











TIC12400

SCPS269 - SEPTEMBER 2017

# TIC12400 24-Input Multiple Switch Detection Interface (MSDI) Device With Integrated ADC and Adjustable Wetting Current

### **Features**

- Operates with Supply Voltage (V<sub>S</sub>) from 6.5 V to 35 V with Over-voltage and Under-voltage Warning
- Monitors up 24 Direct Switch Inputs with 10 Inputs Configurable to Monitor Switches Connected to Either Ground or Supply
- Switch Input Withstands 40 V and Reverse Supply Condition Down to -24 V
- 6 Configurable Wetting Current Settings: (0 mA, 1 mA, 2 mA, 5 mA, 10 mA, and 15 mA)
- Integrated 10-bit ADC for Multi-Position Analog Switch Monitoring
- Integrated Comparator with 4 Programmable Threshold for Input Monitoring
- Ultra-low Operating Current in Polling Mode: 68 μA Typical ( $t_{POLL}$  = 64 ms,  $t_{POLL ACT}$  = 128 μs, All 24 Inputs Active, Comparator Mode, All Switches Open)
- Interfaces Directly to MCU Using 3.3 V/5 V Serial Peripheral Interface (SPI) Protocol
- Interrupt Generation to Support Wake-Up Operation on All Inputs
- Integrated Supply and Temperature Sensing
- ±8 kV Contact Discharge ESD Protection on Input Pins per IEC 61000-4-2 With Appropriate External Components
- 38-Pin TSSOP Package

### Applications

- Signal Measurement
- PLC. DCS and PAC
- Instrumentation

## 3 Description

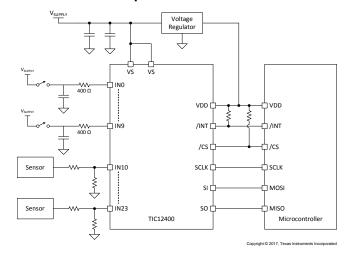
The TIC12400 is an advanced Multiple Switch Detection Interface (MSDI) device designed to detect external switch statuses. The TIC12400 supports 24 direct inputs, with 10 inputs configurable to monitor digital I/O switches. 6 wetting current settings can be programmed for each input to support different application scenarios. The TIC12400 features an integrated 10-bit ADC to monitor multi-position analog switches and a comparator to monitor digital switches independently of the MCU. The device supports wake-up operation on all switch inputs to eliminate the need to keep the MCU active continuously, thus reducing power consumption of the system. The TIC12400 supports 2 modes of operations: continuous and polling mode. In continuous mode, wetting current is supplied continuously. In polling mode, wetting current is turned on periodically to sample the input status based on a programmable timer, thus the system power consumption is significantly reduced. The TIC12400 also offers various fault detection and diagnostic features for improved system robustness.

## Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE	BODY SIZE (NOM)		
TIC12400	TSSOP (38)	9.70 mm x 4.40 mm		

(1) For all available packages, see the orderable addendum at the end of the data sheet.

### Simplified Schematic





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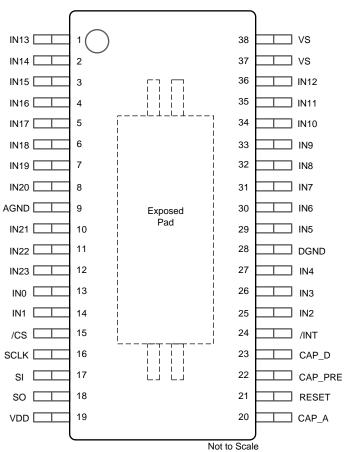
# 4 Revision History

DATE	REVISION	NOTES
September 2017	*	Initial release.

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# 5 Pin Configuration and Functions





## **Pin Functions**

	PIN	TYPE <sup>(1)</sup>	DECODIDATION
NO.	NAME	ITPE	DESCRIPTION
1	IN13	I/O	Ground switch monitoring input with current source
2	IN14	I/O	Ground switch monitoring input with current source
3	IN15	I/O	Ground switch monitoring input with current source
4	IN16	I/O	Ground switch monitoring input with current source
5	IN17	I/O	Ground switch monitoring input with current source
6	IN18	I/O	Ground switch monitoring input with current source
7	IN19	I/O	Ground switch monitoring input with current source
8	IN20	I/O	Ground switch monitoring input with current source
9	AGND	Р	Ground for analog circuitry
10	IN21	I/O	Ground switch monitoring input with current source
11	IN22	I/O	Ground switch monitoring input with current source
12	IN23	I/O	Ground switch monitoring input with current source
13	IN0	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
14	IN1	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.

(1) I = input, O = output, I/O = input and output, P = power.

# Pin Functions (continued)

	PIN	->(1)	
NO.	NAME	TYPE <sup>(1)</sup>	DESCRIPTION
15	CS	I	Active-low input. Chip select from the master for the SPI Interface.
16	SCLK	I	Serial clock output from the master for the SPI Interface
17	SI	I	Serial data input for the SPI Interface.
18	SO	0	Serial data output for the SPI Interface
19	V <sub>DD</sub>	Р	3.3 V to 5.0 V logic supply for the SPI communication. The SPI I/Os are not fail-safe protected: VDD needs to be present during any SPI traffic to avoid excessive leakage currents and corrupted SPI I/O logic levels.
20	CAP_A	I/O	External capacitor connection for the analog LDO. Use capacitance value of 100nF.
21	RESET	I	Keep RESET low for normal operation and drive RESET high and release it to perform a hardware reset of the device. The RESET pin is connected to ground via a $1M\Omega$ pull-down resistor. If not used, the RESET pin shall be grounded to avoid any accidental device reset due to coupled noise onto this pin.
22	CAP_Pre	I/O	External capacitor connection for the pre-regulator. Use capacitance value of 1μF.
23	CAP_D	I/O	External capacitor connection for the digital LDO. Use capacitance value of 100nF.
24	ĪNT	0	Open drain output. Pulled low (internally) upon change of state on the input or occurrence of a special event.
25	IN2	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
26	IN3	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
27	IN4	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
28	DGND	Р	Ground for digital circuitry
29	IN5	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
30	IN6	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
31	IN7	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
32	IN8	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
33	IN9	I/O	Ground/V <sub>SUPPLY</sub> switch monitoring input with configurable current sink or source.
34	IN10	I/O	Ground switch monitoring input with current source
35	IN11	I/O	Ground switch monitoring input with current source
36	IN12	I/O	Ground switch monitoring input with current source
37	Vs	Р	Power supply input pin.
38	Vs	Р	Power supply input pin.
	EP	Р	Exposed Pad. The exposed pad is not electrically connected to AGND or DGND. Connect EP to the board ground to achieve rated thermal and ESD performance.

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## 6 Specifications

### 6.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
Input voltage	$V_S$ , $\overline{INT}$	-0.3	40	V
	V <sub>DD</sub> , SCLK, SI, SO, $\overline{\text{CS}}$ , RESET	-0.3	6	V
Input voltage   IN0- IN23	40	V		
input voltage	CAP_Pre	-0.3	5.5	V
	CAP_A	-0.3	5.5	V
	CAP_D	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	V	
Operating junction	temperature, $T_J$ , $V_S = 18 \text{ V}$	-40	125	°C
Operating junction	temperature, $T_J$ , $V_S = 24 \text{ V}$	-40	95	°C
Storage temperatu	re, T <sub>stg</sub>	-55	155	°C

<sup>(1)</sup> Stresses beyond those listed under Absolute Maximum Ratings may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

## 6.2 ESD Ratings

				VALUE	UNIT
		Liveran hady model (LIDM) nor ANGL/ESDA/JEDEC JS 004(1)	All pins	±2000	
		Human-body model (HBM), per ANSI/ESDA/JEDEC 35-001	Pins IN0-IN23 <sup>(2)</sup>	±4000	
V <sub>(ECD)</sub>	V <sub>(ESD)</sub> Electrostatic discharge	Charged device model (CDM) nor IEDEC enceitigation IECD	All pins	±500	V
*(ESD)	discharge	C101 <sup>(1)</sup>	NSI/ESDA/JEDEC JS-001 <sup>(1)</sup> RII pins ±2000 Pins IN0-IN23 <sup>(2)</sup> ±4000  All pins ±500  Corner pins (pin 1, 19, 20 and 38)  All pins ±750	·	
		an-body model (HBM), per ANSI/ESDA/JEDEC JS-001 <sup>(1)</sup> Pins IN0-IN23 <sup>(2)</sup> All pins  Corner pins (pin 1, 19, 20 and 38)	±8000		

<sup>(1)</sup> JEDEC document JEP155 that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 500-V HBM is possible if necessary if precautions are taken.

### 6.3 Recommended Operating Conditions

over operating free-air temperature range and V<sub>S</sub> = 12 V (unless otherwise noted)

		MIN	NOM MAX	UNIT
V	Power supply voltage, T <sub>A</sub> = -40 °C to 105 °C	6.5	18	V
V <sub>S</sub>	Power supply voltage, T <sub>A</sub> = -40 °C to 85 °C	6.5	24	V
$V_{DD}$	Logic supply voltage	3.0	5.5	V
V <sub>/INT</sub>	INT pin voltage	0	35	V
V <sub>INX</sub>	IN0 to IN23 input voltage	0	35	V
$V_{RESET}$	RESET pin voltage	0	5.5	V
$V_{SPI\_IO}$	SPI input/output logic level	0	$V_{DD}$	V
f <sub>SPI</sub>	SPI communication frequency	20 <sup>(1)</sup>	4M	Hz
T <sub>A</sub>	Operating free-air temperature, VS = 18 V	-40	102	°C
T <sub>A</sub>	Operating free-air temperature, VS = 24 V	-40	85	°C

(1) Lowest frequency characterized.

<sup>(2) ±4</sup>kV rating on pins IN0-IN23 are stressed with respect to GND (with AGND, DGND, and EP tied together).

<sup>(3)</sup> External components: capacitor = 15 nF; resistor = 33  $\Omega$ 

<sup>(4)</sup> ESD generator parameters: storage capacitance = 150 pF or 330pF; discharge resistance = 330  $\Omega$  or 2000  $\Omega$ 

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### 6.4 Thermal Information

		TIC10024-Q1	
	THERMAL METRIC <sup>(1)</sup>	DCP (TSSOP)	UNIT
		38 PINS	
$R_{\theta JA}$	Junction-to-ambient thermal resistance	33.6	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	18.4	°C/W
$R_{\theta JB}$	Junction-to-board thermal resistance	15.2	°C/W
ΨЈТ	Junction-to-top characterization parameter	0.5	°C/W
ΨЈВ	Junction-to-board characterization parameter	15.0	°C/W
R <sub>0</sub> JC(bot)	Junction-to-case (bottom) thermal resistance	1.2	°C/W

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.

