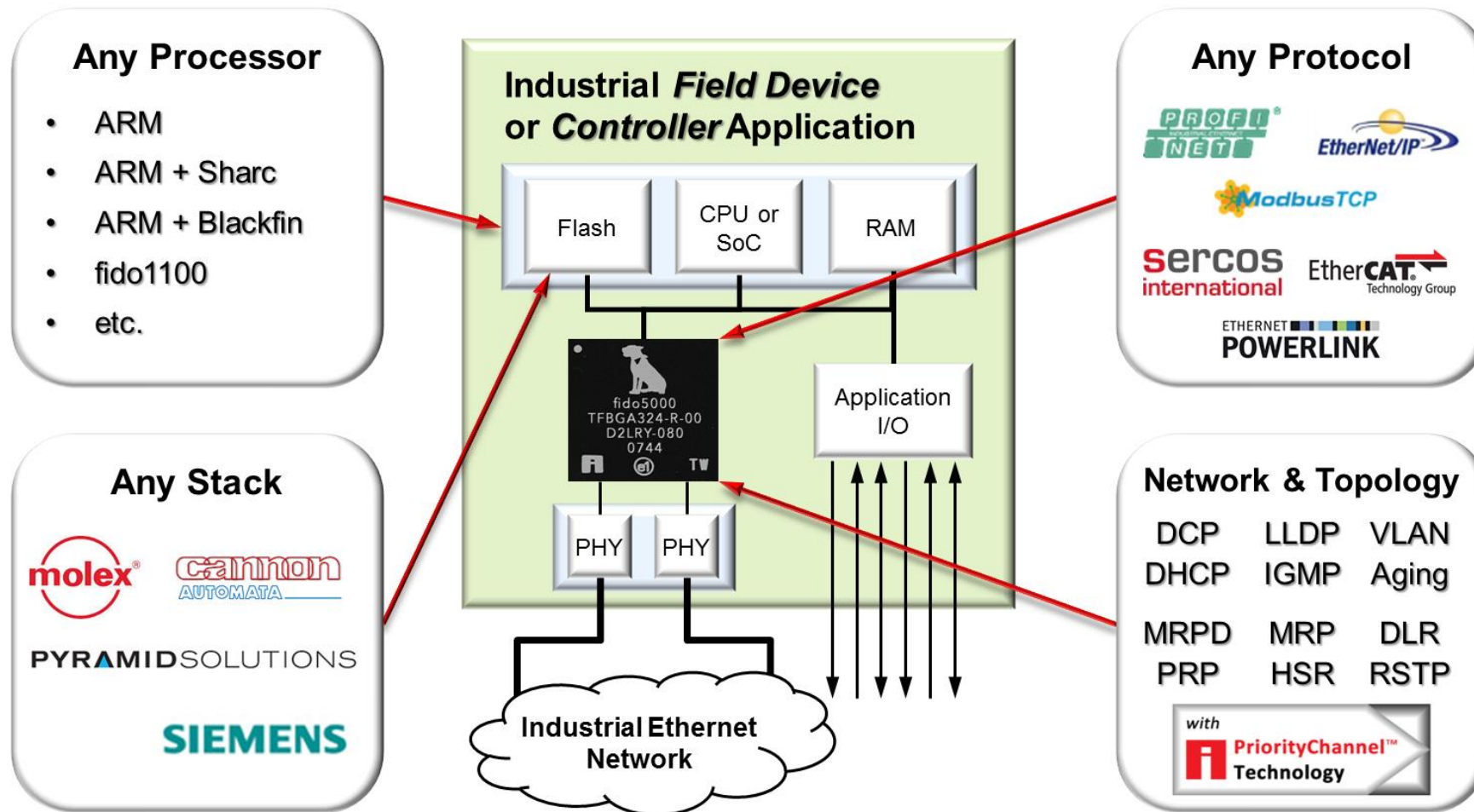


Industrial Communications

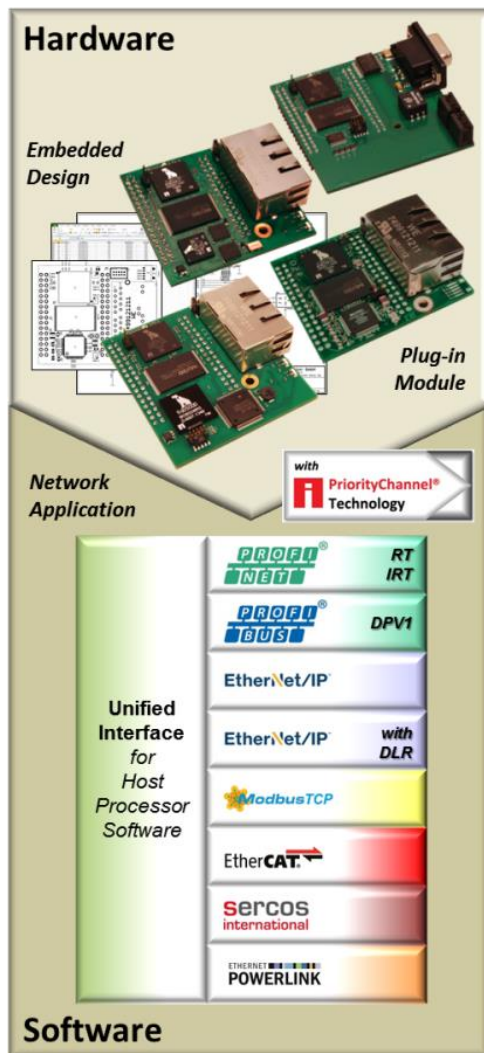


FIDO5000 REM Switch

Multiprotocol Real-Time Ethernet Switch Chip



Easy Evaluation with Complete Service and Support



The RapID Platform is a pre-tested Industrial Ethernet Network Interface Card that processes the industrial protocol and network traffic

- Unique architecture with Innovasic's PriorityChannel® technology eliminates the effects of network traffic
- Available as a card that plugs into your PCB or as schematics to integrate circuit/chips into your PCB
- Common hardware interface supports all protocols
- Common software interface supports all protocols
- No licensing fees or royalties
- Guaranteed first-pass certification

**Next Generation
RapID platform
release: ~Q2 2019**

ADIN1200 / ADIN1300 Robust, Industrial, Low Latency, Low Power Ethernet PHY

- ▶ ADIN1300 10/100/1000 Gigabit PHY
 - Robust Temperature Range: -40 to 105C
 - Robust EMI / EMC / ESD performance
 - Small Footprint: 6x6mm 40-LFCSP
 - Low Power: 365mW
 - Low Latency: 290ns Tx & Rx (RGMII)
- ▶ ADIN1200 10/100 Fast Ethernet PHY
 - Robust Temperature Range: -40 to 105C
 - Robust EMI / EMC / ESD performance
 - Small Footprint: 5x5mm 32-LFCSP
 - Low Power : 175mW
 - Low Latency : 300ns Tx & Rx (MII)

Generic	Package	Temp Range
ADIN1300	40 Lead LFCSP	-40C to 105C
	40 Lead LFCSP	-40C to 85C
ADIN1301	64 Lead LGA	-40C to 105C
	64 Lead LGA	-40C to 85C
ADIN1200	32 Lead LFCSP	-40C to 105C
	32 Lead LFCSP	-40C to 85C

