

# 16V to 60V, 1A 1ch 2.1MHz **Synchronous Buck Converter Integrated FET** For Automotive

# BD9V100MUF-C

#### **General Description**

BD9V100MUF-C is a current mode synchronous buck converter integrating high voltage rating POWER MOSFETs. The wide range input 16V to 60V and very short minimum pulse width down to 20ns enables direct conversion from 48V battery to 3.3V at 2.1MHz operation by Nano Pulse Control<sup>™</sup>.

#### Features

- Nano Pulse Control<sup>™</sup> Enables Direct Conversion 60V to 3.3V at 2.1MHz
- AEC-Q100 Qualified(Note 1)
- SW Minimum ON Time 20ns(Max)
- Synchronous Switching Regulator Integrating **POWER MOSFETs**
- Soft Start Function
- **Current Mode Control**
- **Over Current Protection**
- Input Under Voltage Lock Out Protection
- Input Over Voltage Lock Out Protection
- **Thermal Shutdown Protection**
- **Output Over Voltage Protection**
- Short Circuit Protection
- Wettable Frank QFN Package (Note 1) Grade 1

## **Applications**

- Automotive Battery Powered Supplies
- Industrial Equipment
- **Consumer Supplies**

**Typical Application Circuit** 

#### **Key Specifications**

## Input Voltage Range:

- 16V to 60V Output Voltage Range: 0.8V to 5.5V
- **Output Current:** 1A(Max)
- **Operating Frequency:** 1.9MHz to 2.3MHz Reference Voltage Accuracy:

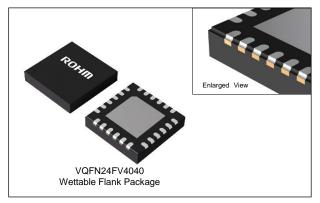
- ±2% (-40°C to +125°C)
- Shutdown Circuit Current:  $0\mu A(Typ)$
- Operating Temperature Range: -40°C to +125°C

#### Package

VQFN24FV4040

# W(Typ) x D(Typ) x H(Max)

4.00mm x 4.00mm x 1.00mm



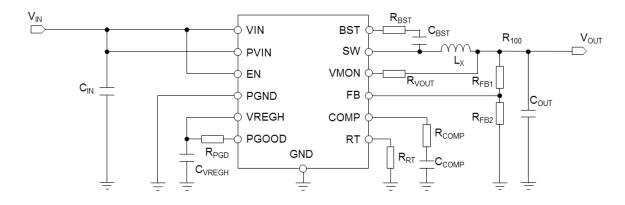


Figure 1. Application Circuit

Nano Pulse Control<sup>™</sup> is a trademark of ROHM Co., Ltd.

OProduct structure : Silicon monolithic integrated circuit OThis product has no designed protection against radioactive rays

# **Pin Configuration**

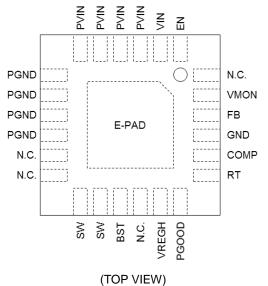


Figure 2. Figure of Terminal Placement

## **Pin Description**

Pin No.	Pin Name	Function
1	EN	Enable pin. Apply Low-level (0.8V or lower) to turn this device off. Apply High-level (2.5V or higher) to turn this device on.
2	VIN	Power supply input pin of the internal circuitry. Connect this pin to PVIN.
3 to 6	PVIN	Power supply input pins that are used for the output stage of the switching regulator. Connecting input ceramic capacitors with values of $2.2\mu$ F and $0.1\mu$ F to this pin is recommended.
7 to 10	PGND	Power GND input pins.
11,12	N.C.	No connection pins. Leave these pins open, or connect PGND pin.
13,14	SW	Switching node pins. These pins are connected to the source of the internal the Top POWER MOSFET and the drain of the internal Bottom side POWER MOSFET. Connect the power inductor and the bootstrap capacitor $0.022\mu$ F and resistor $3.3\Omega$ to these pins.
15	BST	Power supply pin of the internal the Top POWER MOSFET. Connect a $3.3\Omega$ resistor to this pin in series with a $0.022\mu$ F bootstrap capacitor connected to SW pin. This capacitor's voltage becomes the power supply of the Top POWER MOSFET gate driver.
16	N.C.	No connection pin. Leave this pin open.
17	VREGH	Internal power supply output pin. This node supplies power 5V(Typ) to other blocks which are mainly responsible for the control function of the switching regulator. Connect a ceramic capacitor with value of 2.2µF to ground.
18	PGOOD	Power Good pin. This pin is in open drain configuration so pull-up resistor is needed to turn it HIGH or LOW.
19	RT	This pin is used for setting the switching frequency. Connect a frequency setting resistor between this pin and GND pin.
20	COMP	Output of the gm error amplifier, and the input of PWM comparator. Connect phase compensation components to this pin. See page 23 on calculate the resistance and capacitance of phase compensation.
21	GND	Ground pin.
22	FB	V <sub>OUT</sub> voltage feedback pin. Inverting input node for the gm error amplifier. Connect output voltage divider to this pin to set the output voltage. See page 22 on how to compute for the resistor values.
23	VMON	Short Circuit Protection threshold detect pin. This node is monitoring the output voltage and discharging it during shutdown.
24	N.C.	No connection pin. Leave this pin open.
-	E-PAD	Exposed pad. Connect this pad to the internal PCB ground plane using multiple via holes to obtain excellent heat dissipation characteristics.

# Block Diagram

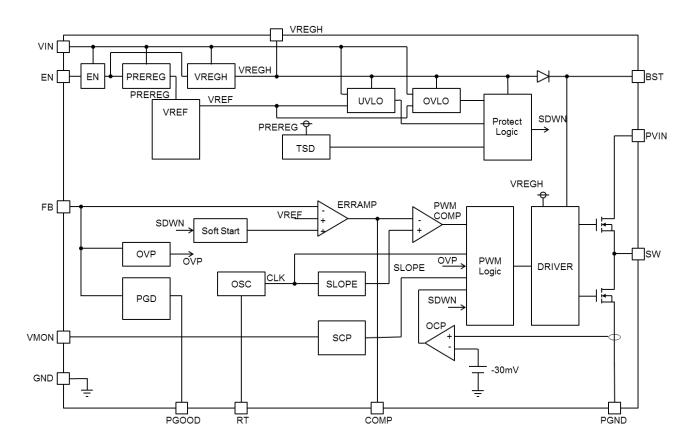


Figure 3. Block Diagram

# **Description of Blocks**

- ERRAMP

The ERRAMP block is an error amplifier and its inputs are the reference voltage 0.8V(Typ) and the FB pin voltage. The duty of switching pulse is controlled by ERRAMP output COMP. Set output voltage with FB pin. Moreover, the external resistor and capacitor are required to COMP pin as phase compensation circuit (refer to Selection of the Phase Compensation Circuit R<sub>COMP</sub>, C<sub>COMP</sub> on page 23).

- Soft Start

The Soft Start block prevents the overshoot of the output voltage by gradually increasing the input of the error amplifier when the power supply turns ON to gradually increase the switching duty cycle. The soft start time is set to 1.1ms ( $f_{SW}$ =2.1MHz). The soft start time can be changed by adjusting the oscillating frequency (refer to Soft Start Time on page 24).

- EN

This IC is in normal operation when the voltage at EN terminal is 2.5V or more. The IC will be shutdown when the voltage at EN terminal becomes open or 0.8V or less.

#### - VREGH

This block outputs a regulated 5V(Typ) and supplies it to different blocks in the chip. Connect  $2.2\mu$ F ceramic capacitor to GND.

- OSC (Oscillator)

This circuit generates a clock signal that determines converter switching frequency which is 1.9MHz to 2.3MHz. The frequency of the clock can be set by a resistor connected between the RT pin and the GND pin (refer to page 24 Figure 38). The OSC output send the clock signal to PWM Logic. This clock is also used to set the Soft Start time and Protect block counter.

## - SLOPE

This block generates a sawtooth waveform from OSC clock. The inductor current feedback is added to the sawtooth signal.

#### - PWM COMP

This block modulates duty cycle by comparing the COMP pin voltage and the sawtooth signal from the SLOPE block.

- PWM Logic

The PWM Logic block controls the POWER MOSFETS ON and OFF timings. In normal operation, the clock signal from OSC block determines the Top POWER MOSFET ON timing, and the PWM COMP block output determines the OFF timing. In addition, each protection output signal is passed to the PWM Logic and it controls proper protection functions.

- TSD (Thermal Shutdown)

This block is a thermal shutdown circuit. Both of the output MOSFETs are turned OFF and the VREGH is stopped to prevent thermal damage or a thermal-runaway of the IC when the chip temperature reaches to approximately 175°C(Typ) or more, and the operation comes back when the chip temperature comes down to 150°C(Typ) or less. Note that the thermal shutdown circuit is intended to prevent destruction of the IC itself. Therefore, it is highly recommended to keep the IC temperature always within the operating temperature range. Operation above operating temperature range will reduce the lifetime of the IC.

- OCP (Over Current Protection)

While the Bottom POWER MOSFET is ON, if the voltage between the drain and source exceeds the reference voltage which is internally set within IC, OCP will activate. This protection is a self-return type. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation of the protection circuit (e.g. when a load that significantly exceeds the output current capability of the chip is connected).

- OVP (Over Voltage Protection)

This is the output over voltage protection circuit. When the output becomes 120%(Typ) or more of the target voltage, both of the output MOSFETs are turned OFF and the regulator operation is stopped. When the output voltage becomes 110%(Typ) or less of the target voltage, it returns to normal operation.

- UVLO (Under Voltage Lock-Out)

UVLO is a protection circuit that prevents low voltage malfunction, especially during power up and down. It monitors the  $V_{IN}$  power supply voltage. If  $V_{IN}$  becomes 15.0V(Max) or less, both of the output MOSFETs are turned OFF and the regulator operation is stopped. When the input voltage becomes 16.0V(Max) or more, the regulator restarts the operation with Soft Start.

- DRIVER

This circuit drives the gate of the output POWER MOSFETs.

- OVLO(Over Voltage Lock-Out)

This is the input over voltage protection circuit. When the input voltage becomes 60.0V(Min) or more, the regulator is shutdown. When the input voltage becomes 59.0V(Min) or less the falling threshold, the regulator restarts the operation with SOFT START. This hysteresis is 1.0V(Typ).

# **Description of Blocks - continued**

- PGD

The PGOOD circuit is a reference voltage monitoring circuit. The PGOOD pin sets to Hi-Z when the FB voltage is 90%(Typ) or more and 110%(Typ) or less of reference voltage, otherwise the PGOOD pin is pulled down to GND. PGOOD detection has a hysteresis of 20mV(Typ) for each of the upper and lower thresholds.