## 6.5 Electrical Characteristics

over operating free-air temperature range,  $V_S = 6.5 \text{ V}$  to 35 V, and  $V_{DD} = 3 \text{ V}$  to 5.5 V (unless otherwise noted)

PAI	RAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
POWER SUPPLY							
I <sub>S_CONT</sub>	Continuous mode V <sub>S</sub> power supply current		I <sub>WETT</sub> = 10 mA, all switches open, no active on, no unserviced interrupt		5.6	7	mA
I <sub>S_POLL_COMP_25</sub>	Polling mode V <sub>S</sub>	T <sub>A</sub> = 25°  Polling mode, t <sub>POLL</sub> = 64 ms, t <sub>POLL</sub> _ACT= 128  T <sub>A</sub> = 25°  T <sub>A</sub> = 25°  Polling mode, t <sub>POLL</sub> = 64 ms, t <sub>POLL</sub> = ACT= 128  T <sub>A</sub> = 25°			68	100	μΑ
I <sub>S_POLL_COMP_85</sub>	power supply	T <sub>A</sub> = -40° to 85°C	μs, all switches open, I <sub>WETT</sub> = 10 mA, no		68	110	μΑ
I <sub>S_POLL_COMP</sub>	average current	$T_A = -40^{\circ} \text{ to } 105^{\circ}\text{C}$	unserviced interrupt		68	170	μΑ
I <sub>S_RESET</sub>	Reset mode V <sub>S</sub> power supply current	Reset mode, V <sub>RESE</sub>	$v_{T} = V_{DD}$ . $V_{S} = 12$ V, all switches open, $T_{A} = 25$ °C		12	17	μΑ
I <sub>S_IDLE_25</sub>		TRIGGER bit in CC unserviced interrup	ONFIG register = logic 0, T <sub>A</sub> = 25°C, no t		50	75	μΑ
I <sub>S_IDLE_85</sub>	V <sub>S</sub> power supply average current in idle state	TRIGGER bit in CC unserviced interrup	ONFIG register = logic 0, T <sub>A</sub> = -40°C to 85°C, no t		50	95	μΑ
I <sub>S_IDLE</sub>	10.0 010.0	TRIGGER bit in CC no unserviced inter	ONFIG register = logic 0, T <sub>A</sub> = -40°C to 125°C, rupt		50	145	μΑ
I <sub>DD</sub>	Logic supply current from V <sub>DD</sub>	$SCLK = SI = 0 V, \overline{C}$	SCLK = SI = 0 V, $\overline{CS} = \overline{INT} = V_{DD}$ , no SPI communication			10	μΑ
V <sub>POR_R</sub>	Power on reset		Threshold for rising V <sub>S</sub> from device OFF condition resulting in INT pin assertion and a flagged POR bit in the INT_STAT register			4.5	V
V <sub>POR_F</sub>	(POR) voltage for V <sub>S</sub>	Threshold for falling mode and loss of S	g V <sub>S</sub> from device normal operation to reset SPI communication	1.95		2.8	V
V <sub>OV_R</sub>	Over-voltage (OV) condition for V <sub>S</sub>		V <sub>S</sub> from device normal operation resulting in nd a flagged OV bit in the INT_STAT register	35		40	V
V <sub>OV_HYST</sub>	Over-voltage (OV) condition hysteresis for V <sub>S</sub>			1		3.5	٧
$V_{UV\_R}$	Under-voltage (UV)		V <sub>S</sub> from under-voltage condition resulting in nd a flagged UV bit in the INT_STAT register	3.85		4.5	V
$V_{UV_{F}}$	condition for V <sub>S</sub>		Threshold for falling V <sub>S</sub> from under-votlage condition resulting in INT pin assertion and a flagged UV bit in the INT_STAT register			4.4	V
V <sub>UV_HYST</sub>	Under-voltage (UV) condition hysteresis for V <sub>S</sub> <sup>(1)</sup>			75		275	mV
$V_{DD_F}$		Threshold for falling	g V <sub>DD</sub> resulting in loss of SPI communication	2.5		2.9	V
V <sub>DD_HYST</sub>	Valid V <sub>DD</sub> voltage hysteresis			50		150	mV

(1) Specified by design.



# **Electrical Characteristics (continued)**

over operating free-air temperature range,  $V_S = 6.5 \text{ V}$  to 35 V, and  $V_{DD} = 3 \text{ V}$  to 5.5 V (unless otherwise noted)

PARA	METER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
WETTING CURRENT . VALUE WITH SWITCH		WITCHES, MAXIMU	IM RESISTANCE VALUE WITH SWITCH CLOS	ED ≤ 100Ω ,	MINIMUM	RESISTA	NCE
		1 mA setting		0.84	1	1.14	
	Wetting current	2 mA setting		1.71	2	2.32	
WETT (CSO)	accuracy for CSO	5 mA setting		4.3	5	5.6	
	(switch closed)	10 mA setting		8.4	10	11.4	
		15 mA setting		12.5	15	17	
		1 mA setting	6.5 V ≤ V <sub>S</sub> ≤ 35 V	0.75	1.1	2.05	mA
	Motting ourrent	2 mA setting		1.6	2.2	3.3	
WETT (CSI)	Wetting current accuracy for CSI	5 mA setting		4.3	5.6	7.1	
	(switch closed)	10 mA setting		9.2	11.5	13.4	
		15 mA setting		13.7	16.5	19.2	
	Voltage drop from IN <sub>x</sub>	10 mA setting, R <sub>SW</sub> = 5kΩ				1.7	
V <sub>CSI_DROP_OPEN</sub>	pin to AGND across CSI (switch open)	15 mA setting, R <sub>SW</sub> = 5kΩ	6.5 V ≤ V <sub>S</sub> ≤ 35V			1.7	V
		2mA setting, I <sub>IN</sub> = 1mA				1.2	٧
	Voltage drop from	5mA setting, I <sub>IN</sub> = 1mA or 2mA				1.3	V
V <sub>CSI_DROP_CLOSED</sub>	INx pin to ground across CSI (switch closed)	10mA setting, I <sub>IN</sub> = 1mA, 2mA, or 5mA	N= 6.5 V ≤ V <sub>S</sub> ≤ 35V			1.5	V
		15mA setting, I <sub>IN</sub> = 1mA, 2mA, 5mA, or 10mA				2.1	V
LEAKAGE CURRENT	S						
IN_LEAK_OFF	Leakage current at	$0 \text{ V} \leq V_{INx} \leq V_{S}$ , ch	annel disabled (EN_INx register bit= logic 0)	-4		5.3	
IN_LEAK_OFF_25	input INx when channel is disabled	$0 \text{ V} \le \text{V}_{\text{INx}} \le \text{V}_{\text{S}}$ , ch $\text{T}_{\text{A}} = 25^{\circ}\text{C}$	$0 \text{ V} \le V_{INX} \le V_S$ , channel disabled (EN_INx register bit= logic 0), $T_A = 25^{\circ}\text{C}$			0.5	μA
IN_LEAK_0mA	Leakage current at input INx when wetting current setting is 0mA	$0 \text{ V} \le V_{INx} \le 6 \text{ V}, 6.$	$5 \text{ V} \le \text{V}_{\text{S}} \le 35 \text{ V}$ , $\text{I}_{\text{WETT}}$ setting = 0 mA	-110		110	μА
In_leak_loss_of_gnd	Leakage current at input INx under loss of GND condition	$V_S = 24 \text{ V}, 0 \text{ V} \leq V_I$ = 24 V, $V_{DD}$ shorted	<sub>Nx</sub> ≤ 24 V, all grounds (AGND, DGND, and EP) d to the grounds <sup>(1)</sup>	-5			μA
I <sub>IN_LEAK_LOSS_OF_VS</sub>	Leakage current at input INx under loss of V <sub>S</sub> condition	0 V ≤ V <sub>INx</sub> ≤ 24 V, \	$V_{\rm S}$ shorted to the grounds = 0 V, $V_{\rm DD}$ = 0 V			5	μΑ
LOGIC LEVELS							
	INT output low	I <sub>/INT</sub> = 2 mA				0.35	V
J <sub>/INT_L</sub>	voltage	I <sub>/INT</sub> = 4 mA				0.6	v
/ <sub>SO_L</sub>	SO output low voltage	I <sub>SO</sub> = 2 mA				0.2V <sub>DD</sub>	V
V <sub>so_н</sub>	SO output high voltage	I <sub>SO</sub> = -2 mA		0.8V <sub>DD</sub>			V
V <sub>IN_L</sub>	SI, SCLK, and $\overline{\text{CS}}$ input low voltage					0.3V <sub>DD</sub>	V
V <sub>IN_H</sub>	SI, SCLK, and CS input high voltage			$0.7V_{DD}$			V
V <sub>RESET_L</sub>	RESET input low voltage					0.8	V
V <sub>RESET_H</sub>	RESET input high voltage			1.6			V
R <sub>ESET_25</sub>	RESET pin internal	$V_{RESET} = 0$ to 5.5V,	T <sub>A</sub> = 25°C	0.85	1.25	1.7	МΩ
R <sub>RESET</sub>	pull-down resistor	$V_{RESET} = 0$ to 5.5V,	$T_A = -40^{\circ} \text{ to } 105^{\circ}\text{C}$	0.2		2.1	10177

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# **Electrical Characteristics (continued)**

over operating free-air temperature range,  $V_S = 6.5 \text{ V}$  to 35 V, and  $V_{DD} = 3 \text{ V}$  to 5.5 V (unless otherwise noted)

PAR	AMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
COMPARATOR PAR	AMETERS					
V <sub>TH_ COMP_2V</sub>	Comparator threshold for 2 V	THRES_COMP = 2 V	1.85		2.25	V
V <sub>TH_ COMP_2p7V</sub>	Comparator threshold for 2.7 V	THRES_COMP = 2.7 V	2.4		2.9	V
V <sub>TH_ COMP_3V</sub>	Comparator threshold for 3 V	THRES_COMP = 3 V	2.85		3.3	V
V <sub>TH_ COMP_4V</sub>	Comparator threshold for 4 V	THRES_COMP = 4 V	3.7		4.35	V
		THRES_COMP = 2 V	30	130		
D	Comparator	THRES_COMP = 2.7 V	35	130		kΩ
R <sub>IN, COMP</sub>	equivalent input resistance	THRES_COMP = 3 V	35	105		K12
		THRES_COMP = 4 V	43	95		