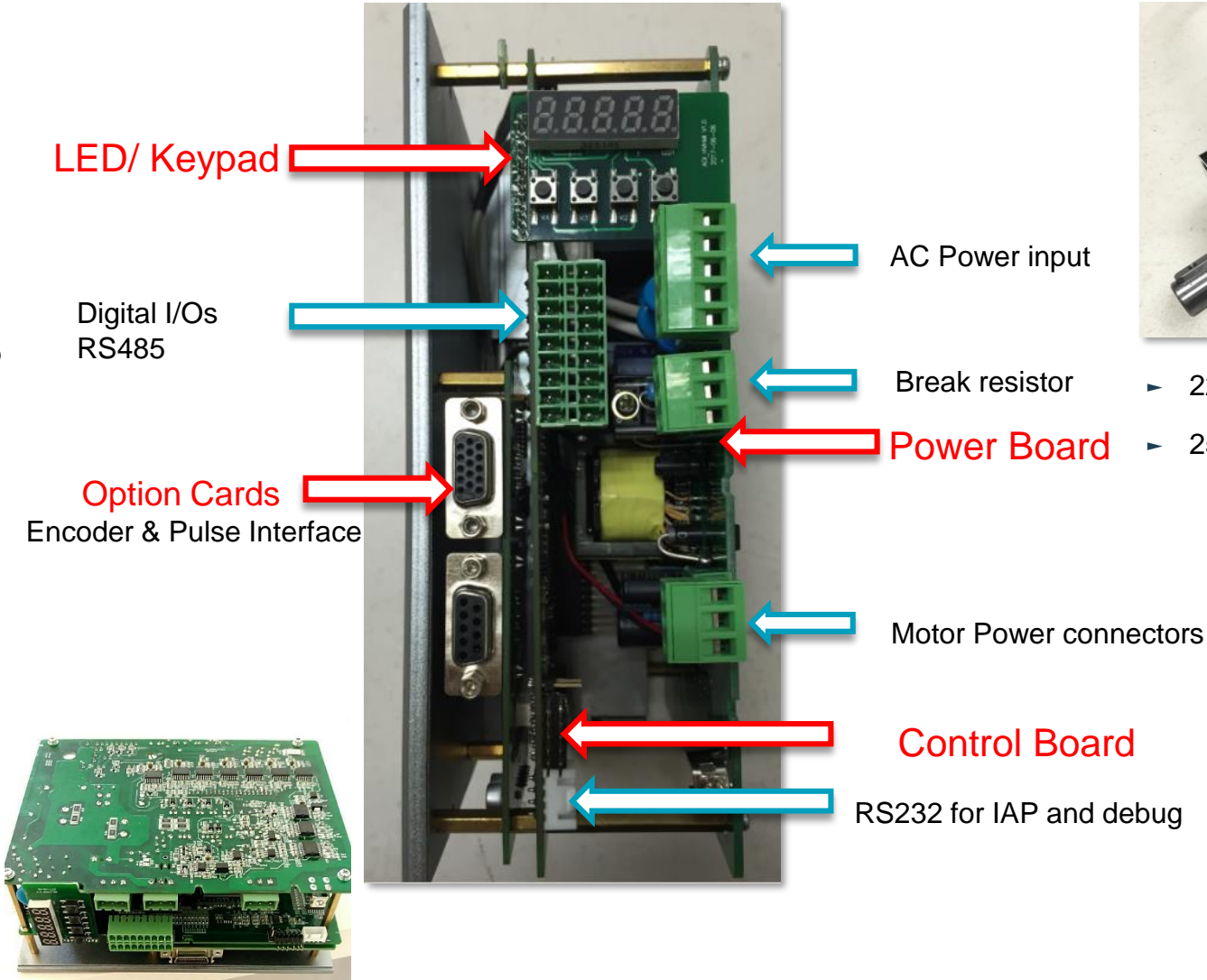
- ▶ PHY Samples
 - ADIN1300 Dec 2018
 - ADIN1200 Jan 2019
- ▶ PHY Production Release
 - ADIN1300 Dec 2019
 - ADIN1200 Jan 2020.

System Solutions

220V 1kW AC Servo ADP with Option Cards

also supports general motor drive development (IM, BLDC)

- ▶ **System demonstrations**
 - To show what key ADI devices can be used in a motor drive
 - To show basic capabilities of ADI motor control solutions
- ▶ **Key parts' evaluation**
 - Evaluation in a system environment that is most similar to typical drive products
 - ADI sigma delta ADC performance
 - ADI isolation technologies
 - ADI gate driver
- ▶ **Flexible extensions**
 - Generic interface to new functionalities in motor drive systems
- ▶ **Software development**
 - A HW platform that can run almost all motor control related software