- SCP(Short Circuit Protection)

The short circuit protection circuit. Depending on the level of the VIN terminal voltage and VMON terminal voltage, a reference pulse signal with varying ON time will be produced. If the SW ON time exceeds 2.5times(Typ) the ON time of this reference pulse signal for 2clk cycles, short circuit protection will be activated. Then the Top and Bottom POWER MOSFETs will be turned OFF.

# Absolute Maximum Ratings (Ta=25°C)

Parameter	Symbol	Rating	Unit
Supply Voltage	$V_{\text{IN}},PV_{\text{IN}}$	-0.3 to +70	V
EN Input Voltage	VEN	-0.3 to V <sub>IN</sub>	V
BST Voltage	V <sub>BST</sub>	-0.3 to +70	V
Voltage from SW to BST	ΔV <sub>BST</sub>	Vsw -0.3 to Vsw + 7	V
FB, RT, COMP, PGOOD Input Voltage	Vfb, Vrt, Vcomp, Vpgood	-0.3 to +7	V
VMON Input Voltage	VVMON	-0.3 to +7	V
VREGH Input Voltage	VVREGH	-0.3 to +7	V
Storage Temperature Range	Tstg	-55 to +150	°C
Maximum Junction Temperature	Tjmax	150	°C

Caution 1: Operating the IC over the absolute maximum ratings may damage the IC. The damage can either be a short circuit between pins or an open circuit between pins and the internal circuitry. Therefore, it is important to consider circuit protection measures, such as adding a fuse, in case the IC is operated over the absolute maximum ratings.

Caution 2: Should by any chance the maximum junction temperature rating be exceeded the rise in temperature of the chip may result in deterioration of the properties of the chip. In case of exceeding this absolute maximum rating, increase the board size and copper area to prevent exceeding the maximum junction temperature rating.

#### Thermal Resistance<sup>(Note 1)</sup>

Sympol	Thermal Res	Linit	
Symbol	1s <sup>(Note 3)</sup>	2s2p <sup>(Note 4)</sup>	Unit
θյΑ	150.6	37.9	°C/W
$\Psi_{JT}$	20	9	°C/W
-		Symbol         1s <sup>(Note 3)</sup> θJA         150.6	Symbol         1s <sup>(Note 3)</sup> 2s2p <sup>(Note 4)</sup> θ <sub>JA</sub> 150.6         37.9

(Note 1) Based on JESD51-2A (Still-Air)

(Note 2) The thermal characterization parameter to report the difference between junction temperature and the temperature at the top center of the outside (Note 3) Using a PCB board based on JESD51-3.

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Layer Number of Measurement Board	Material	Board Size
Single	FR-4	114.3mm x 76.2mm x 1.57mmt
Тор		
Copper Pattern	Thickness	
Footprints and Traces	70µm	
		-

(Note 4) Using a PCB board based on JESD51-5, 7.

Layer Number of	Matorial	Board Size		Material Board Size		Thermal Via <sup>(Note 5)</sup>		
Measurement Board	Material			Pitch	Diameter			
4 Layers	FR-4	114.3mm x 76.2mm x 1.6mmt		1.20mm	Ф0.30mm			
Тор		2 Internal Layers		Bottom				
Copper Pattern	Thickness	Copper Pattern	Thickness	Copper Pattern	Thickness			
Footprints and Traces	70µm	74.2mm x 74.2mm	35µm	74.2mm x 74.2m	m 70µm			

(Note 5) This thermal via connects with the copper pattern of all layers.

## **Recommended Operating Conditions**

Symbol	Min	Тур	Max	Unit
Vin	16	-	60	V
Topr	-40	-	+125	°C
Vout	0.8	-	5.5	V
tonmin	-	9	20	ns
IOUT	0	-	1	А
fsw	1.9	2.1	2.3	MHz
CIN	1.2	-	-	μF
Rrt	6.9	7.5	8.1	kΩ
	VIN Topr Vout tonmin Iout fsw Cin	VIN         16           Topr         -40           VOUT         0.8           tonmin         -           Iout         0           fsw         1.9           CIN         1.2	VIN         16         -           Topr         -40         -           VOUT         0.8         -           tonmin         -         9           lout         0         -           fsw         1.9         2.1           C <sub>IN</sub> 1.2         -	VIN         16         -         60           Topr         -40         -         +125           VOUT         0.8         -         5.5           tonmin         -         9         20           Iout         0         -         1           fsw         1.9         2.1         2.3           CIN         1.2         -         -

(Note 1) This parameter is for 0.5A output. Not 100% tested.

(Note 2) Ceramic capacitor is recommended. The capacitor value including temperature change, DC bias change, and aging change must be larger than minimum value (Refer to Selection of Input Capacitor C<sub>IN</sub>, C<sub>BLK</sub> on page 22). Also, the IC might not function properly when the PCB layout or the position of the capacitor is not good. Please check PCB Layout Design on page 30.

## Electrical Characteristics (Unless otherwise specified Ta=-40°C to +125°C, V<sub>IN</sub>=48V, V<sub>EN</sub>=5V)

					N-101,	• = • • • /
Parameter	Symbol	Min	Тур	Max	Unit	Conditions
Shutdown Circuit Current	Isdn	-	0	5	μA	V <sub>EN</sub> =0V, Ta=105°C
Circuit Current	Icc	-	2.5	3.8	mA	V <sub>FB</sub> =2.0V
Reference Voltage	Vfb	0.784	0.800	0.816	V	V <sub>FB</sub> =V <sub>COMP</sub>
FB Input Current	IFB	-1	0	+1	μA	V <sub>FB</sub> =5.0V
COMP Pin Sink Current	ICPSINK	35	60	85	μA	V <sub>COMP</sub> =1.0V, V <sub>FB</sub> =2V
COMP Pin Source Current	ICPSOURCE	-85	-60	-35	μA	V <sub>COMP</sub> =1.0V, V <sub>FB</sub> =0V
Soft Start Time <sup>(Note1)</sup>	tss	0.7	1.1	1.5	ms	fsw=2.1MHz, R <sub>RT</sub> =7.5kΩ
Top Power NMOS ON Resistance	Ronh	-	600	900	mΩ	Iou⊤=-50mA
Bottom Power NMOS ON Resistance	Ronl	-	400	600	mΩ	Iout=50mA
Output Leak Current H	Ioleakh	-5	0	+5	μA	V <sub>IN</sub> =70V, V <sub>EN</sub> =0V Ta=105°C, V <sub>SW</sub> =0V
Output Leak Current L	Ioleakl	-5	0	+5	μA	V <sub>IN</sub> =70V, V <sub>EN</sub> =0V Ta=105°C, V <sub>SW</sub> =70V
Operating Output Switch Current of Overcurrent Protection	Isw	1.5	2.4	3.3	А	
Oscillating Frequency	fsw	1.9	2.1	2.3	MHz	R <sub>RT</sub> =7.5kΩ
EN Threshold Voltage H	Venh	2.5	-	Vin	V	
EN Threshold Voltage L	Venl	0	-	0.8	V	
EN Input Current	IEN	-	8.5	20	μA	V <sub>EN</sub> =5V
VIN Under Voltage Protection Detection Voltage	Vuv_on	12.5	13.7	15.0	V	V <sub>IN</sub> Falling
VIN Under Voltage Protection Return Voltage	Vuv_off	13.5	14.7	16.0	V	V <sub>IN</sub> Rising
VIN Over Voltage Protection Detection Voltage	V <sub>OV_ON</sub>	60.0	62.5	65.0	V	V <sub>IN</sub> Rising
VIN Over Voltage Protection Return Voltage	V <sub>OV_OFF</sub>	59.0	61.5	64.0	V	V <sub>IN</sub> Falling
OVP Threshold Voltage H	VOVPH	0.87	0.96	1.05	V	V <sub>FB</sub> Rising
OVP Threshold Voltage L	Vovpl	0.83	0.92	1.01	V	V <sub>FB</sub> Falling
PGOOD L Threshold	Vpgdl	V <sub>FB</sub> x 0.82	V <sub>FB</sub> x 0.90	V <sub>FB</sub> x 0.98	V	V <sub>FB</sub> Falling
PGOOD L Hysteresis	Vpgdlh	4	20	40	mV	
PGOOD H Threshold	Vpgdh	V <sub>FB</sub> x 1.02	V <sub>FB</sub> x 1.10	V <sub>FB</sub> x 1.18	V	V <sub>FB</sub> Rising
PGOOD H Hysteresis	Vpgdhl	-40	-20	-4	mV	
PGOOD ON Resistance	R <sub>PGD</sub>	-	0.22	1	kΩ	I <sub>PGOOD</sub> =10mA
PGOOD Leak Current	IPGD	-	0	1	μA	Vpgood=5V

(Note 1)  $V_{FB}$  transient time from 0.1V to 0.7V.

(Note 2) Not 100% tested.