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## 6.6 Timing Requirements

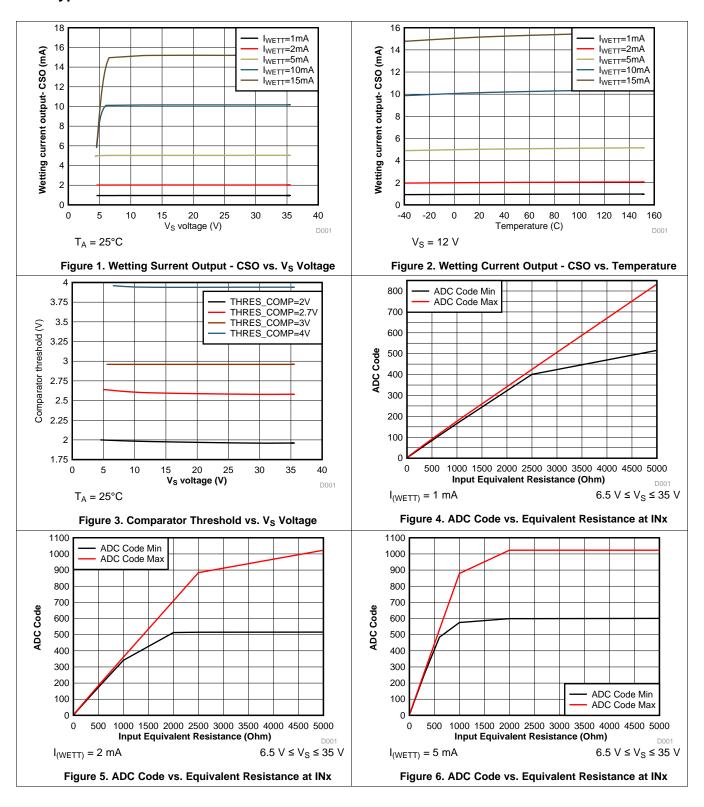
 $V_S$ = 6.5 V to 35 V,  $V_{DD}$ = 3 V to 5.5 V, and 10 pF capacitive load on SO unless otherwise noted; verified by design and characterization

			MIN	NOM	MAX	UNIT	
SWITCH MONITORING, INTERRUPT, STARTUP AND RESET							
t <sub>POLL_ACT</sub>	Polling active time accuracy	Polling mode	-12%		12%		
t <sub>POLL</sub>	Polling time accuracy	Polling mode	-12%		12%		
t <sub>COMP</sub>	Comparator detection time			18		μs	
t <sub>CCP_TRAN</sub>	Transition time between last input sampling and start of cle	ean current		20		μs	
t <sub>CCP_ACT</sub>	Clean current active time		-12%		12%		
t <sub>STARTUP</sub>	Polling startup time		200	300	400	μs	
t <sub>INT_ACTIV</sub>	Active INT assertion duration		1.5	2	2.5	ms	
t <sub>INT_INACT</sub>	INT de-assertion duration during a pending interrupt		3	4	5	ms	
t <sub>INT_IDLE</sub>	Interrupt idle time		80	100	120	μs	
t <sub>RESET</sub>	Time required to keep the RESET pin high to successfully reset the device (no pending interrupt) <sup>(1)</sup>		2			μs	
t <sub>REACT</sub>	Delay between a fault event (OV, UV, TW, or TSD) to a high to low transition on the INT pin	See Figure 10 for OV example.			20	μs	
SPI INTER	FACE						
t <sub>LEAD</sub>	Falling edge of $\overline{\text{CS}}$ to rising edge of SCLK setup time		100			ns	
$t_{LAG}$	Falling edge of SCLK to rising edge of $\overline{\text{CS}}$ setup time		100			ns	
t <sub>SU</sub>	SI to SCLK falling edge setup time		30			ns	
t <sub>HOLD</sub>	SI hold time after falling edge of SCLK		20			ns	
$t_{VALID}$	Time from rising edge of SCLK to valid SO data				70	ns	
t <sub>SO(EN)</sub>	Time from falling edge of $\overline{\text{CS}}$ to SO low-impedance				60	ns	
t <sub>SO(DIS)</sub>	Time from rising edge of $\overline{\text{CS}}$ to SO high-impedance	Loading of 1 $k\Omega$ to GND. See Figure 11.			60	ns	
t <sub>R</sub>	SI, $\overline{\text{CS}}$ , and SCLK signals rise time	•		5	30	ns	
$t_{F}$	SI, $\overline{\text{CS}}$ , and SCLK signals fall time			5	30	ns	
t <sub>INTER_FR</sub> AME	Delay between two SPI communication (CS low) sequences		1.5			μs	
t <sub>CKH</sub>	SCLK High time		120			ns	
t <sub>CKL</sub>	SCLK Low time					ns	
t <sub>INITIATION</sub>	Delay between valid V <sub>DD</sub> voltage and initial SPI communic	ation	45			μs	

<sup>(1)</sup> If there is a pending interrupt (/INT pin asserted low), it can take up to 1ms for the device to complete the reset.

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## 6.7 Typical Characteristics



Product Folder Links: TIC12400

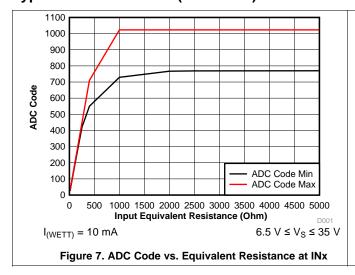
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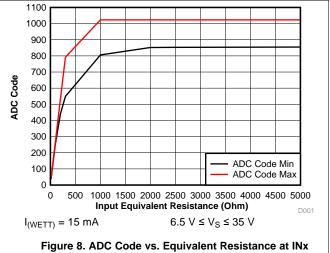
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# **Typical Characteristics (continued)**





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# 7 Parameter Measurement Information

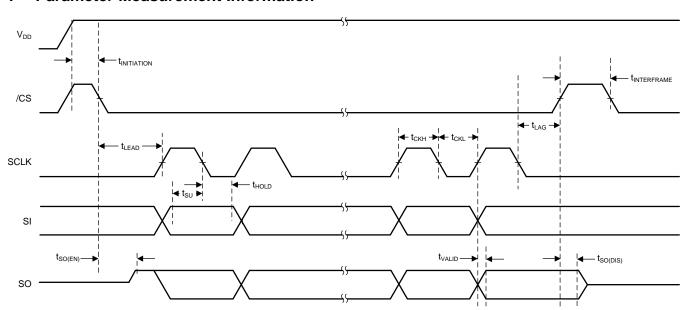


Figure 9. SPI Timing Parameters

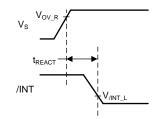


Figure 10.  $t_{REACT}$  Timing Parameters

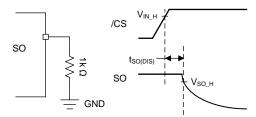


Figure 11. t<sub>SO(DIS)</sub> Timing Parameters

## 8 Detailed Description

#### 8.1 Overview

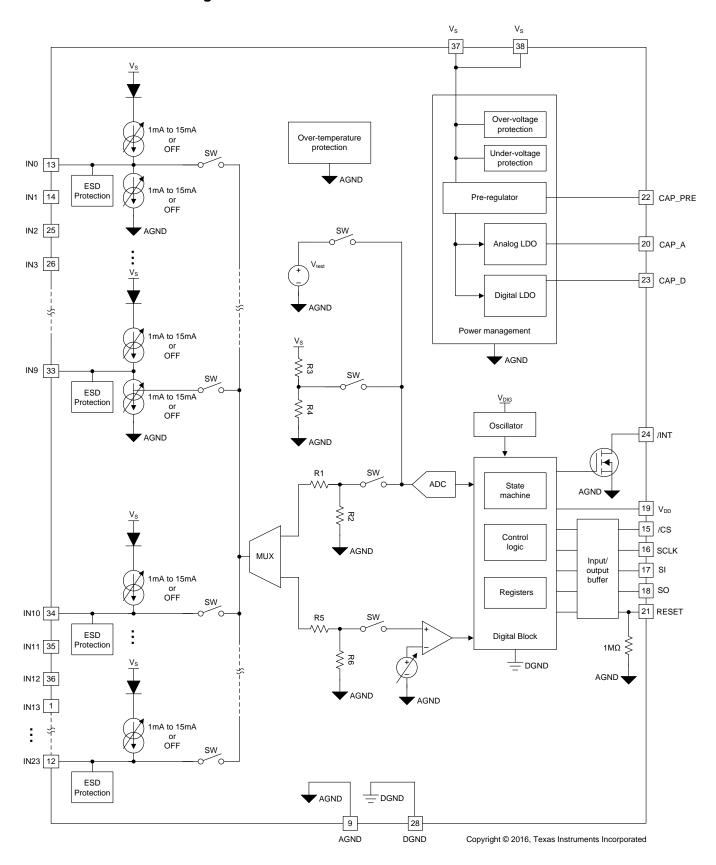
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The TIC12400 is an advanced 24-input Multiple Switch Detection Interface (MSDI) device designed to detect external mechanical switches status in an industrial system by acting as an interface between the switches and the low-voltage microcontroller. The TIC12400 is an integrated solution that replaces many discrete components and provides integrated protection, input serialization, and system wake-up capability.

The device monitors 14 switches to GND and 10 additional switches that can be programmed to be connected to either GND or  $V_{\text{SUPPLY}}$ . It features SPI interface to report individual switch status and provides programmability to control the device operation. The TIC12400 features a 10-bit ADC, which is useful to monitor analog inputs, such as resistor coded switches, that have multiple switching positions. To monitor only digital switches, an integrated comparator can be used instead to monitor the input status. The device has 2 modes of operation: continuous mode and polling mode. The polling mode is a low-power mode that can be activated to reduce current drawn in the system by only turning on the wetting current for a small duty cycle to detect switch status changes. An interrupt is generated upon detection of switch status change and it can be used to wake up the microcontroller to bring the entire system back to operation.

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## 8.2 Functional Block Diagram





### 8.3 Feature Description

### 8.3.1 V<sub>S</sub> Pin

The  $V_S$  supply provides power to the entire chip and the TIC12400 is designed to operate with  $V_S$  ranging from 6.5 V to 35 V.

### 8.3.2 V<sub>DD</sub> Pin

The  $V_{DD}$  supply is used to determine the logic level <u>on</u> the SPI communication interface, source the current for the SO driver, <u>and</u> sets the pull-up voltage for the  $\overline{CS}$  pin. It can also be used as a possible external pull-up supply for the  $\overline{INT}$  pin in addition to the  $V_S$  and it shall be connected to a 3 V to 5.5 V logic supply. Removing  $V_{DD}$  from the device disables SPI communications, but does not reset the register configurations.

#### 8.3.3 Device Initialization

When the device is powered up for the first time, the condition is called Power-On Reset (POR), which sets the registers to their default values and initializes the device state machine. The internal POR controller holds the device in a reset condition until  $V_S$  has reached  $V_{POR\_R}$ , at which the reset condition is released with the device registers and state machine initialized to their default values. After the initialization process is completed, the  $\overline{INT}$  pin is asserted low to notify the microcontroller, and the register bit POR in the  $\overline{INT\_STAT}$  register is asserted to logic 1. The SPI flag bit POR is also asserted at the SPI output (SO).