- ▶ 220V/400W PMSM
- ▶ 2500 line incremental encoder



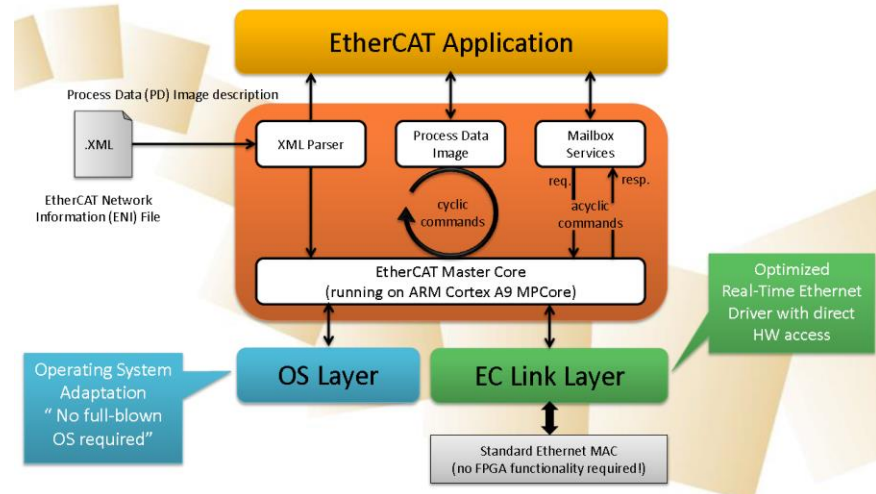
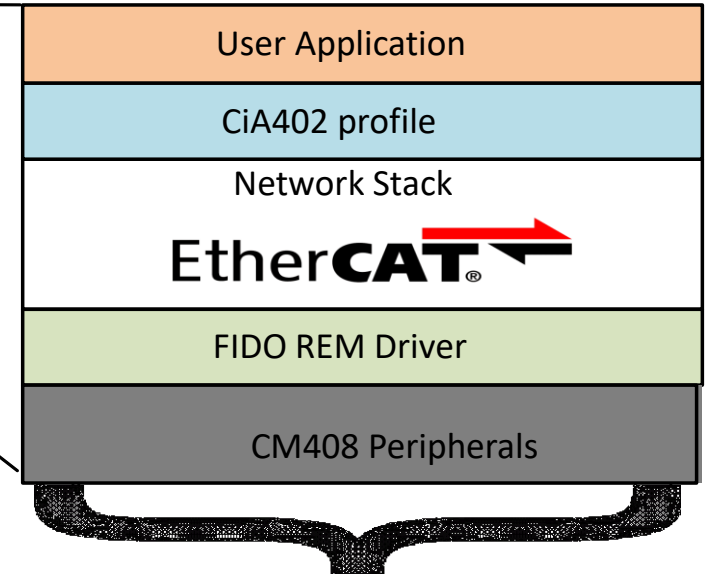
- ▶ 220V induction motor

Bare Metal Ethercat Slave Solution

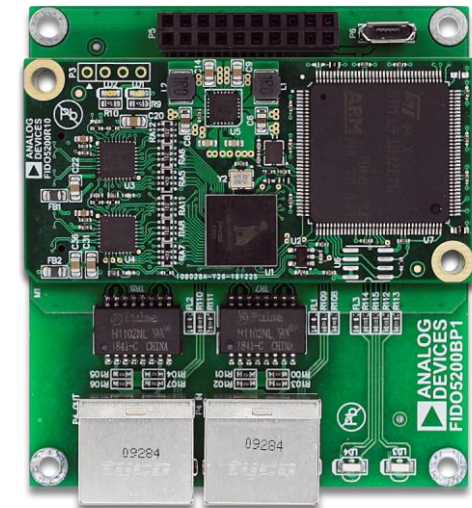
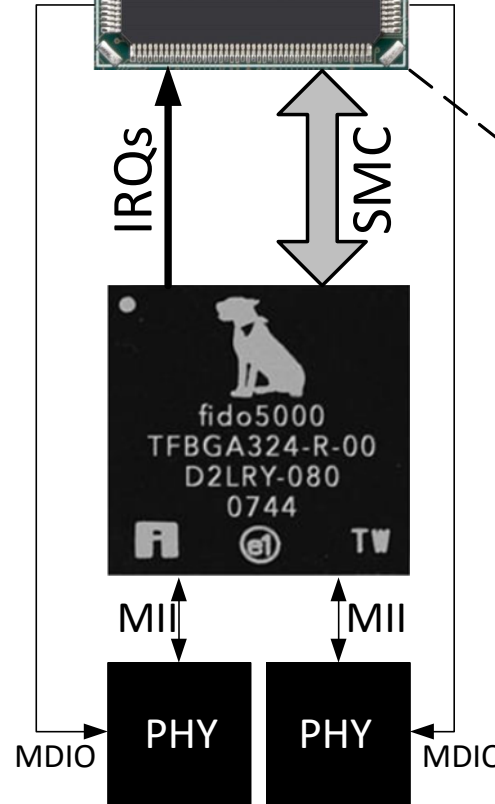


TwinCAT

EtherCAT



ARM9 Core



Thank you!