# **Typical Performance Curves**

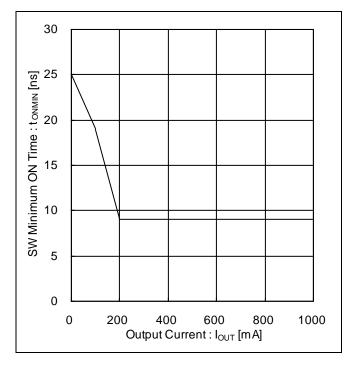


Figure 4. SW Minimum ON Time vs Output Current

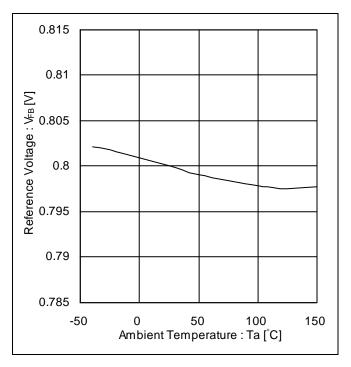


Figure 5. Reference Voltage vs Ambient Temperature

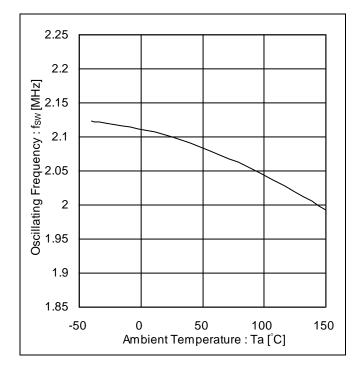
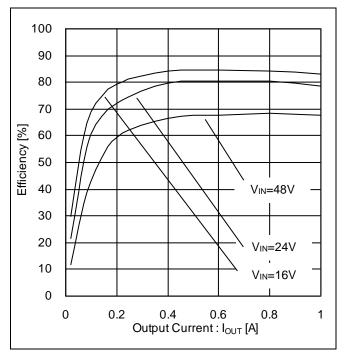
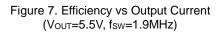
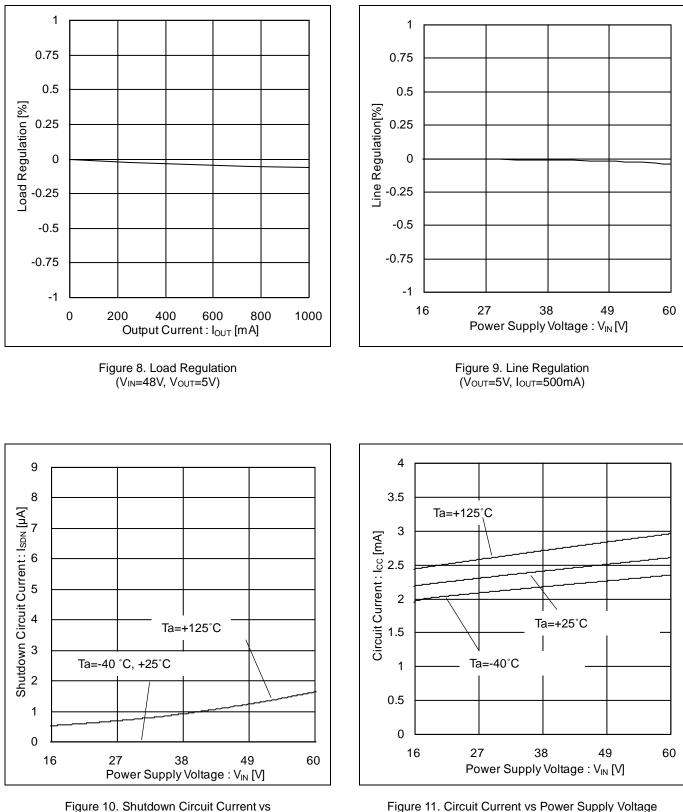


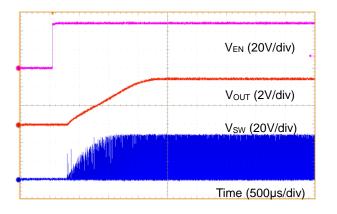
Figure 6. Oscillating Frequency vs Ambient Temperature







Power Supply Voltage (V<sub>EN</sub>=0V)



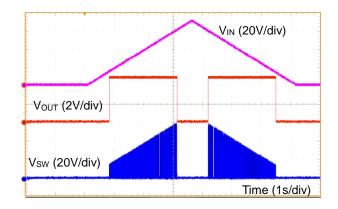
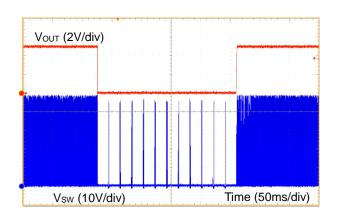
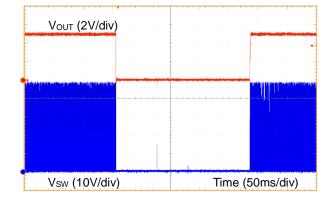


Figure 12. Startup Waveform (VIN=48V, VOUT=5V, IOUT=0.5A)

Figure 13. Startup and Shutdown Waveform (V\_{IN}=0V \leftrightarrow 70V, V\_{OUT}=5V, I\_{OUT}=0.5A)





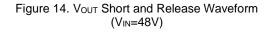


Figure 15. SW Short and Release Waveform ( $V_{IN}$ =48V)

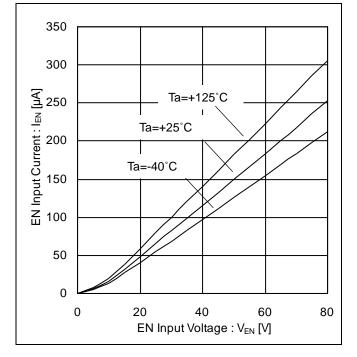


Figure 16. EN Input Current vs EN Input Voltage

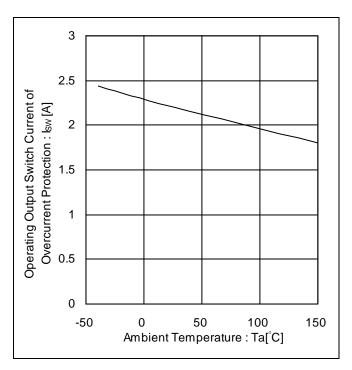


Figure 17. Operating Output Switching Current of Over Current Protection vs Ambient Temperature  $(V_{IN}$ =48V,  $V_{OUT}$ =5V)

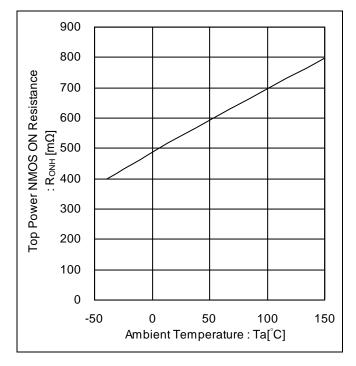


Figure 18. Top Power NMOS ON Resistance vs Ambient Temperature

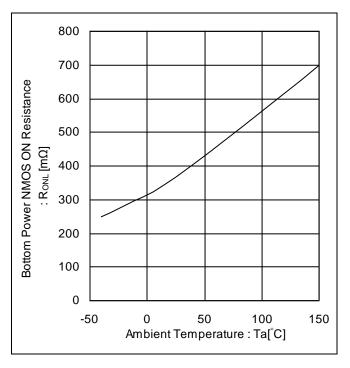
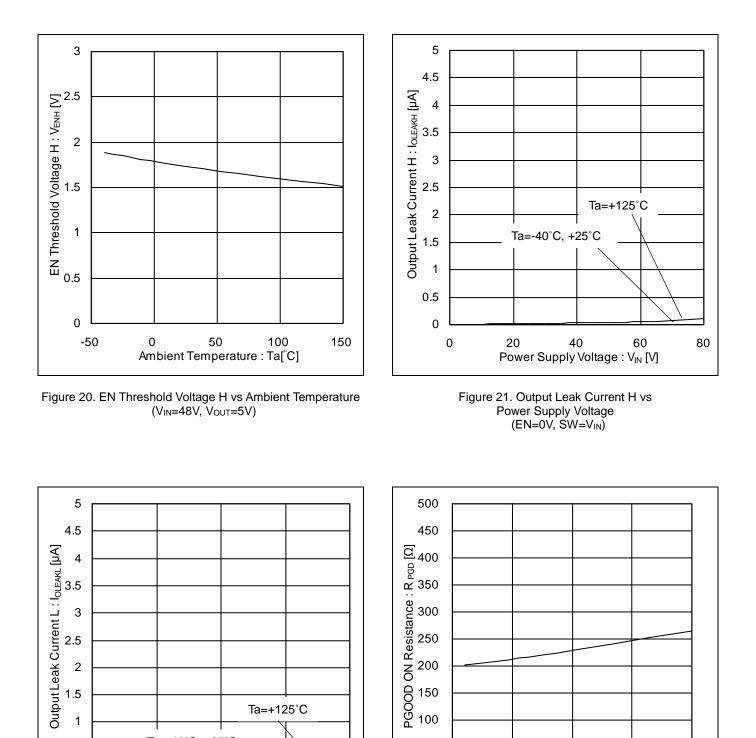
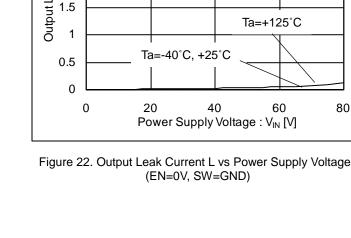


Figure 19. Bottom Power NMOS ON Resistance vs Ambient Temperature





2.5

2

Figure 23. PGOOD ON Resistance vs Ambient Temperature

50

Ambient Temperature : Ta[°C]

0

80

50

0

-50

100

150

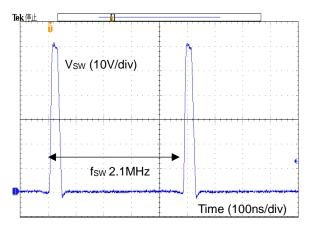
# **Function Explanation**

1. Nano Pulse Control<sup>™</sup>

Nano Pulse Control<sup>™</sup> is an original technology developed by ROHM Co., Ltd. It enables to control voltage stably, which is difficult in the conventional technology, even in a narrow SW ON Pulse such as less than 50ns at typical condition. Therefore, high frequency switching operation become possible. BD9V100MUF-C is designed with 9ns(Typ) Minimum SW ON time for current sense and 2.1MHz(Typ) switching frequency by using this technology.

(1) High VIN Low VOUT Operation

Narrow SW ON Pulse enables direct convert of high output voltage to low output voltage. BD9V100MUF-C, the output voltage V<sub>OUT</sub> 3.3V can be output directly from the supply voltage V<sub>IN</sub> 60V at 2.1MHz.



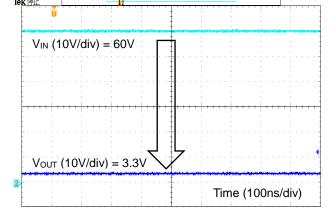


Figure 24. Switching Waveform (V\_{IN}=60V, V\_{OUT}=3.3V, I\_{OUT}=0.5A, f\_{SW}=2.1MHz)

Figure 25. V\_IN V\_OUT Waveform (V\_IN=60V, V\_OUT=3.3V, I\_OUT=0.5A, f\_Sw=2.1MHz)

(2) Stable Startup Waveform

Narrow SW ON Pulse enables stable output waveform even at startup. BD9V100MUF-C achieves a stable Soft Start operation under wide input voltage conditions.

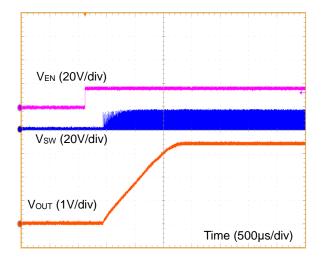


Figure 26. Startup Waveform (V\_{IN}=16V, V\_{OUT}=3.3V, I\_{OUT}=0.5A, f\_{SW}=2.1MHz)

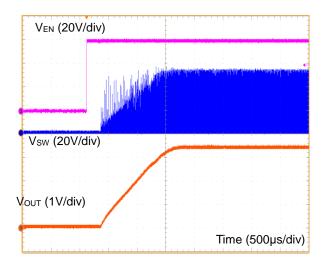
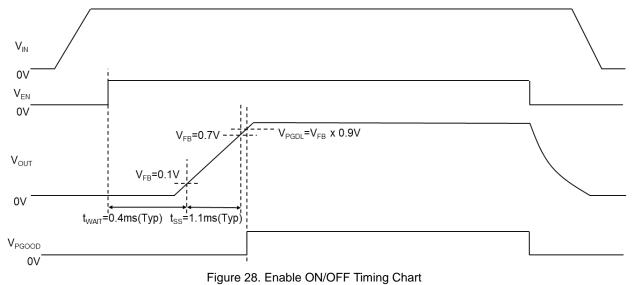


Figure 27. Startup Waveform (VIN=60V, VOUT=3.3V, IOUT=0.5A, fsw=2.1MHz)

# **Function Explanation - continued**

2. Enable Operation

Shutdown and startup of the IC can be controlled by the voltage applied to the EN pin. When EN voltage reaches 2.5V(Max) or more, the internal VREGH activates and the IC operates. When an EN voltage become 0.8V(Max) or less, the IC will be shutdown.