During device initialization, some factory settings are programmed into the device to allow accurate device operation. The device performs a self-check after the device is programmed to ensure correct settings are loaded. If the self-check returns an error, the CHK\_FAIL bit in the INT\_STAT register will be flagged to logic 1 along with the POR bit. If this very unlikely event occurs, the microcontroller is recommended to initiate software reset (see section Software Reset) to re-initialize the device to allow the correct settings to be re-programmed.

### 8.3.4 Device Trigger

After device initialization, the TIC12400 is ready to be configured. The microcontroller can use SPI commands to program desired settings to the configuration registers. Once the device configuration is completed, the microcontroller is required to set the bit TRIGGER in the CONFIG register to logic 1 in order to activate wetting current and start external switch monitoring.

After the switch monitoring starts, the configuration registers turn into read-only registers (with the exception of the TRIGGER, CRC\_T, and RESET bits in the CONFIG register and all bits in the CCP\_CFG1 register). If at any time the device setting needs to be re-configured, the microcontroller is required to first set the bit TRIGGER in the CONFIG register to logic 0 to stop wetting current and switch monitoring. The microcontroller can then program configuration registers to the desired settings. Once the re-configuration is completed, the microcontroller can set the TRIGGER bit back to logic 1 to re-start switch monitoring.

Note the cyclic redundancy check (CRC) feature stays accessible during switch monitoring, which allows the microcontroller to verify device settings at all time. Refer to section Cyclic Redundancy Check (CRC) for more details of the CRC feature.

#### 8.3.5 Device Reset

There are 3 ways to reset the TIC12400 and re-initialize all registers to their default values:

### 8.3.5.1 $V_S$ Supply POR

The device is turned off and all register contents are lost if the  $V_S$  voltage drops below  $V_{POR\_F}$ . To turn the device back on, the  $V_S$  voltage must be raised back above  $V_{POR\_R}$ , as illustrated in Figure 12. The device then starts the initialization process as described in section Device Initialization .

### **Feature Description (continued)**

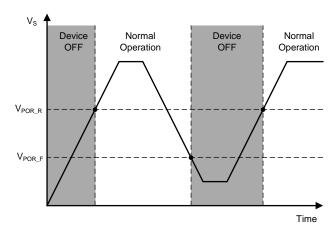


Figure 12. V<sub>S</sub> is Lowered Below The POR threshold, Then Ramped Back Up To Complete A POR Cycle

#### 8.3.5.2 Hardware Reset

Microcontroller can toggle the RESET pin to perform a hardware reset to the device. The RESET pin is internally pulled-down via a  $1M\Omega$  resistor and must be kept low for normal operation. When the RESET pin is toggled high, the device enters the reset state with most of the internal blocks turned off and consumes very little current of  $I_{S\_RESET}$ . Switch monitoring and SPI communications are stopped in the reset state, and all register contents are cleared. When RESET pin is toggled back low, all the registers are set to their default values and the device state machine is re-initialized, similar to a POR event. When the re-initialization process is completed, the  $\overline{INT}$  pin is asserted low, and the interrupt register bit POR and the SPI status flag POR are both asserted to notify the microcontroller that the device has completed the reset process.

Note in order to successfully reset the device, the RESET pin needs to be kept high for a minimum duration of  $t_{RESET}$ . The pin is required to be driven with a stable input (below  $V_{RESET\_L}$  for logic low or above  $V_{RESET\_H}$  for logic H) to prevent the device from accidental reset.

### 8.3.5.3 Software Reset

In addition to hardware reset, the microcontroller can also issue a SPI command to initiate software reset. This is triggered by setting the RESET bit in the register CONFIG to logic 1, which re- initialized the device with all registers set to their default value. When the re-initialization process is completed, the  $\overline{\text{INT}}$  pin is asserted low, and the interrupt register bit POR and the SPI status flag POR are both asserted to notify the microcontroller that the device has completed the reset process.

### 8.3.6 V<sub>S</sub> Under-Voltage (UV) Condition

During normal operation of a typical 12 V system, the  $V_S$  voltage is usually quite stable and stays well above 12 V. However, the  $V_S$  voltage might drops temporarily during certain operations. If the  $V_S$  voltage drops below  $V_{UV\_F}$ , the TIC12400 enters the under-voltage (UV) condition since there is not enough voltage headroom for the device to accurately generate wetting currents. The following describes the behavior of the TIC12400 under UV condition:

- 1. All current sources/sinks de-activate and switch monitoring stops.
- 2. Interrupt is generated by asserting the INT pin low and the bit UV in the interrupt register (INT\_STAT) is flagged to logic 1. The bit UV\_STAT is asserted to logic 1 in the register IN\_STAT\_MISC. The OI SPI flag is asserted during any SPI transactions. The INT pin is released and the interrupt register (INT\_STAT) is cleared on the rising edge of CS provided the interrupt register has been read during the SPI transaction.
- 3. SPI communication stays active, and all register settings say intact without resetting. Previous switch status, if needed, can be retrieved without any interruption.
- 4. The device continues to monitor the V<sub>S</sub> voltage, and the UV condition sustains if the V<sub>S</sub> voltage continues to stay below V<sub>UV\_R</sub>. No further interrupt is generated once cleared.

Note the device resets as described in section VS Supply POR if the V<sub>S</sub> voltage drops below V<sub>POR F</sub>, .

### Feature Description (continued)

When the  $V_S$  voltage rises above  $V_{UV\_R}$ , the  $\overline{INT}$  pin is asserted low to notify the microcontroller that the UV condition no longer exists. The UV bit in the register INT\_STAT is flagged to logic 1 and the bit UV\_STAT bit is de-asserted to logic 0 in the register IN\_STAT\_MISC to reflect the clearance of the UV condition. The device resumes operation using current register settings (regardless of the  $\overline{INT}$  pin and SPI communication status) with polling restarted from the first enabled channel. The Switch State Change (SSC) interrupt is generated at the end of the first polling cycle and the detected switch status becomes the baseline switch status for subsequent polling cycles. The content of the INT\_STAT register, once read by the microcontroller, is cleared, and the INT pin is released afterwards.

The following diagram describes the TIC12400 operation at various different  $V_S$  voltages. If the  $V_S$  voltage stays above  $V_{UV\_F}$  (Case 1), the device stays in normal operation. If the  $V_S$  voltage drops below  $V_{UV\_F}$  but stays above  $V_{POR\_F}$  (Case 2), the device enters the UV condition. If  $V_S$  voltage drops below  $V_{POR\_F}$  (Case 3), the device resets and all register settings are cleared. The microcontroller is then required to re-program all the configuration registers in order to resume normal operation after the  $V_S$  voltage recovers.

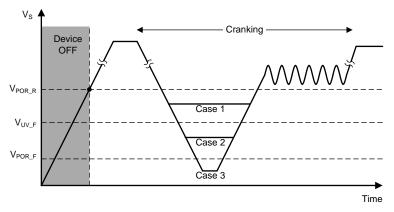


Figure 13. TIC12400 Operation At Various V<sub>S</sub> Voltage Levels

### 8.3.7 V<sub>S</sub> Over-Voltage (OV) Condition

If  $V_S$  voltage rises above  $V_{OV\_R}$ , the TIC12400 enters the over-voltage (OV) condition to prevent damage to internal structures of the device on the  $V_S$  and INx pins. The following describes the behavior of the TIC12400 under OV condition:

- 1. All current sources/sinks de-activate and switch monitoring stops.
- 2. Interrupt is generated by asserting the INT pin low and the bit OV in the interrupt register (INT\_STAT) is flagged to logic 1. The bit OV\_STAT is asserted to logic 1 in the register IN\_STAT\_MISC. The OI SPI flag is asserted during any SPI transactions. The INT pin is released and the interrupt register (INT\_STAT) is cleared on the rising edge of CS provided the interrupt register has been read during the SPI transaction.
- 3. SPI communication stays active, and all register settings say intact without resetting. Previous switch status, if needed, can be retrieved without any interruption.
- 4. The device continues to monitor the  $V_S$  voltage, and the OV condition sustains if the  $V_S$  voltage continues to stays above  $V_{OV\_R}$   $V_{OV\_HYST}$ . No further interrupt is generated once cleared.

When the  $V_S$  voltage drops below  $V_{OV\_R^-}$   $V_{OV\_HYST}$ , the  $\overline{INT}$  pin is asserted low to notify the microcontroller that the over-voltage condition no longer exists. The OV bit in the register INT\_STAT is flagged to logic 1 and the bit OV\_STAT bit is de-asserted to logic 0 in the register IN\_STAT\_MISC to reflect the clearance of the OV condition. The device resumes operation using current register settings (regardless of the  $\overline{INT}$  pin and SPI communication status) with polling restarted from the first enabled channel. The Switch State Change (SSC) interrupt is generated at the end of the first polling cycle and the detected switch status becomes the baseline status for subsequent polling cycles. The content of the INT\_STAT register, once read by the microcontroller, is cleared, and the  $\overline{INT}$  pin is released afterwards.

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## **Feature Description (continued)**

## 8.3.8 Switch inputs Settings

IN0 to IN23 are inputs connected to external mechanical switches. All the inputs can sustain up to 40 V without being damaged. The switch status of each input, whether open or closed, is indicated by the status registers. Table 1 below describe various settings that can be configured for each input. Note some settings are shared between multiple inputs and it is required to first stop device operation by setting the TRIGGER bit low in the register CONFIG before making any configuration changes, as described in Device Trigger.

