

PD86-1180

86mm / NEMA34 Stepper Motor with Controller / Driver, Encoder and Serial Interface Optional CANopen

| | MAIN CHARACTERISTICS |
|--------------------|---|
| ELECTRICAL DATA | \cdot 24 to 48V DC (nom.) supply voltage |
| MOTOR DATA | flange size 86mm/NEMA34 |
| | holding torque 7.0 Nm |
| INTERFACE | · CAN, USB, RS232, RS485 |
| | step&direction interface |
| | inputs for ref. & stop switches |
| | • general purpose I/Os |
| | • encoder interface (ABN) |
| FEATURES | stallGuardz[™] sensorless high resolution load detection |

- coolStep[™] sensorless load dependent current control
- up to 256 times microstepping
- microPlyer™ 16 to 256 times microstepping interpolation
- memory for 2048 TMCL commands
- motion profile calculation in hardware (RT)
- on the fly alteration of motion parameters (e.g. position, velocity, acceleration)
- software stand-alone operation using TMCL™ or remote controlled operation
 - PC-based application development software TMCL-IDE included
 - optional CANopen firmware (CiA 302, 402)
 - $_{\text{OTHER}}$ $\,$ \cdot pluggable JST connectors
 - RoHS compliant

| ORDER CODE | DESCRIPTION | | |
|-----------------------|---|--|--|
| PD86-3-1180 (-option) | PANdrive 7.00 Nm, 118.5mm length with motor QSH8618-96-55-700 | | |
| INTERFACE OPTIONS | | | |
| TMCL | with TMCL™ firmware | | |
| CANopen | with CANopen firmware (under development) | | |

^{INFO} The PANdrive PD86-1180 is a mechatronic solution including a 86mm flange motor, a controller board and a sensOstep[™] encoder. It can be controlled via serial interface or operated in stand-alone mode. Power supply, external encoder, interface and multi purpose I/Os can be connected with JST connectors.

With the advanced stallGuardz[™] feature the load of the motor can be detected with high resolution. The new outstanding coolStep[™] technology for sensorless load dependent current control allows energy efficient motor operation.

The PD86-1180 comes with the PC based software development environment TMCL-IDE for the Trinamic Motion Control Language (TMCL™). Predefined high level TMCL™ commands guarantee a rapid development of motion control applications. Communication traffic is kept very low since all time critical operations, e.g. ramp calculation are performed onboard. CANopen firmware will be available optionally.

PD86-1180

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Drive

ABN

MOSFET Driver Stage

TMCM-118

Motion ontroller

TMC428

TMCL™

μC

R5232 ← 🛃

RS485 ← 🛃

USB← 🗧

add. I/Os Step/←

18... 55V D