3. Power Good

When the output voltage is within the voltage range of  $\pm 10\%$ (Typ), the PGOOD pin set Hi-Z. When the output voltage is outside the voltage range of  $\pm 10\%$ (Typ), the PGOOD pin is pulled down with a built-in MOSFET of  $0.22k\Omega$ (Typ). Pull up the PGOOD pin to VREGH with a resistor of about  $10k\Omega$  to  $100k\Omega$ .

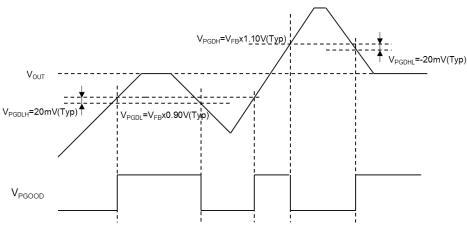


Figure 29. PGOOD Timing Chart

# **Protect function**

1. Under Voltage Lockout (UVLO)

Under Voltage Lockout monitors the VIN terminal voltages. When the VIN voltage is at 15.0V(Max) or less, both of the output MOSFETs are turned OFF and the regulator operation is stopped. When the input voltage becomes 16.0V(Max) or more, the regulator restarts the operation with Soft Start.

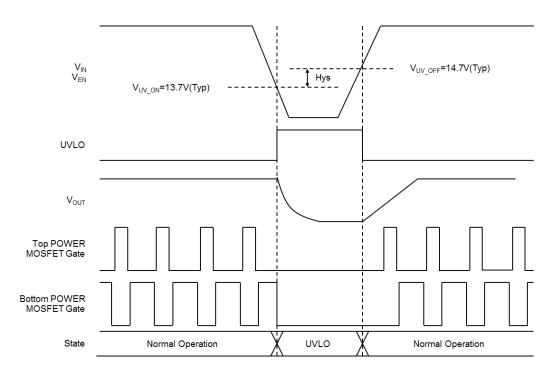


Figure 30. UVLO Timing Chart

## **Protect function - continued**

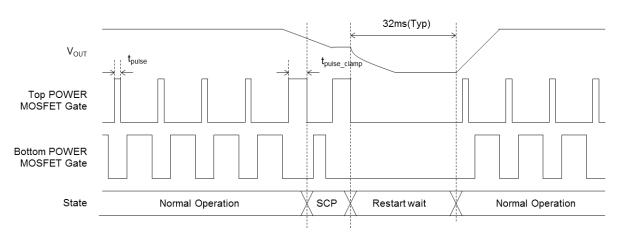
2. Short Circuit Protection(SCP)

The Short Circuit Protection function produces a reference pulse that has an ON time derived from  $V_{IN}$  and  $V_{OUT}$ . This reference pulse's ON time is compared to the SW ON time. If the SW ON time exceeds 2.5times(Typ) of the expected SW ON time, and remains in that state for 2clk (clk =  $1/f_{SW}$ ) cycles, it will stop both of the output MOSFETs for 32ms(Typ) and then restarts again. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation of the protection circuit (e.g. when a load that significantly exceeds the output current capability of the chip is connected).

The assumed SW ON Time is obtained from the following formula:

$$t_{pulse} = \frac{1}{2.1[MHz]} \times \frac{V_{OUT}}{V_{IN}} \text{ [µs]}$$

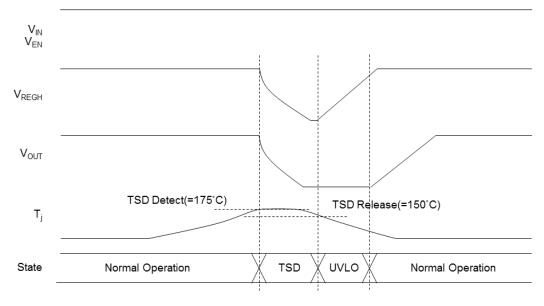
$$t_{pulse\_clamp} = \frac{1}{2.1[MHz]} \times \frac{V_{OUT}}{V_{IN}} \times 2.5$$
 [µs]





3. Thermal Shutdown(TSD)

When the chip temperature exceeds  $T_j=175^{\circ}C(Typ)$ , both of the output MOSFETs are turned OFF and the VREGH is stopped. The operation comes back when the chip temperature comes down to  $150^{\circ}C(Typ)$  or less. TSD prevents the IC from thermal runaway under abnormal conditions exceeding Tjmax= $150^{\circ}C$ . The TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

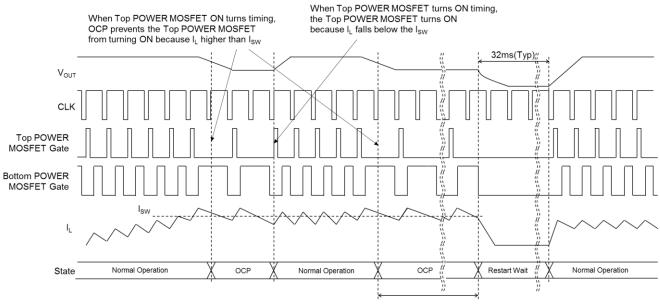




## **Protect function - continued**

4. Over Current Protection (OCP)

Over Current Protection detects the lower limit value of the inductor current. The OCP is designed at 2.4A(Typ). This circuit prevents the Top POWER MOSFET from turning ON until the inductor current  $I_L$  falls below the OCP limit I<sub>SW</sub>. If OCP is detected 8times in 30µs(Typ), operation stops for 32ms(Typ) and then restarts again. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation of the protection circuit (e.g. when a load that significantly exceeds the output current capability of the chip is connected).

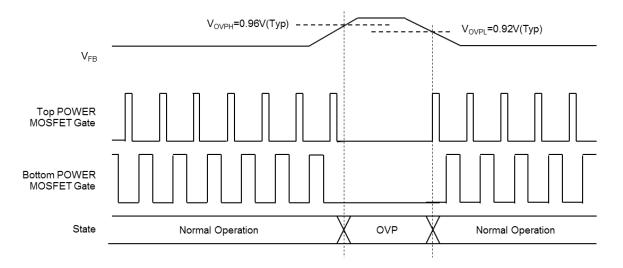


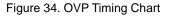
OCP is detected 8times in 30µs(Typ), operation stops



#### 5. Over Voltage Protection (OVP)

Over Voltage Protection compares the feedback voltage with an internal reference voltage. When the feedback voltage exceeds 0.96V(Typ) or more, the Top and Bottom POWER MOSFETs will turn OFF. When the output voltage decreases to a value of 0.92V(Typ) or less, it goes back to normal operation.





# **Protect function - continued**

6. Over Voltage Lockout(OVLO)

Over Voltage Lockout monitors the VIN terminal voltage. When the VIN voltage is 60.0V(Min) or more, the chip will be on standby mode, and when the VIN voltage is 59.0V(Min) or less, the chip will startup again.

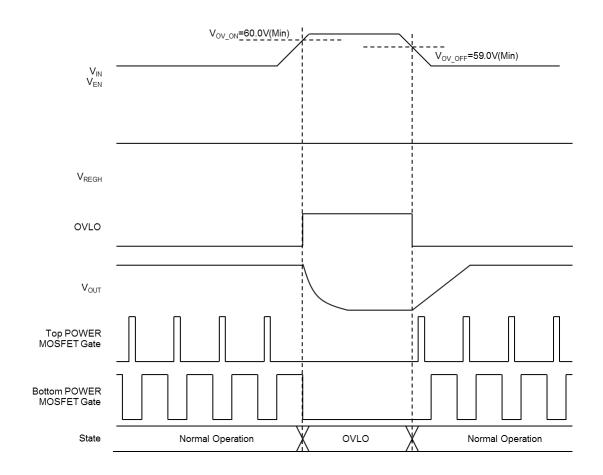


Figure 35. OVLO Timing Chart

# Selection of Components Externally Connected

## Contact us if not use the recommended constant in the application circuit.

Necessary parameters in designing the power supply are as follows:

Table 1	Applicatio	n Specification
	, applicatio	in opcomoution

Parameter	Symbol	Specification Case
Input Voltage	Vin	16V to 60V
Output Voltage	V <sub>OUT</sub>	5.0V
Output Ripple Voltage	ΔV <sub>P-P</sub>	20mV <sub>p-p</sub>
Output Current	lout	Min 0.1A / Typ 0.5A / Max 1.0A
Switching Frequency	fsw	2.1MHz
Operating Temperature Range	Topr	-40°C to +125°C

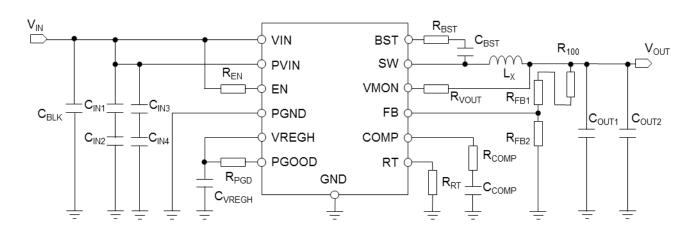


Figure 36. Application Sample Circuit

1. Selection of the inductor L<sub>X</sub> value

Role of the coil in the switching regulator is that it also serves as a filter for smoothing the output voltage to supply a continuous current to the load. The Inductor ripple current  $\Delta I_{L}$  that flows to the inductor becomes small when an inductor with a large inductance value is selected. Consequently, the voltage of the output ripple  $\Delta V_{P-P}$  also becomes small. It is the trade-off between the size and the cost of the inductor.