Table 1. TIC12400 Wetting Current and Threshold Setting Details

		Threshold  Comparator Input Mode  ADC Input Mode			0 (000) (	Supported Switch Type	
Input	Comparator Input Mode			Wetting Current	Current Source (CSO) / Current Sink (CSI)		
IN0	THRES0 to THRES7			WC INO INI	CSO CSI	Switch to GND Switch to VSUPPLY	
IN1	THRES_COMP_IN THRES0 to THRES7  0_IN3 THRES0 to THRES0 to THRES7	WC_IN0_IN1		CSO CSI	Switch to GND Switch to VSUPPLY		
IN2				WC IN2 IN3	CSO CSI	Switch to GND Switch to VSUPPLY	
IN3		THRES0 to THRES7		WC_IIIZ_IIIS	CSO CSI	Switch to GND Switch to VSUPPLY	
IN4		THRES0 to THRES7		WC_IN4	CSO CSI	Switch to GND Switch to VSUPPLY	
IN5	THRES_COMP_IN	THRES0 to THRES7	TUDES COM	WC_IN5	CSO CSI	Switch to GND Switch to VSUPPLY	
IN6	4_IN7	THRES0 to THRES7	THRES_COM	WC_IN6_IN7	CSO CSI	Switch to GND Switch to VSUPPLY	
IN7		THRES0 to THRES7			CSO CSI	Switch to GND Switch to VSUPPLY	
IN8		THRES0 to THRES7		WC_IN8_IN9	CSO CSI	Switch to GND Switch to VSUPPLY	
IN9	THRES_COMP_IN	THRES0 to THRES7			CSO CSI	Switch to GND Switch to VSUPPLY	
IN10	8_IN11	THRES0 to THRES7		WC_IN10	cso	Switch to GND	
IN11		THRES0 to THRES7		WC_IN11	cso	Switch to GND	
IN12	THRES2A THRES2B		WC_IN12_13	CSO	Switch to GND		
IN13	THRES_COMP_IN		IRES2A IRES2B	WC_IN12_13	CSO	Switch to GND	
IN14	12_IN15		IRES2A IRES2B		CSO	Switch to GND	
IN15			IRES2A IRES2B	WO_IN14_13	CSO	Switch to GND	
IN16		THI		WC IN46 47	CSO	Switch to GND	
IN17			IRES2A IRES2B	WC_IN16_17	CSO	Switch to GND	
IN18	THRES_COMP_IN 16_IN19	T⊦	IRES3A IRES3B IRES3C	WC IN18 19	CSO	Switch to GND	
IN19		T⊦	IRES3A IRES3B IRES3C	WO_INTO_18	CSO	Switch to GND	



### **Feature Description (continued)**

Table 1. TIC12400 Wetting Current and Threshold Setting Details (continued)

Input	Threshold			Current Source (CSO) /	Commented Codes	
	Comparator Input Mode	ADC Input Mode	Wetting Current	Current Sink (CSI)	Supported Switch Type	
IN20		THRES3A THRES3B THRES3C	WC INDO 24	CSO	Switch to GND	
IN21		THRES3A THRES3B THRES3C	WC_IN20_21	CSO	Switch to GND	
IN22	THRES_COMP_IN 20_IN23	THRES3A THRES3B THRES3C	WC_IN22	CSO	Switch to GND	
IN23		THRES3A THRES3B THRES3C THRES8 THRES9	WC_IN23	cso	Switch to GND	

### 8.3.8.1 Input Current Source/Sink Selection

Among the 24 inputs, IN10 to IN23 are intended for monitoring only ground-connected switches and are connected to current sources. IN0 to IN9 can be programmed to monitor either ground-connected switches or supply-connected switches by configuring the CS\_SELECT register. The default configuration of the IN0-IN9 inputs after POR is to monitor ground-connected switches (current sources are selected). To set an input to monitor supply-connected switches, set the corresponding bit to logic 1.

### 8.3.8.2 Input Mode Selection

The TIC12400 has a built-in ADC and a comparator that can be used to monitor resistor coded switches or digital switches. Digital switch inputs have only two states, either open or closed, and can be adequately detected by a comparator. Resistor coded switches may have multiple positions that need to be detected, and an ADC is appropriate to monitor the different states. Each input of the TIC12400 can be individually programmed to use either a comparator or an ADC by configuring the appropriate bits in the MODE register depending on the knowledge of the external switch connections. The benefit of using a comparator instead of an ADC to monitor digital switches is its reduced polling time, which translates to overall power saving when the device operates in the low-power polling mode.

Comparator input mode is selected by default for all enabled inputs upon device reset.

### 8.3.8.3 Input Enable Selection

The TIC12400 provides switch status monitoring for up to 24 inputs, but there might be circumstances in which not all inputs need to be constantly monitored. The microcontroller may choose to enable/disable monitoring of certain inputs by configuring the IN\_EN register. Setting the corresponding bit to logic 0 to de-activates the wetting current source/sink and stops switch status monitoring for the input. Disabling monitoring of unused inputs reduce overall power consumption of the device.

All inputs are disabled by default upon device reset.

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#### 8.3.8.4 Thresholds Adjustment

When an input is configured as comparator input mode, the threshold level for interrupt generation of can be programmed by setting the THRES\_COMP register. The threshold level settings can be set to for each individual input groups and each group consist of 4 inputs. Four threshold levels are available: 2V, 2.7V, 3V, and 4V.

When an input is configured as ADC input mode, the threshold level for interrupt generation can be configured, up to 1023 different levels, by setting the THRES\_CFG1 to THRES\_CFG2 registers. One threshold level can be programmed individually for each of the input from IN0 to IN11. Additionally, one common threshold, shared between inputs IN0 to IN11, can be programmed by configuring the THRES\_COM bits in register MATRIX. The common threshold acts independently from the threshold THRES0 to THRES7. Inputs IN12 to IN17 use 2 preset threshold levels (THRES2A and THRES2B). Inputs 18 to 22 use 3 preset threshold levels (THRES3A, THRES3B, THRES3C, THRES8 and THRES9).

When multiple threshold settings are used for ADC inputs, the thresholds levels needs to be configured properly. Use the rules below (see Table 2) when setting up the threshold levels:

Input	Proper Threshold Configuration
IN12 to IN17	THRES2B ≥ THRES2A
IN18 to IN22	THRES3C ≥ THRES3B ≥ THRES3A
IN23	THRES9 ≥ THRES8 ≥ THRES3C ≥ THRES3B ≥ THRES3A

**Table 2. Proper Threshold Configuration For ADC Inputs** 

Caution should be used when setting up the threshold for switches that are connected externally to the supply as there are finite voltage drop (as high as  $V_{CSl\_DROP}$  for 10mA and 15mA settings) across the current sinks. Therefore, even for an open switch, then voltage on the INx pin can be as high as  $V_{CSl\_DROP}$  and the detection threshold shall be configured above it. It shall also be noted that a lower wetting current sink setting might not be stronger enough to pull the INx pin close to ground in the presence of a leaky open external switch, as illustrated in the diagram below (see Figure 14). In this example, the external switch, although in the open state, has large leakage current and can be modelled as an equivalent resistor ( $R_{DIRT}$ ) of  $5k\Omega$ . The 2mA current sink is only able to pull the INx pin voltage down to 2V, even the switch is in the open state.

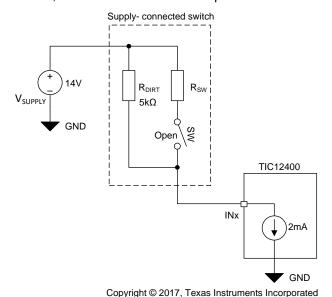


Figure 14. Example showing The Calculation Of The INx Pin Voltage For A Leaky Supply-connected Switch

It is possible to configure an input to ADC input mode, instead of comparator input mode, to monitor single-threshold digital switches. The following programming procedure is recommended under such configuration:

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Table 3. Recommended threshold Configuration When Using An ADC Input To Monitor Digital Switches

Input	Recommended Threshold Configuration			
IN0 to IN11	Configure the desired threshold to one of the settings from THRES0 to THRES7 and map it accordingly			
IN12 to IN17	<ul> <li>Configure the desired threshold to THRES2B</li> <li>Set THRES2A to the same code as THRES2B</li> <li>Disable interrupt generation for THRES2A by configuring the INT_EN_CFG1 or INT_EN_CFG2 register.</li> </ul>			
IN18 to IN22	<ul> <li>Configure the desired threshold to THRES3C</li> <li>Set THRES3A and THRES3B to the same code as THRES3C.</li> <li>Disable interrupt generation for THRES3A and THRES3B by configuring the INT_EN_CFG3 or INT_EN_CFG4 register.</li> </ul>			
IN23	<ul> <li>Configure the desired threshold to THRES9</li> <li>Set THRES3A, THRES3B, THRES3C, and THRES8 to the same code as THRES9.</li> <li>Disable interrupt generation for THRES3A, THRES3B, THRES3C, and THRES8 by configuring the INT_EN_CFG4 register.</li> </ul>			

#### 8.3.8.5 Wetting Current Configuration

There are 6 different wetting current settings (0mA, 1mA, 2mA, 5mA, 10mA, and 15mA) that can be programmed by configuring the WC CFG0 and WC CFG1 registers. 0mA is selected by default upon device reset.

To monitor resistor coded switches, a lower wetting current setting (1 mA, 2 mA, or 5 mA) is generally desirable to get the resolution needed to resolve different input voltages while keeping them within the ADC full-scale range (0 V to 6 V). Higher wetting current settings (10mA and 15mA) are useful to clean switch contact oxidation that may form on the surface of an open switch contact. If switch contact cleaning is required for resistor coded switches, the clean current polling (CCP) feature can be activated to generate short cleaning pulses periodically using higher wetting current settings at the end of every polling cycle.

The accuracy of the wetting current has stronger dependency on the V<sub>S</sub> voltage when V<sub>S</sub> voltage is low. The lower the V<sub>S</sub> voltage falls, the more deviation on the wetting currents from their nominal values. Refer to I<sub>WETT</sub> (CSO) and I<sub>WETT</sub> (CSI) specifications for more details.

### 8.3.9 Interrupt Generation and INT Assertion

The INT pin is an active-low, open-drain output that asserts low when an event (switch input state change, temperature warning, over-voltage shutdown...etc) is detected by the TIC12400. An external pull-up resistor to  $V_{DD}$  is needed on the  $\overline{INT}$  pin (see Figure 15). If  $\underline{V_{DD}}$  supply is absent, the  $\overline{INT}$  output is functional provided that it is pulled up to a different supply voltage. The  $\overline{INT}$  pin can tolerate up to 40 V but is recommended to be kept below 35V for normal operation.

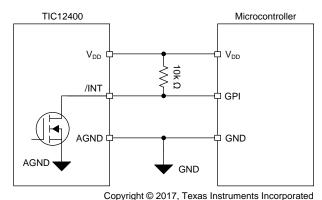


Figure 15. INT Connection Example #1

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### 8.3.9.1 INT Pin Assertion Scheme

TIC12400 supports two configurable schemes for  $\overline{\text{INT}}$  assertion: static and dynamic. The scheme can be adjusted by configuring the INT\_CONFIG bit in the CONFIG register.

If the static  $\overline{\text{INT}}$  assertion scheme is used (INT\_CONFIG = 0 in the CONFIG register), the  $\overline{\text{INT}}$  pin is asserted low upon occurrence of an event. The  $\overline{\text{INT}}$  pin is released on the rising edge of  $\overline{\text{CS}}$  only if a READ command has been issued to read the INT\_STAT register while  $\overline{\text{CS}}$  is low, otherwise the  $\overline{\text{INT}}$  will be kept low indefinitely. The content of the INT\_STAT interrupt register is latched on the first rising edge of SCLK after  $\overline{\text{CS}}$  goes low for every SPI transaction, and the content is cleared upon a READ command issued to the INT\_STAT register, as illustrated in Figure 16.

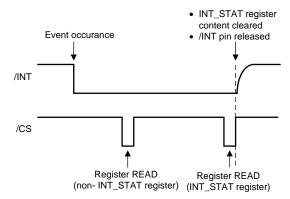


Figure 16. Static INT Assertion Scheme

In some system implementation, an edge-triggered based microcontroller might potentially miss the  $\overline{\text{INT}}$  assertion if it is configured to the static scheme, especially when the microcontroller is in the process of waking up. To prevent missed  $\overline{\text{INT}}$  assertion and improve robustness of the interrupt behavior, the TIC12400 provides the option to use the dynamic assertion scheme for the  $\overline{\text{INT}}$  pin. When the dynamic scheme is used (INT\_CONFIG= 1 in the CONFIG register), the  $\overline{\text{INT}}$  pin is asserted low for a duration of  $t_{\text{INT\_ACTIVE}}$ , and is de-asserted back to high if the INT\_STAT register has not been read after  $t_{\text{INT\_INACTIVE}}$  has elapsed. The  $\overline{\text{INT}}$  is kept high for a duration of  $t_{\text{INT\_INACTIVE}}$ , and is re-asserted low after  $t_{\text{INT\_INACTIVE}}$  has elapsed. The  $\overline{\text{INT}}$  pin continues to toggle until the  $\overline{\text{INT\_STAT}}$  register is read.

If the INT\_STAT register is read when INT pin is asserted low, the INT pin is released on the READ command's CS rising edge and the content of the INT\_STAT register is also cleared, as shown in Figure 17. If the INT\_STAT register is read when INT pin is de-asserted, the content of the INT\_STAT register is cleared on the READ command's CS rising edge, and the INT pin is not re-asserted back low, as shown in Figure 18.

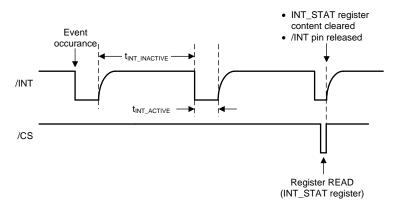


Figure 17. INT Assertion Scheme With INT\_STAT Register Read During t<sub>INT\_ACTIVE</sub>

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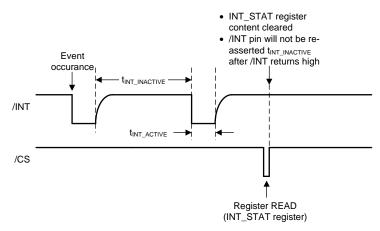


Figure 18. Dynamic INT Assertion Scheme With INT\_STAT Register Read During t<sub>INT INACTIVE</sub>

The static  $\overline{\text{INT}}$  assertion scheme is selected by default upon device reset. The  $\overline{\text{INT}}$  pin assertion scheme can only be changed when bit TRIGGER is logic 0 in the CONFIG register.

## 8.3.9.2 Interrupt Idle Time (t<sub>INT IDLE</sub>) Time

Interrupt idle time (t<sub>INT IDLE</sub>) is implemented in TIC12400 to:

- Allow the INT pin enough time to be pulled back high by the external pull-up resistor to allow the next assertion to be detectable by an edge-triggered microcontroller.
- Minimize the chance of glitching on the INT pin if back-to-back events occur.

When there is a pending interrupt event and the interrupt event is not masked,  $t_{\text{INT\_IDLE}}$  is applied after the READ command is issued to the INT\_STAT register. If another event occurs during the interrupt idle time, the INT\_STAT register content is updated instantly, but the INT pin is not asserted low until  $t_{\text{INT\_IDLE}}$  has elapsed. If another READ command is issued to the INT\_STAT register during  $t_{\text{INT\_IDLE}}$ , the INT\_STAT register content is cleared immediately, but the INT pin is not re-asserted back low after  $t_{\text{INT\_IDLE}}$  has elapsed. An example of the interrupt idle time is given below to illustrate the INT pin behavior under the static /INT assertion schemes:

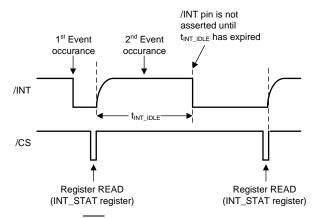


Figure 19. INT Assertion Scheme With t<sub>INT IDLE</sub>

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### 8.3.9.3 Microcontroller Wake-Up

When used together with external PNP transistors, the  $\overline{\text{INT}}$  pin could also be used for wake-up purpose to activate a voltage regulator via its inhibit inputs (see Figure 20). This is especially useful for waking up a microcontroller in sleep mode. Before the wake-up, the  $V_{DD}$  could be unavailable to the TIC12400 and the  $\overline{\text{INT}}$  pin can be pulled up externally to the  $V_S$  voltage. When an event (switch status change, temperature warning, or OV...etc) takes place, the  $\overline{\text{INT}}$  pin will be asserted low to activate the voltage regulator, which in turn activates the microcontroller to enable the communication between the microcontroller and the TIC12400. The event information is stored inside the device interrupt register (INT\_STAT) for the microcontrollers retrieval when the communication is reestablished.

The wake-up implementation is applicable only when the device is configured to use the static  $\overline{\text{INT}}$  assertion scheme.

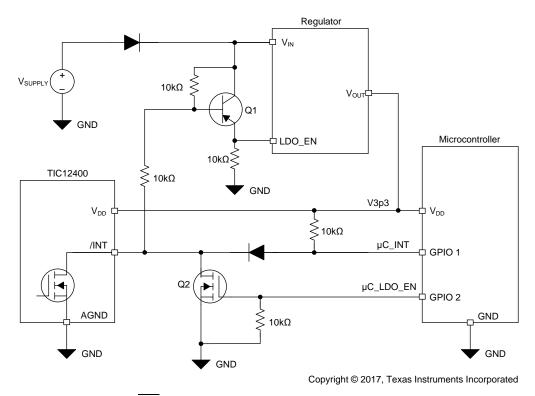


Figure 20. INT Connection to Support Microcontroller Wake-Up

### 8.3.9.4 Interrupt Enable/disable And Interrupt generation Conditions

Each switch input can be programmed to enable or disable interrupt generation upon status change by configuring registers INT\_EN\_COMP1 to INT\_EN\_COMP2 (for comparator inputs) and INT\_EN\_CFG1 to INT\_EN\_CFG4 (for ADC inputs). Interrupt generation condition can be adjusted for THRES\_COM (for IN0-IN11) by adjusting the IN\_COM\_EN bit in the MATRIX register.

The abovementioned registers can also be used to control interrupt generation condition based on the following settings:

- Rising edge: an interrupt is generated if the current input measurement is above the corresponding threshold and the previous measurement was below.
- 2. **Falling edge:** an interrupt is generated if the current input measurement is below the corresponding threshold and the previous measurement was above.
- 3. Both edges: changes of the input voltage in either direction results in an interrupt generation.

Note interrupt generation from switch status change is disabled for all inputs by default upon device reset.

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#### 8.3.9.5 Detection Filter

When monitoring the switch input status, an detection filter can be configured by setting the DET\_FILTER bits in the CONFIG register to generate switch status change (SSC) interrupt only if the same input status (w.r.t the threshold) is sampled consecutively. This detection filter can be useful to debounce inputs during switch toggle event. Four different filtering schemes are available:

- 1. Generate an SSC interrupt if the voltage level at an input crossed its threshold
- 2. Generate an SSC interrupt if the voltage level at an input crossed its threshold and the status is stable (w.r.t. the threshold) for at least 2 consecutive polling cycles
- 3. Generate an SSC interrupt if the voltage level at an input crossed its threshold and the status is stable (w.r.t. the threshold) for at least 3 consecutive polling cycles
- 4. Generate an SSC interrupt if the voltage level at an input crossed its threshold and the status is stable (w.r.t. the threshold) for at least 4 consecutive polling cycles

The default value of switch status is stored internally after the 1st detection cycle, even if detection filter (by configure the DET\_FILTER in the CONFIG register) is used. An example is illustrated below with the assumption that DET\_FILTER in register CONFIG is set to 11 (SSC interrupt generated if the input crosses threshold and the status is stable w.r.t. the threshold for at least 4 consecutive detection cycles). Assume switch status change is detected in the 3rd detection cycle and stays the same for the next 3 cycles.

Detection cycle	1	2	3	4	5	6
Event	Default Switch status stored	_	Switch status change detected	_	_	

The detection filter applies to all enabled inputs regardless its input modes (ADC or comparator) selection. The detection filter counter is reset to 0 when the TRIGGER bit in the CONFIG register is de-asserted to logic 0. Upon device reset, the default setting for the detection filter is set to generating an SSC interrupt at every threshold crossing.

Note the detection filter does not apply to the common threshold THRES\_COM.

#### 8.3.10 Temperature Monitor

With multiple switch inputs closed and high wetting current setting enabled, considerable power could be dissipated by the device and raise the device temperature. TIC12400 has integrated temperature monitoring and protection circuitry to prevent permanent device damage resulted from device overheating. Two types of temperature protection mechanisms are integrated in the device: Temperature Warning (TW) and Temperature Shutdown (TSD). The triggering temperatures and hysteresis are specified in Table 4 below:

Table 4. Temperature Monitoring Characteristics of TIC12400

Parameter	Min	Тур	Max	Unit
Temperature warning trigger temperature (T <sub>TW</sub> )	130	140	155	°C
Temperature shutdown trigger temperature (T <sub>TSD</sub> )	150	160	175	°C
Temperature hysteresis (T <sub>HYS</sub> ) for T <sub>TW</sub> and T <sub>TSD</sub>		15		°C

#### 8.3.10.1 Temperature Warning (TW)

When the device temperature goes above the temperature warning trigger temperature ( $T_{TW}$ ), the TIC12400 performs the following operations:

- 1. Generate an interrupt by asserting the  $\overline{\text{INT}}$  pin low and flag the TW bit in INT\_STAT register to logic 1. The TEMP bit in the SPI flag is also flagged to logic 1 for all SPI transactions.
- 2. The TW\_STAT bit of the IN\_STAT\_MISC register is flagged to logic 1.
- 3. If the TW\_CUR\_DIS\_CSO or TW\_CUR\_DIS\_CSO bit in CONFIG register set to logic 0 (default), the wetting current is adjusted down to 2 mA for 10 mA or 15 mA settings. The wetting current stays at its pre-configured value if 0 mA, 1 mA, 2 mA, or 5 mA setting is used.
- 4. Maintain the low wetting current as long as the device junction temperature stays above T<sub>TW</sub> T<sub>HYS</sub>.

The  $\overline{\text{INT}}$  pin is released and the INT\_STAT register content is cleared on the rising edge of  $\overline{\text{CS}}$  provided the INT\_STAT register has been read during  $\overline{\text{CS}}$  low. The TIC12400 continues to monitor the temperature, but does not issue further interrupts if the temperature continues to stay above  $T_{\text{TW}}$ . The status bit TW\_STAT in register IN\_STAT\_MISC continues to stay at logic 1 as long as the temperature warning condition exists.