The inductance of the inductor is shown in the following equation:

$$L = \frac{(V_{IN(Max)} - V_{OUT}) \times V_{OUT}}{V_{IN(Max)} \times f_{SW} \times \Delta I_L} \quad [H]$$

Where:

V <sub>IN (Max)</sub>	is the maximum input voltage
$V_{OUT}$	is the output voltage
<i>f<sub>sw</sub></i>	is the switching frequency
$\Delta I_L$	is the peak to peak inductor current

In current mode control, sub-harmonic oscillation may happen. The slope compensation circuit is integrated into the IC in order to prevent sub-harmonic oscillation. The sub-harmonic oscillation depends on the rate of increase of output switch current. If the inductor value is too small, the sub-harmonic oscillation may happen because the inductor ripple current  $\Delta I_L$  is increased. And if the inductor value is too large, the feedback loop may not achieve stability because the inductor ripple current  $\Delta I_L$  is decreased. Therefore, use an inductor value of the coil within the range of  $3.3\mu$ H to  $10\mu$ H. The smaller the  $\Delta I_L$ , the smaller the Inductor core loss (iron loss), and the smaller is the loss due to ESR of the output capacitor. In effect,  $\Delta V_{P-P}$  (Output peak-to-peak ripple voltage) will be reduced.  $\Delta V_{P-P}$  is shown in the following equation.

$$\Delta V_{P-P} = \Delta I_L \times ESR + \frac{\Delta I_L}{8 \times C_{OUT} \times f_{SW}} \quad [V]$$
(a)

Where:

ESR	is the equivalent series resistance of the output capacitor
$C_{OUT}$	is the output capacitance
$\Delta I_L$	is the peak to peak inductor current
f <sub>sw</sub>	is the switching frequency

Generally, even if  $\Delta I_L$  is somewhat large, the  $\Delta V_{P-P}$  target is satisfied because the ceramic capacitor has a very-low ESR. It also contributes to the miniaturization of the application board. Also, because of the lower rated current, smaller inductor is possible since the inductance is small. The disadvantages are increase in core losses in the inductor and the decrease in maximum output current. When other capacitors (electrolytic capacitor, tantalum capacitor, and electro conductive polymer etc.) are used for output capacitor  $C_{OUT}$ , check the ESR from the manufacturer's data sheet and determine the  $\Delta I_L$  to fit within the acceptable range of  $\Delta V_{P-P}$ . Especially in the case of electrolytic capacitor, because the decrease in capacitance at low temperatures is significantly large, this will make  $\Delta V_{P-P}$  increase. When using capacitor at low temperature, this is an important consideration.

The shielded type (closed magnetic circuit type) is the recommended type of inductor to be used. Please note that magnetic saturation may occur. It is important not to saturate the core in all cases. Precautions must be taken into account on the given provisions of the current rating because it differs on every manufacturer. Please confirm the rated current at maximum ambient temperature of application to the manufacturer.

#### 2. Selection of Output Capacitor COUT

The output capacitor is selected based on the ESR that is required from the equation (a).  $\Delta V_{P-P}$  can be reduced by using a capacitor with a small ESR. The ceramic capacitor is the best option that meets this requirement. It is because not only does it has a small ESR but the ceramic capacitor also contributes to the size reduction of the application circuit. Please confirm the frequency characteristics of ESR from the datasheet of the manufacturer, and consider a low ESR value for the switching frequency being used. It is necessary to consider the ceramic capacitor because the DC biasing characteristic is important. For the voltage rating of the ceramic capacitor, twice or more than the maximum output voltage is usually required. By selecting a high voltage rating, it is possible to reduce the influence of DC bias characteristics. Moreover, in order to maintain good temperature characteristics, the one with the characteristics of X7R or better is recommended. Because the voltage rating of a large ceramic capacitor is low, the selection becomes difficult for an application with high output voltage. In that case, please connect multiple ceramic capacitors in series or select electrolytic capacitor. Consider having a voltage rating of 1.2 times or more of the output voltage when using electrolytic capacitor. Electrolytic capacitors have a high voltage rating, large capacitance, small amount of DC biasing characteristics, and are generally reasonable. Since the electrolytic capacitor is usually OPEN when it fails, it is effective to use for applications when reliability is required such as automotive. But there are disadvantages such as, ESR is relatively high, and decreases capacitance value at low temperatures. In this case, please take note that  $\Delta V_{P-P}$  may increase at low temperature conditions. Moreover, consider the lifetime characteristic of this capacitor because it has a possibility to dry up. A tantalum capacitor and a conductive polymer hybrid capacitor have excellent temperature characteristics unlike the electrolytic capacitor. Moreover, since their ESR is smaller than an electrolytic capacitor, the ripple voltage is relatively-small over a wide temperature range. Since these capacitors have almost no DC bias characteristics, design will be easier. Regarding voltage rating, the tantalum capacitor is selected such that its capacitance is twice the value of the output voltage, and for the conductive polymer hybrid capacitor, it is selected such that the voltage rating is 1.2 times the value of the output voltage. The disadvantage of a tantalum capacitor is that it is SHORTED when it is destroyed, and its breakdown voltage is low. It is not generally selected in an application that reliability is a demand such as in automotive. An electro conductive polymer hybrid capacitor is OPEN when destroyed. Though it is effective for reliability, its disadvantage is that it is generally expensive.

To improve the performance of ripple voltage in this condition, following is recommended:

- 1. Use low ESR capacitor like ceramic or conductive polymer hybrid capacitor.
- 2. Use a capacitor  $C_{\text{OUT}}$  with a higher capacitance value.

These capacitors are rated in ripple current. The RMS values of the ripple current that can be obtained in the following equation must not exceed the ripple current rating.

$$I_{CO(RMS)} = \frac{\Delta I_L}{\sqrt{12}}$$
 [A]

Where:

 $I_{CO(RMS)}$  is the value of the ripple electric current  $\Delta I_L$  is the peak to peak inductor current

In addition, for the total value of capacitance in the output line  $C_{OUT}(Max)$ , choose a capacitance value less than the value obtained by the following equation:

$$C_{OUT(Max)} < \frac{t_{SS(Min)} \times (I_{SW(Min)} - I_{SWSTART(Max)})}{V_{OUT}}$$
 [F]

Where:

$I_{SW(Min)}$	is the OCP operation switch current (Min)
$t_{SS(Min)}$	is the Soft Start Time (Min)
I <sub>SWSTART(Max)</sub>	is the maximum output current during startup
V <sub>OUT</sub>	is the output voltage

Startup failure may happen if the limits from the above-mentioned are exceeded. Especially if the capacitance value is extremely large, over-current protection may be activated by the inrush current at startup preventing the output to turn on. Please confirm this on the actual application. For stable transient response, the loop is dependent to  $C_{OUT}$ . Please select after confirming the setting of the phase compensation circuit.

Also, in case of large changing input voltage and load current, select the capacitance accordingly by verifying that the actual application setup meets the required specification.

3. Selection of Input Capacitor CIN, CBLK

The input capacitor is usually required for two types of decoupling: capacitors  $C_{IN}$  and bulk capacitors  $C_{BLK}$ . Ceramic capacitors with values more than 1.2µF are necessary for the decoupling capacitor  $C_{IN}$ . Ceramic capacitors are effective by placing it as close as possible to the VIN pin. The voltage rating of the capacitors is recommended to be more than 1.2 times the maximum input voltage, or twice the normal input voltage. The capacitor value including device variation, temperature change, DC bias change, and aging change must be larger than minimum value. Also, the IC might not operate properly when the PCB layout or the position of the capacitor is not good. Please check "Notes on the PCB Layout" on page 30.

The bulk capacitor is optional. The bulk capacitor prevents the decrease in the line voltage and serves as a backup power supply to keep the input voltage constant. A low ESR electrolytic capacitor with large capacitance is suitable for the bulk capacitor. It is necessary to select the best capacitance value for each set of application. In that case, please take note not to exceed the rated ripple current of the capacitor.

The RMS value of the input ripple current I<sub>CIN(RMS)</sub> is obtained in the following equation:

$$I_{CIN(RMS)} = I_{OUT(MAX)} \times \frac{\sqrt{V_{OUT} \times (V_{IN} - V_{OUT})}}{V_{IN}}$$
 [A]

Where:

 $I_{OUT(MAX)}$  is the maximum output current.

In addition, in automotive and other applications requiring high reliability, it is recommended to connect the capacitors in parallel to accommodate multiple electrolytic capacitors and minimize the chances of drying up. For ceramic capacitors, it is recommended to make two series + two parallel structures to decrease the risk of capacitor destruction due to short circuit conditions.

When the impedance on the input side is high for some reason (because the wiring from the power supply to VIN is long, etc.), then high capacitance is needed. In actual conditions, it is necessary to verify that there are no problems like IC turns off, or the output overshoots due to the change in  $V_{IN}$  at transient response.

4. Selection of Output Voltage Setting Resistance R<sub>FB1</sub>, R<sub>FB2</sub> The output voltage is described by the following equation:

$$V_O = 0.8 \times \frac{R_{FB1} + R_{FB2}}{R_{FB2}}$$
 [V]

Power efficiency is reduced with a small  $R_{FB1} + R_{FB2}$ , please set the current flowing through the feedback resistors as small as possible in comparison to the output current  $I_{OUT}$ .

5. Selection of the Phase Compensation Circuit RCOMP, CCOMP

A good high frequency response performance is achieved by setting the 0dB crossing frequency, fc, (frequency at 0dB gain) high. However, you need to be aware of the trade-off correlation between speed and stability. Moreover, DC / DC converter application is sampled by switching frequency, so the gain of this switching frequency must be suppressed. It is necessary to set the 0dB crossing frequency to 80kHz or less of the switching frequency. In general, target these characteristics as follows:

- At 0dB crossing frequency, fc, phase lag should be 135° or less (phase margin is 45° or more).
- The 0dB crossing frequency, fc, must be 80kHz or less.

Achieving stability by using phase compensation is done by cancelling the  $f_{P1}$  and  $f_{P2}$  (error amp pole and power stage pole) of the feedback loop by the use of  $f_{Z1}$ .  $f_{P1}$ ,  $f_{P2}$  and  $f_{Z1}$  are determined in the following equations:

$$f_{Z1} = \frac{1}{2\pi \times R_{COMP} \times C_{COMP}}$$
 [Hz]  
$$f_{P1} = \frac{1}{2\pi \times C_{OUT} \times R_{OUT}}$$
 [Hz]

 $f_{P2} = \frac{G_{EA}}{2\pi \times C_{COMP} \times A_V} \qquad [Hz]$ 

Where:

- $R_{OUT}$  is the resistance assumed actual load[ $\Omega$ ] = Output Voltage[V] / Output Current[A],
- $G_{EA}$  is the Error Amp trans conductance (300µA/V)

 $A_V$  is the Error Amp Voltage Gain (63dB)

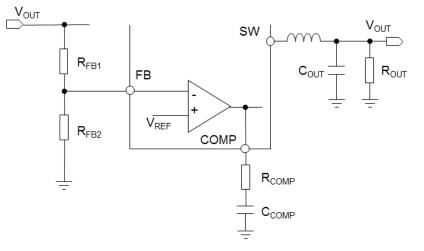


Figure 37. Setting the Phase Compensation Circuit

6. Selection of the Switching Frequency Setting Resistance R<sub>RT</sub> The internal switching frequency can be set by connecting a resistor between RT and GND. The range of frequency that can be set is 1.9MHz to 2.3MHz, and the relation between resistance and the switching frequency is decided as shown in the figure below. When setting beyond this range, there is a possibility that there is no oscillation and IC operation cannot be guaranteed.