If desired, the reduction of wetting current down to 2 mA setting (from 10 mA or 15 mA) can be disabled by setting the  $\underline{TW}$ \_CUR\_DIS\_CSO or  $\underline{TW}$ \_CUR\_DIS\_CSI bit in the CONFIG register to 1. The interrupt is still generated (INT asserted low and INT\_STAT interrupt register content updated) when the temperature warning event occurs but the wetting current is not reduced. This setting applies to both the polling and continuous mode operation. Note if the feature is enabled, switch detection result might be impacted upon  $T_{TW}$  event if the wetting current is reduced to 2mA from 10mA or 15mA.

When the temperature drops below  $T_{TW}$  -  $T_{HYS}$ , the  $\overline{INT}$  pin is asserted low (if released previously) to notify the microcontroller that the temperature warning condition no longer exists. The TW bit of the interrupt register INT\_STAT is flagged logic 1. The TW\_STAT bit in the IN\_STAT\_MISC register is de-asserted back to logic 0. The device resumes operation using the current programmed settings (regardless of the  $\overline{INT}$  and  $\overline{CS}$  status).

### 8.3.10.2 Temperature Shutdown (TSD)

After the device enters TW condition, if the junction temperature continues to rise and goes above the temperature shutdown threshold ( $T_{TSD}$ ), the TIC12400 enters the Temperature Shutdown (TSD) condition and performs the following operations:

- 1. Opens all the switches connected to the current sources/sinks to prevent any further heating due to excessive current flow.
- 2. Generate an interrupt by asserting the  $\overline{\text{INT}}$  pin (if not already asserted) low and flag the bit TSD in the INT STAT register to logic 1. The TEMP bit in the SPI flag is also flagged to logic 1 for all SPI transactions.
- The TSD\_STAT bit of the IN\_STAT\_MISC register is flagged to logic 1. The TW\_STAT bit also stays at logic 1.
- 4. SPI communication stays on, and all register settings say intact without resetting. Previous switch status, if needed, can be retrieved without any interruption.
- 5. Maintain the setting as long as the junction temperature stays above T<sub>TSD</sub> T<sub>HVS</sub>.

The  $\overline{\text{INT}}$  pin is released and the INT\_STAT register content is cleared on the rising edge of  $\overline{\text{CS}}$  provided the INT\_STAT register has been read during  $\overline{\text{CS}}$  low. The TIC12400 continues to monitor the temperature, but does not issue further interrupts if the temperature continues to stay above T<sub>TSD</sub>- T<sub>HYS</sub>. The status bit TSD\_STAT in register IN\_STAT\_MISC continues to stay at logic 1 as long as the temperature shutdown condition exists.

When the temperature drops below  $T_{TSD}$  -  $T_{HYS}$ , the  $\overline{INT}$  pin is asserted low (if released previously) to notify the microcontroller that the temperature shutdown condition no longer exists. The TSD bit of the interrupt register INT\_STAT is flagged logic 1. In the IN\_STAT\_MISC register, the TSD\_STAT bit is de-asserted back to logic 0, while the TW\_STAT bit stays at logic 1. The device resumes operation using the wetting current setting described in section Temperature Warning if the temperature stays above  $T_{TW}$  -  $T_{HYS}$ . Note the polling restarts from the first enabled channel and the SSC interrupt is generated at the end of the first polling cycle. The detected switch status from the first polling cycle becomes the default switch status for subsequent polling.

### 8.3.11 Parity Check And Parity Generation

The TIC12400 uses parity bit check to ensure error-free data transmission from/to the SPI master.

The device uses odd parity, for which the parity bit is set so that the total number of ones in the transmitted data on SO (including the parity bit) is an odd number (that is, Bit $0 \oplus$  Bit $1 \oplus$  .... $\oplus$  Bit $30 \oplus$  Bit $31 \oplus$  Parity = 1).

The device also does odd parity check after receiving data on SI from the SPI master. If the total number of ones in the received data (including the parity bit) is an even number, the received data is discarded. The INT will be asserted low and the PRTY\_FAIL bit in the interrupt register (INT\_STAT) is flagged to logic 1 to notify the host that transmission error occurred. The PRTY\_FAIL flag is also asserted during SPI communications.

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## 8.3.12 Cyclic Redundancy Check (CRC)

The TIC12400 includes a CRC module to support redundancy checks on the configuration registers to ensure the integrity of data. The CRC calculation is based on the ITU-T X.25 implementation, and the CRC polynomial (0x1021) used is popularly known as CRC-CCITT-16 since it was initially proposed by the ITU-T (formerly CCITT) committee. The CRC calculation rule is defined as:

Table 3. CNG Calculation rule						
CRC Rule Value						
CRC result width	16 bits					
Polynomial	x^16+ x^12+ x^5+1 (1021h)					
Initial (seed) value	FFFFh					
Input data reflected	No					
Result data reflected	No					
XOR value	0000h					

Table 5 CRC calculation rule

The CRC calculation is done on all the configuration registers starting from register CONFIG and ending at register MODE. The device substitutes a "zero" for each reserved configuration register bit during the CRC calculation. The CRC calculation can be triggered by asserting the CRC\_T bit in the CONFIG register. Once completed, the CRC\_CALC interrupt bit in the INT\_STAT register is asserted and an interrupt is issued, The 16-bit CRC calculation result is stored in the register CRC. This interrupt can be disabled by de-asserting the CRC\_CALC\_EN bit in the INT\_EN\_CFG0 register. It is important to avoid writing data to the configuration registers when the device is undergoing CRC calculations to prevent generation of any false calculation result.

The diagram below shows the block diagram of the CRC module. The module consists of 16 shift-registers and 3 exclusive-OR gates. The registers start with 1111-1111-1111 (or FFFFh) and the module performs XOR action and shifts its content until the last bit of the register string is used. The final register's content after the last data bit is the calculated CRC value of the data set and the content is stored in the CRC register.

Note the CRC\_T bit is self-clearing after CRC calculation is completed. Logic 1 is used for CRC\_T bit during CRC calculation.

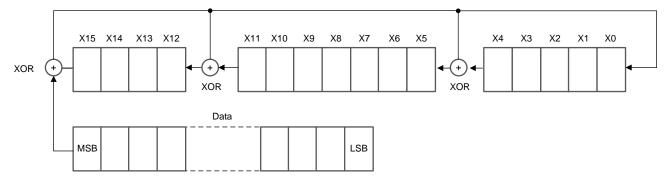


Figure 21. CCITT-16 CRC Module Block Diagram

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#### 8.4 Device Functional Modes

The TIC12400 has 2 modes of operation: continuous mode, and polling mode. The following sections describe the two operation modes in details, as well as some of the advanced features that could be activated during normal operations.

#### 8.4.1 Continuous Mode

In continuous mode, wetting current is continuously applied to each enabled input channel, and the status of each channel is sampled sequentially (starting from the IN0 to IN23). The TIC12400 monitors enabled inputs and issues an interrupt (if enabled) if switch status change event is detected. The wetting current setting for each input can be individually adjusted by configuring the WC\_CFG0 and WC\_CFG1 to the 0 mA, 1 mA, 2 mA, 5 mA, 10 mA, or 15 mA setting. Each input is monitored by either a comparator or an ADC depending on the setting of the input mode in the register MODE.

Figure 22 below illustrates an example of the timing diagram of the detection sequence in continuous mode. After the TRIGGER bit in register CONFIG is set to logic 1, it takes t<sub>STARTUP</sub> to activate the wetting current for all enabled inputs. The wetting currents stay on continuously, while each input is routed to the ADC/comparator for sampling in a sequential fashion. After conversion/comparison is done for an input, the switch status (below or above detection threshold) is stored in registers (IN\_STAT\_COMP for comparator inputs and IN\_STAT\_ADC0 to IN\_STAT\_ADC1 for ADC inputs) to be used as the default state for subsequent detection cycles. The digital values (if the input is configured as ADC input mode) are stored inside the registers ANA\_STAT0 to ANA\_STAT11. After the end of the first polling cycle, the INT pin is asserted low to notify the microcontroller that the default switch status is ready to be read. The SSC bit in INT\_STAT register and the SPI status flag SSC are also asserted to logic 1. The polling cycle time (t<sub>POLL</sub>) determines how frequently each input is sampled and can be configured in the register CONFIG.

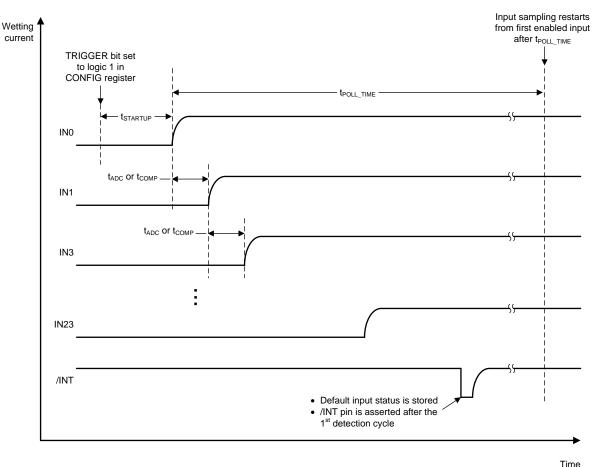


Figure 22. An Example Of The Detection Sequence In continuous Mode

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# **Device Functional Modes (continued)**

The INT\_STAT register is cleared and INT pin de-asserted if a SPI READ commanded is issued to the register. Note the interrupt is always generated after the 1st detection cycle (after the TRIGGER bit in register CONFIG is set to logic 1). In subsequent detection cycles, the interrupt is generated only if switch status change is detected.

No wetting current is applied to the inputs configured to the 0mA setting, although some biasing current (as specified by I<sub>IN\_LEAK\_0mA</sub>) may still flow in and out of the input. Threshold crossing monitoring is still performed for the input using the defined threshold(s). The 0mA setting is useful to utilize the integrated ADC or comparator to measure applied voltage on a specific input without getting affected by the device wetting current.

### 8.4.2 Polling Mode

The polling mode can be activated to reduce current drawn to reduce heat dissipation. Unlike in the continuous mode, the current sources/sinks do not stay on continuously in the polling mode. Instead, they are turned on/off sequentially from IN0 to IN23 and cycled through each individual input channel. The microcontroller can be put to sleep to reduce overall system power. If a switch status change (SSC) is detected by the TIC12400, the INT pin (if enabled for the input channel) is asserted low (and the SSC bit in INT\_STAT register and the SPI status flag SSC are also asserted to logic 1). The INT assertion can be used to wake up the system regulator, which in turn wakes up the microcontroller as described in section Microcontroller Wake-Up. The microcontroller can then use SPI communication to read the switch status information.

The polling is activated when the TRIGGER bit in the CONFIG register is set to logic 1. There are 2 different polling schemes that can be configured in TIC12400: standard polling and matrix polling.