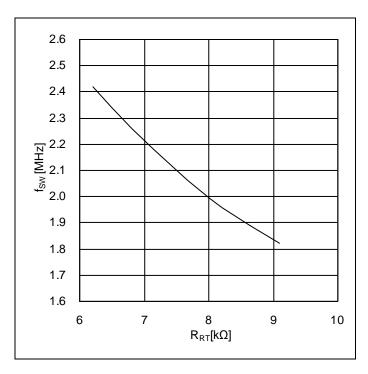


Table 2. RRT vs fsw			
R <sub>RT</sub> [kΩ]	fsw [MHz]		
6.8	2.26		
7.5	2.10		

8.2

1.96

Figure 38. Switching Frequency vs Switching Frequency Setting Resistance

7. Selection of the Bootstrap Capacitor and Resistor

Bootstrap capacitor  $C_{BST}$  value shall be 0.022µF. Bootstrap resistor  $R_{BST}$  value shall be 3.3 $\Omega$ . Connect the bootstrap capacitor in series with the bootstrap resistor between SW pin and BST pin. Recommended products are described in Application Examples1 on page 25.

8. Selection of the VREGH Capacitor.

VREGH capacitor C<sub>VREGH</sub> shall be 2.2µF ceramic capacitor. Connect the VREGH capacitor between VREGH pin and GND.

9. Selection of the VMON Resistor

At the time of V<sub>OUT</sub> short circuit, current may be drawn from the VMON terminal due to an inductive load. Connect a resistor to limit that current. VMON resistor R<sub>VOUT</sub> shall be  $2k\Omega$ .

10. Soft Start Time

Soft Start prevents the overshoot of the output voltage. It changes in proportion to the switching frequency  $f_{SW}$ . Soft start time at  $f_{SW}$  2.1MHz(Typ) is 1.1ms(Typ). The production tolerance of  $t_{SS}$  is ±36%.  $t_{SS}$  can be calculated by using the equation.

$$t_{SS} = \frac{2310}{fsw}$$
 [s]

# **Application Examples1**

Table 3. Specification Example 1

Parameter	Symbol	Specification Case
Product Name	IC	BD9V100MUF-C
Input Voltage	Vin	16V to 60V
Output Voltage	Vout	5.0V
Output Ripple Voltage	ΔV <sub>P-P</sub>	20mVp-p
Output Current	Іоит	0A to 1.0A
Switching Frequency	fsw	2.1MHz
Operating Temperature	Topr	-40°C to +125°C

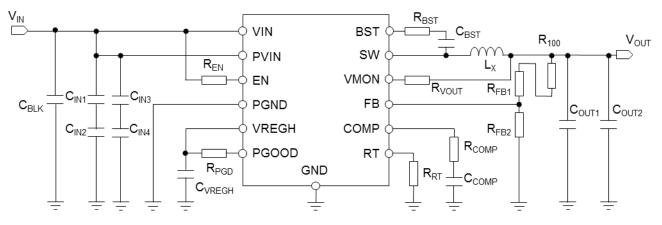


Figure 39. Reference Circuit 1

No	Package	Parameters	Part Name (Series)	Туре	Manufacturer
CBLK	-	-	-	-	-
CIN1	3225	4.7µF, X7R, 50V	GCM32ER71H475K	Ceramic	MURATA
CIN2	3225	4.7µF, X7R, 50V	GCM32ER71H475K	Ceramic	MURATA
Сімз	1608	0.1µF, X7R, 50V	GCM188R71H104K	Ceramic	MURATA
C <sub>IN4</sub>	1608	0.1µF, X7R, 50V	GCM188R71H104K	Ceramic	MURATA
CBST	1608	0.022µF, X7R, 50V	GCM188R71H223K	Ceramic	MURATA
RBST	1608	3.3Ω, 5%, 1/10W	MCR03EZPJ3R3	Chip Resistor	ROHM
$\mathbf{C}_{VREGH}$	2012	2.2µF, X7R ,16V	GCM21BR71C225K	Ceramic	MURATA
Rpgd	1608	100kΩ, 0.5%, 1/10W	MCR03EZPD1003	Chip Resistor	ROHM
R <sub>VOUT</sub>	1608	2.0kΩ, 0.5%, 1/10W	MCR03EZPD2001	Chip Resistor	ROHM
R <sub>100</sub>	-	Short	-	-	-
R <sub>FB1</sub>	1608	43kΩ, 0.5%, 1/10W	MCR03EZPD4302	Chip Resistor	ROHM
R <sub>FB2</sub>	1608	8.2kΩ, 0.5%, 1/10W	MCR03EZPD8201	Chip Resistor	ROHM
R <sub>RT</sub>	1608	7.5kΩ, 0.5%, 1/10W	MCR03EZPD7501	Chip Resistor	ROHM
RCOMP	1608	51kΩ, 0.5%, 1/10W	MCR03EZPD5102	Chip Resistor	ROHM
CCOMP	1608	1000pF, X7R, 50V	GCM188R71H102K	Ceramic	MURATA
L <sub>X</sub>	-	4.7µH	CLF6045NIT-4R7N-D	Inductor	TDK
COUT1	3225	22µF, X7R, 16V	GCM32ER71C226K	Ceramic	MURATA
C <sub>OUT2</sub>	3225	22µF, X7R, 16V	GCM32ER71C226K	Ceramic	MURATA

# **Application Examples1 - continued**

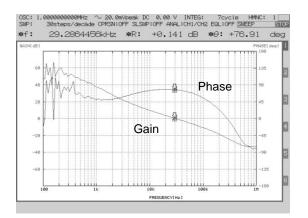


Figure 40. Frequency Characteristics (V<sub>IN</sub>=48V, V<sub>OUT</sub>=5V, I<sub>OUT</sub>=500mA)

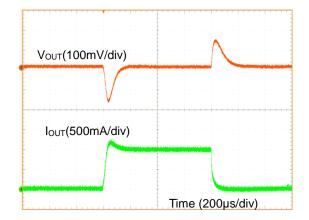


Figure 42. V<sub>IN</sub> Load Response (V<sub>IN</sub>=48V, V<sub>OUT</sub>=5V, I<sub>OUT</sub>=0A  $\leftrightarrow$  1A)

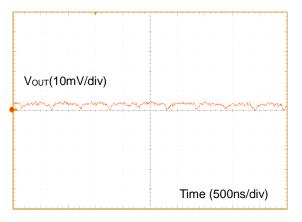


Figure 41. Ripple Voltage (VIN=48V, VOUT=5V, IOUT=500mA)

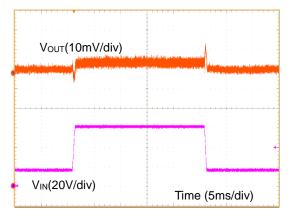


Figure 43. V<sub>IN</sub> Transient Response (V<sub>IN</sub>=16V  $\leftrightarrow$  60V, V<sub>OUT</sub>=5V, I<sub>OUT</sub>=500mA)

# **Application Examples2**

Table 5. Specification Example 2

Parameter	Symbol	Specification Case	
Product Name	IC	BD9V100MUF-C	
Input Voltage	Vin	16V to 60V	
Output Voltage	Vout	3.3V	
Output Ripple Voltage	ΔV <sub>P-P</sub>	20mVp-p	
Output Current	Іоит	0A to 1.0A	
Switching Frequency	f <sub>SW</sub>	2.1MHz	
Operating Temperature	Topr	-40°C to +125°C	

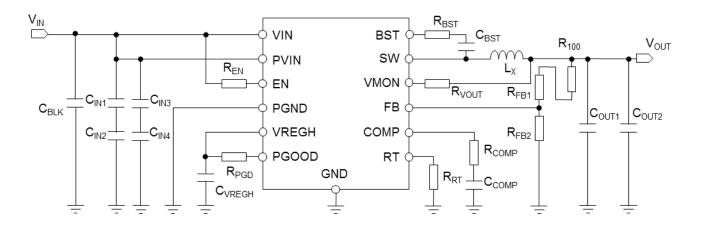


Figure 44. Reference Circuit 2

able 6. Par	ts List 2				
No	Package	Parameters	Part Name (Series)	Туре	Manufacturer
CBLK	-	-	-	-	-
CIN1	3225	4.7µF, X7R, 50V	GCM32ER71H475K	Ceramic	MURATA
C <sub>IN2</sub>	3225	4.7µF, X7R, 50V	GCM32ER71H475K	Ceramic	MURATA
Сімз	1608	0.1µF, X7R, 50V	GCM188R71H104K	Ceramic	MURATA
CIN4	1608	0.1µF, X7R, 50V	GCM188R71H104K	Ceramic	MURATA
CBST	1608	0.022µF, X7R, 50V	GCM188R71H223K	Ceramic	MURATA
RBST	1608	3.3Ω, 5%, 1/10W	MCR03EZPJ3R3	Chip Resistor	ROHM
$C_{VREGH}$	2012	2.2µF, X7R ,16V	GCM21BR71C225K	Ceramic	MURATA
Rpgd	1608	100kΩ, 0.5%, 1/10W	MCR03EZPD1003	Chip Resistor	ROHM
R <sub>VOUT</sub>	1608	2.0kΩ, 0.5%, 1/10W	MCR03EZPD2001	Chip Resistor	ROHM
R100	-	Short	-	-	-
R <sub>FB1</sub>	1608	47kΩ, 0.5%, 1/10W	MCR03EZPD4702	Chip Resistor	ROHM
R <sub>FB2</sub>	1608	15kΩ, 0.5%, 1/10W	MCR03EZPD1502	Chip Resistor	ROHM
R <sub>RT</sub>	1608	7.5kΩ, 0.5%, 1/10W	MCR03EZPD7501	Chip Resistor	ROHM
R <sub>COMP</sub>	1608	75kΩ, 0.5%, 1/10W	MCR03EZPD7502	Chip Resistor	ROHM
Ссомр	1608	560pF, X7R, 50V	GCM188R71H561K	Ceramic	MURATA
Lx	-	4.7µH	CLF6045NIT-4R7N-D	Inductor	TDK
Cout1	3225	22µF, X7R, 16V	GCM32ER71C226K	Ceramic	MURATA
COUT2	3225	22µF, X7R, 16V	GCM32ER71C226K	Ceramic	MURATA

# **Application Examples2 - continued**

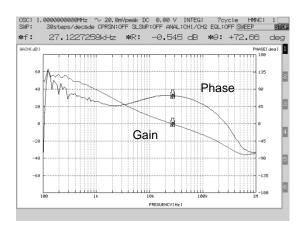


Figure 45. Frequency Characteristics ( $V_{IN}$ =48V,  $V_{OUT}$ =3.3V,  $I_{OUT}$ =500mA)

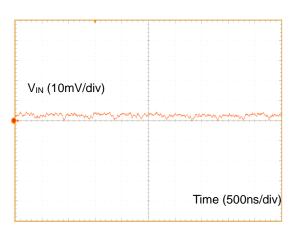
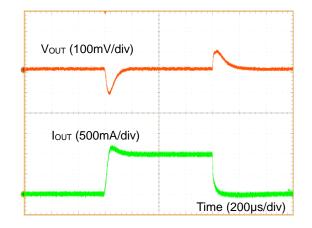
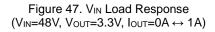


Figure 46. Ripple Voltage (VIN=48V, VOUT=3.3V, IOUT=500mA)





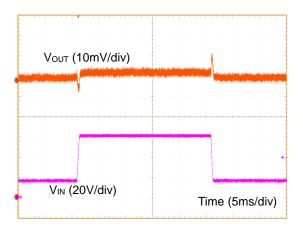


Figure 48. V<sub>IN</sub> Transient Response (V<sub>IN</sub>=16V  $\leftrightarrow$  60V, V<sub>OUT</sub>=3.3V, I<sub>OUT</sub>=500mA)

# Automotive Power Supply Line Circuit

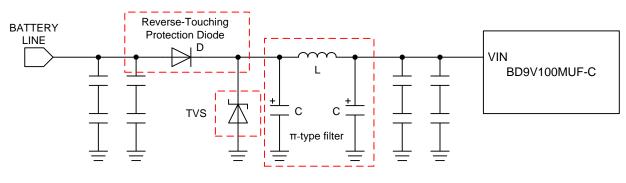


Figure 49. Automotive Power Supply Line Circuit

As a reference, the automotive power supply line circuit example is given in Figure 49.

 $\pi$ -type filter is a third-order LC filter. In general, it is used in combination with decoupling capacitors for high frequency. Large attenuation characteristics can be obtained and thus excellent characteristic as a EMI filter. Devices used for  $\pi$ -type filters should be placed close to each other.

TVS (Transient Voltage Suppressors) is used for primary protection of the automotive power supply line. Since it is necessary to withstand high energy of load dump surge, a general zener diode is insufficient. Recommended device is shown in the following table.

In addition, a reverse polarity protection diode is needed considering if a power supply such as BATTERY is accidentally connected in the opposite direction.

## Table 7. Reference Parts of Automotive Power Supply Line Circuit

Device	Part name (series)	Manufacturer	Device	Part name (series)	Manufacturer
L	CLF series	TDK	TVS	SMB series	Vishay
L	XAL series	Coilcraft	D	S3A to S3M series	Vishay
С	CJ series / CZ series	NICHICON			

## **Recommended Parts Manufacturer List**

Shown below is the list of the recommended parts manufacturers for reference.

Туре	Manufacturer	URL	
Electrolytic Capacitor	NICHICON	www.nichicon-us.com	
Ceramic Capacitor	Murata	www.murata.com	
Inductor	TDK	product.tdk.com	
Inductor	Coilcraft	www.coilcraft.com	
Inductor	SUMIDA	www.sumida.com	
Diode	Vishay	www.vishay.com	
Resistor	ROHM	www.rohm.com	

# **PCB Layout Design**

PCB layout design for DC/DC converter power supply IC is as important as the circuit design. Appropriate layout can avoid various problems caused by power supply circuit. Figure 50-a to 50-c show the current path in a buck converter circuit. The Loop 1 in Figure 50-a is a current path when H-side switch is ON and L-side switch is OFF, the Loop 2 in Figure 50-b is when H-side switch is OFF and L-side switch is ON. The thick line in Figure 50-c shows the difference between Loop1 and Loop2. The current in thick line change sharply each time the switching element H-side and L-side switch change from OFF to ON, and vice versa. These sharp changes induce several harmonics in the waveform. Therefore, the loop area of thick line that is consisted by input capacitor and IC should be as small as possible to minimize noise. For more detail refer to application note of switching regulator series "PCB Layout Techniques of Buck Converter".

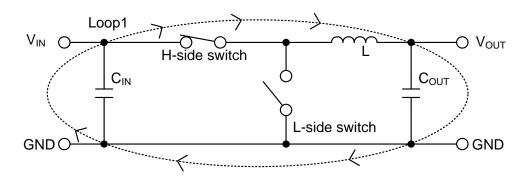


Figure 50-a. Current path when H-side switch = ON, L-side switch = OFF

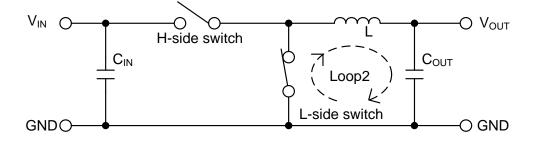


Figure 50-b. Current path when H-side switch = OFF, L-side switch = ON

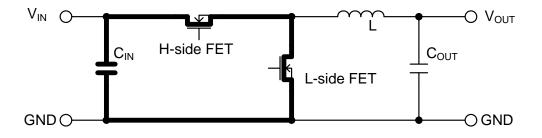


Figure 50-c. Difference of current and critical area in layout

# **PCB Layout Design - continued**

When designing the PCB layout, please pay extra attention to the following points:

- Place input capacitor on the same PCB surface as the IC and as close as possible to the IC's PVIN terminal.
- Switching nodes should be traced as thick and short as possible to the inductor, because they may induce the noise to the other nodes due to AC coupling.
- Please keep the lines connected to FB and COMP away from the SW node as far as possible.
- Please place output capacitor away from input capacitor to avoid harmonics noise from the input.
- R<sub>100</sub> is an option, used for feedback's frequency response measurement.
   By inserting a resistor at R<sub>100</sub>, it is possible to measure the frequency response (phase margin) using a FRA.

However, the resistor will not be used in actual application, please use this resistor pattern in short-circuit mode.

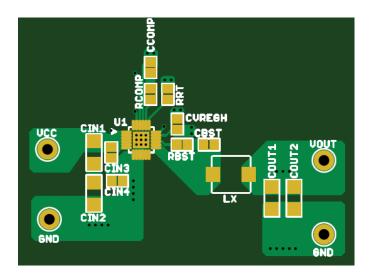


Figure 51. Evaluation Board Layout Example

## **Power Dissipation**

For thermal design, be sure to operate the IC within the following conditions.

(Since the temperatures described hereunder are all guaranteed temperatures, take margin into account.)

- 1. The ambient temperature Ta is to be 125 °C or less.
- 2. The chip junction temperature Tj is to be 150  $^\circ C$  or less.

The chip junction temperature Tj can be considered in the following two patterns:

1. To obtain Tj from the package surface center temperature Tt in actual use

 $Tj = Tt + \psi_{JT} \times W$  [°C]

2. To obtain Tj from the ambient temperature Ta

$$Tj = Ta + \theta_{JA} \times W$$
 [°C]

Where:

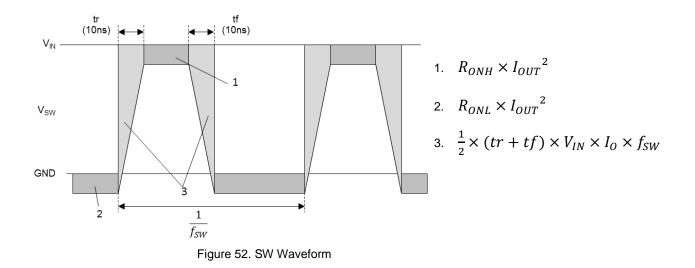
 $\psi_{JT}$  is junction to top characterization parameter (Refer to page 6)  $\theta_{JA}$  is junction to ambient (Refer to page 6)

The heat loss W of the IC can be obtained by the formula shown below:

$$\begin{split} W &= R_{ONH} \times I_{OUT}^2 \times \frac{V_{OUT}}{V_{IN}} + R_{ONL} \times I_{OUT}^2 \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \\ &+ V_{IN} \times I_{CC} + \frac{1}{2} \times (tr + tf) \times V_{IN} \times I_{OUT} \times f_{SW} \ [W] \end{split}$$

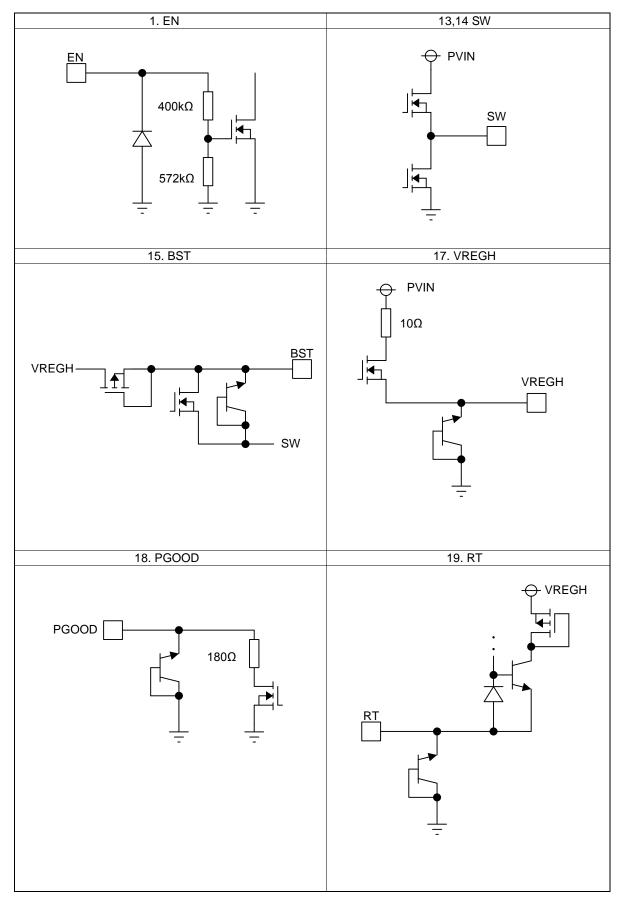
Where:

R <sub>ONH</sub>	is the Top Power NMOS ON Resistance (Refer to page 7) $\left[\Omega\right]$
R <sub>ONL</sub>	is the Bottom Power NMOS ON Resistance (Refer to page 7) $\left[\Omega\right]$
I <sub>OUT</sub>	is the Load Current [A]
V <sub>OUT</sub>	is the Output Voltage [V]
$V_{IN}$	is the Input Voltage [V]
I <sub>CC</sub>	is the Circuit Current (Refer to page 7) [A]
tr	is the Switching Rise Time [s] (Typ:10ns)
tf	is the Switching Fall Time [s] (Typ:10ns)
$f_{SW}$	is the Switching Frequency [Hz]

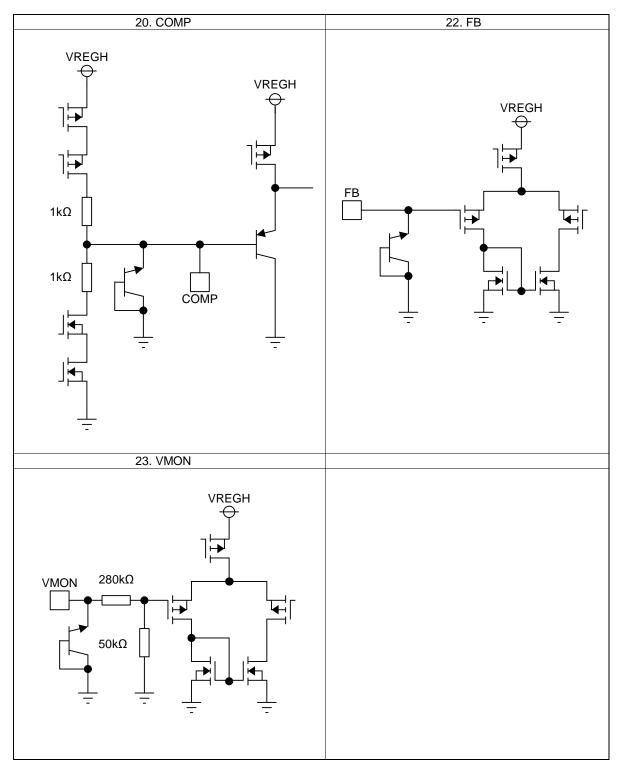


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# I/O Equivalent Circuit



# I/O Equivalent Circuit - continued



## **Operational Notes**

## 1. Reverse Connection of Power Supply

Connecting the power supply in reverse polarity can damage the IC. Take precautions against reverse polarity when connecting the power supply, such as mounting an external diode between the power supply and the IC's power supply pins.

## 2. Power Supply Lines

Design the PCB layout pattern to provide low impedance supply lines. Furthermore, connect a capacitor to ground at all power supply pins. Consider the effect of temperature and aging on the capacitance value when using electrolytic capacitors.

## 3. Ground Voltage

Except for pins the output and the input of which were designed to go below ground, ensure that no pins are at a voltage below that of the ground pin at any time, even during transient condition.

## 4. Ground Wiring Pattern

When using both small-signal and large-current ground traces, the two ground traces should be routed separately but connected to a single ground at the reference point of the application board to avoid fluctuations in the small-signal ground caused by large currents. Also ensure that the ground traces of external components do not cause variations on the ground voltage. The ground lines must be as short and thick as possible to reduce line impedance.

## 5. Recommended Operating Conditions

The function and operation of the IC are guaranteed within the range specified by the recommended operating conditions. The characteristic values are guaranteed only under the conditions of each item specified by the electrical characteristics.

## 6. Inrush Current

When power is first supplied to the IC, it is possible that the internal logic may be unstable and inrush current may flow instantaneously due to the internal powering sequence and delays, especially if the IC has more than one power supply. Therefore, give special consideration to power coupling capacitance, power wiring, width of ground wiring, and routing of connections.

## 7. Operation Under Strong Electromagnetic Field

Operating the IC in the presence of a strong electromagnetic field may cause the IC to malfunction.

## 8. Testing on Application Boards

When testing the IC on an application board, connecting a capacitor directly to a low-impedance output pin may subject the IC to stress. Always discharge capacitors completely after each process or step. The IC's power supply should always be turned off completely before connecting or removing it from the test setup during the inspection process. To prevent damage from static discharge, ground the IC during assembly and use similar precautions during transport and storage.

#### 9. Inter-pin Short and Mounting Errors

Ensure that the direction and position are correct when mounting the IC on the PCB. Incorrect mounting may result in damaging the IC. Avoid nearby pins being shorted to each other especially to ground, power supply and output pin. Inter-pin shorts could be due to many reasons such as metal particles, water droplets (in very humid environment) and unintentional solder bridge deposited in between pins during assembly to name a few.

## 10. Unused Input Pins

Input pins of an IC are often connected to the gate of a MOS transistor. The gate has extremely high impedance and extremely low capacitance. If left unconnected, the electric field from the outside can easily charge it. The small charge acquired in this way is enough to produce a significant effect on the conduction through the transistor and cause unexpected operation of the IC. So unless otherwise specified, unused input pins should be connected to the power supply or ground line.

## **Operational Notes – continued**

#### 11. Regarding the Input Pin of the IC

This monolithic IC contains P+ isolation and P substrate layers between adjacent elements in order to keep them isolated. P-N junctions are formed at the intersection of the P layers with the N layers of other elements, creating a parasitic diode or transistor. For example (refer to figure below):

When GND > Pin A and GND > Pin B, the P-N junction operates as a parasitic diode. When GND > Pin B, the P-N junction operates as a parasitic transistor.

Parasitic diodes inevitably occur in the structure of the IC. The operation of parasitic diodes can result in mutual interference among circuits, operational faults, or physical damage. Therefore, conditions that cause these diodes to operate, such as applying a voltage lower than the GND voltage to an input pin (and thus to the P substrate) should be avoided.

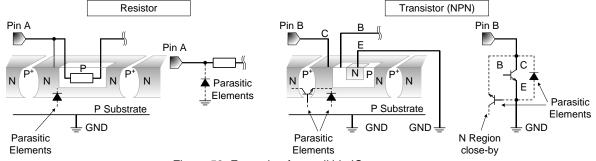


Figure 53. Example of monolithic IC structure

#### 12. Ceramic Capacitor

When using a ceramic capacitor, determine a capacitance value considering the change of capacitance with temperature and the decrease in nominal capacitance due to DC bias and others.

#### 13. Area of Safe Operation (ASO)

Operate the IC such that the output voltage, output current, and the maximum junction temperature rating are all within the Area of Safe Operation (ASO).

#### 14. Thermal Shutdown Circuit(TSD)

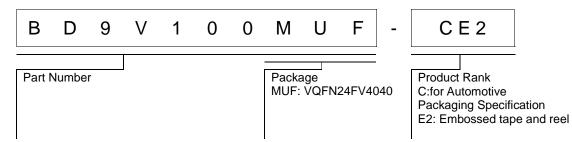
This IC has a built-in thermal shutdown circuit that prevents heat damage to the IC. Normal operation should always be within the IC's maximum junction temperature rating. If however the rating is exceeded for a continued period, the junction temperature (Tj) will rise which will activate the TSD circuit that will turn OFF all output pins. When the Tj falls below the TSD threshold, the circuits are automatically restored to normal operation.

Note that the TSD circuit operates in a situation that exceeds the absolute maximum ratings and therefore, under no circumstances, should the TSD circuit be used in a set design or for any purpose other than protecting the IC from heat damage.

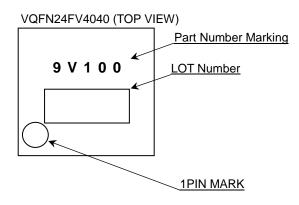
#### 15. Over Current Protection Circuit (OCP)

This IC incorporates an integrated overcurrent protection circuit that is activated when the load is shorted. This protection circuit is effective in preventing damage due to sudden and unexpected incidents. However, the IC should not be used in applications characterized by continuous operation or transitioning of the protection circuit.

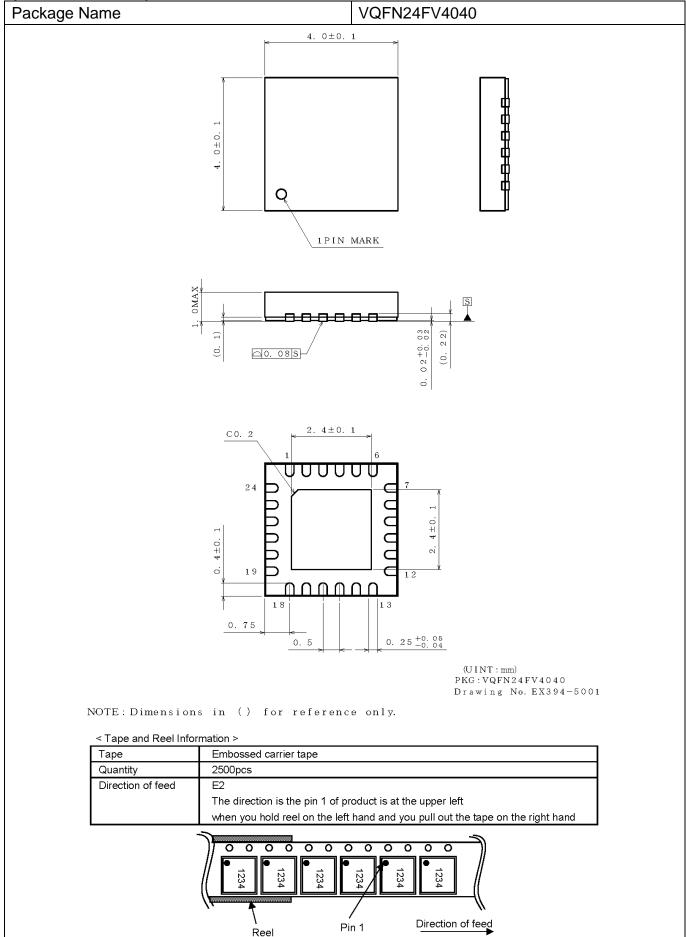
# **Ordering Information**



## **Marking Diagrams**



## **Physical Dimension, Tape and Reel Information**



\*Order quantity needs to be multiple of the minimum quantity.

# **Revision History**

Date	Revision	Changes
01.Jun.2017	001	New Release

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- 7. De-rate Power Dissipation depending on ambient temperature. When used in sealed area, confirm that it is the use in the range that does not exceed the maximum junction temperature.
- 8. Confirm that operation temperature is within the specified range described in the product specification.
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- 1. When a highly active halogenous (chlorine, bromine, etc.) flux is used, the residue of flux may negatively affect product performance and reliability.
- 2. In principle, the reflow soldering method must be used on a surface-mount products, the flow soldering method must be used on a through hole mount products. If the flow soldering method is preferred on a surface-mount products, please consult with the ROHM representative in advance.

For details, please refer to ROHM Mounting specification

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