### 8.4.2.1 Standard Polling

In standard polling mode, wetting current is applied to each input for a pre-programmed polling active time set by the POLL\_ACT\_TIME bits in the CONFIG register between 64us and 2048 us. At the end of the wetting current application, the input voltage is sampled by the comparator (if input is configured as comparator input mode) or the ADC (if input is configured as ADC input mode). Each input is cycled through in sequential order from IN0 to IN23. Sampling is repeated at a frequency set by the POLL\_TIME bits in the CONFIG register from 2ms to 4096ms. Wetting currents are applied to closed switches only during the polling active time; hence the overall system current consumption can be greatly reduced.

Similar to continuous mode, after the first polling cycle, the switch status of each input (below or above detection threshold) is stored internally in registers (IN\_STAT\_COMP for comparator inputs and IN\_STAT\_ADC0 to IN\_STAT\_ADC1 for ADC inputs) to be used as the default state for subsequent polling cycles. The digital values (if the input is configured as ADC input mode) are stored inside the registers ANA\_STAT0 toANA\_STAT11. The INT pin is asserted low to notify the microcontroller that the default switch status is ready to be read. The SSC bit in INT\_STAT register and the SPI status flag SSC are also asserted to logic 1. The INT\_STAT register is cleared and /INT pin de-asserted if a SPI READ commanded is issued to the register. Note the interrupt is always generated after the 1st polling cycle (after the TRIGGER bit in register CONFIG is set to logic 1). In subsequent polling cycles, the interrupt is generated only if switch status change is detected.

An example of the timing diagram of the polling mode operation is shown in Figure 23. Note in this example, IN1 is set to comparator input mode, while the other inputs are set to ADC input mode. As a result, the wetting current applied to IN2 is activated faster ( $t_{COMP}$  instead of  $t_{ADC}$  after IN1 wetting current turns off) to shorten the overall polling period. Shortened polling period translates to reduced overall power consumption for the system.

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## **Device Functional Modes (continued)**

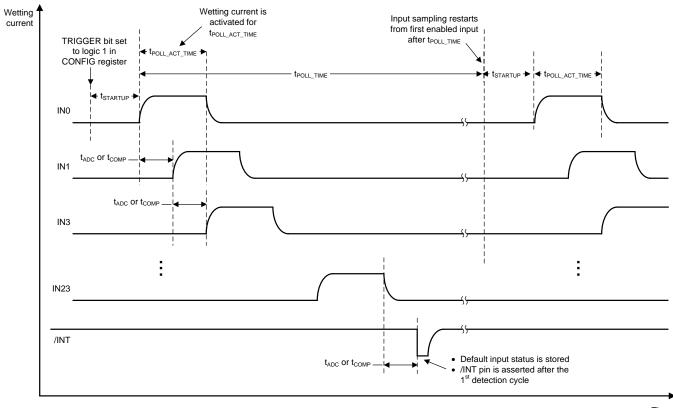


Figure 23. An Example Of The Polling Sequence In Standard Polling Mode

Time

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## **Device Functional Modes (continued)**

If the switch position changes between two active polling times, no interrupt will be generated and the status registers (IN\_STAT\_COMP for comparator inputs and IN\_STAT\_ADC0 to IN\_STAT\_ADC1 for ADC inputs) will not reflect such a change. An example is shown in Figure 24.

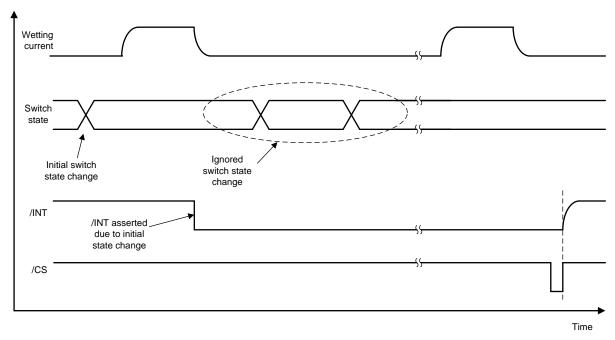


Figure 24. Example For Ignored Switch Position Change Between 2 Wetting Current Cycles

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# **Device Functional Modes (continued)**

# 8.4.2.2 Matrix Polling

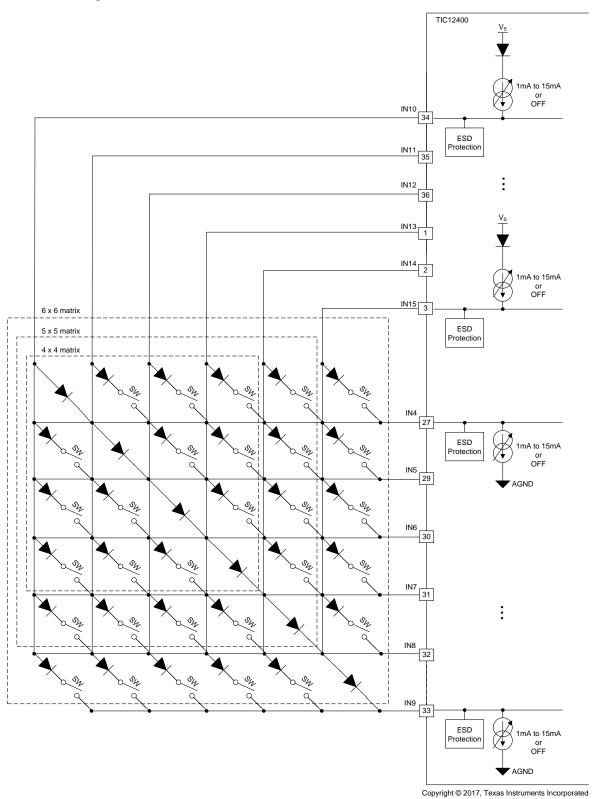


Figure 25. TIC12400 Matrix Configuration

## **Device Functional Modes (continued)**

From IN4 to IN15, a special input switch matrix (see Figure 25) can be configured and monitored in addition to the standard switches to GND and  $V_{SUPPLY}$ . This feature could be useful to monitor a special switch input configuration call Matrix, as required by some specific OEMs.

Three different matrix configurations are possible, and are defined by MATRIX bits in the MATRIX register. If the MATRIX bits are set to '00', all inputs are treated as standard inputs with identical polling active time according to the POLL\_ACT\_TIME bits in the CONFIG register. Any settings other than '00' for MATRIX bits causes the polling active time for the matrix inputs to be configured according to POLL\_ACT\_TIME\_M bits in the MATRIX register. Inputs that are not part of the matrix configuration will be configured using the POLL\_ACT\_TIME bits in the CONFIG register. t<sub>POLL\_ACT\_TIME\_M</sub> should be configured properly to allow sufficient time for the current source/sink to charge/discharge the capacitors (if any) connected to the switch inputs.

4x4 matrix 5x5 matrix 6x6 matrix Input **Polling Active Time Current Source Polling Active Current Source Current Source Polling Active Time** Or Sink **Time Setting** Or Sink Setting Or Sink Setting IN4 CSI CSI CSI IN5 CSI CSI CSI POLL\_ACT\_TIME \_M IN<sub>6</sub> CSI CSI CSI POLL\_ACT\_TIME\_M IN7 CSI CSI CSI Configurable to IN8 CSI CSI CSO or CSI POLL\_ACT\_TIME Configurable to Configurable to POLL\_ACT\_TIME\_ IN9 POLL\_ACT\_TIME CSI CSO or CSI CSO or CSI М cso CSO IN10 CSO IN11 CSO CSO CSO POLL\_ACT\_TIME  $_{\mathsf{M}}$ IN12 CSO CSO POLL\_ACT\_TIME\_M CSO IN13 CSO CSO CSO IN14 CSO CSO CSO POLL\_ACT\_TIME CSO CSO POLL\_ACT\_TIME CSO IN15

**Table 6. TIC12400 Matrix Configuration Settings** 

The TIC12400 implements a different polling scheme when matrix input is configured. After the polling sequence is started (by setting TRIGGER bit in CONFIG register to logic 1), the polling takes place within the matrix input group first before the rest of the standard inputs are polled. After the matrix inputs are polled, the switch status of each input combination (below or above detection threshold) is stored internally in registers IN\_STAT\_MATRIX0 and IN\_STAT\_MATRIX1, and it is used as the default state for subsequent matrix polling cycles. The standard inputs follow the same polling behavior as described in section Standard Polling. After the polling cycle (matrix+standard) is completed, the INT pin is asserted low to notify the microcontroller that the default switch status is ready to be read. The SSC bit in the INT\_STAT register and the SPI status flag SSC are also asserted to logic 1.

The INT\_STAT register is cleared and INT pin de-asserted if a SPI READ commanded is issued to the register. Note the interrupt is always generated after the 1st complete polling cycle (after the TRIGGER bit in register CONFIG is set to logic 1). In subsequent polling cycles, the interrupt is generated only if switch status change is detected.

Note the following programming requirement when using the matrix polling:

- It is critical to program the CSO/CSI configuration for each matrix input appropriately according to Table 6 to avoid incorrect switch status detection.
- It is mandatory to set higher wetting current for the sinks (IN4-IN9) than the sources (IN10-IN15). The actual current flowing through the external switches will be the lesser of the two settings. If the same setting is used for both the sink and the source, the detected result might be incorrect. Because of this, 15mA setting shall not be used for the current sources and 1 mA setting shall not be used for the current sinks. Depending on the type of matrix switches, the TIC12400 might require some specific wetting current settings to be able to distinguish between switch open/closed states.
- If TW\_CUR\_DIS\_CSO or TW\_CUR\_DIS\_CSI is set to logic 0 in the CONFIG register, wetting current is
  reduced to 2 mA for 10 mA and 15 mA settings upon TW event. Since it's mandatory to have higher wetting
  current for the sinks (IN4-IN9) than the sources (IN10-IN15) during matrix polling, Table 7 below summarizes
  the only possible settings if TW event is expected:

Table 7. Possible Wetting Current Settings For The Matrix Polling Mode If TW\_CUR\_DIS=0 And TW Event Is Expected

CSO (IN10-IN15)	CSI (IN4-IN9)	Resulting wetting current
1 mA	2 mA, 5 mA, 10 mA, 15 mA	1 mA
2 mA	5 mA	2 mA

If higher wetting current is needed and TW event might be expected, the TW wetting current reduction feature needs to be disabled by setting TW\_CUR\_DIS\_CSO or TW\_CUR\_DIS\_CSI bit in the CONFIG register to 1.

Only comparator input mode is supported for the matrix polling. Do not program the matrix inputs into ADC input mode. The comparison takes place on the source side (IN10-IN15) since the sink side is pulled to ground. Interrupt generation condition can be set by configuring the INT\_EN\_COMP1 and INT\_EN\_COMP2 registers for inputs IN10 to IN15.

Some programmability is removed when matrix polling mode is used, as listed below:

- To keep the polling scheme simple, the ability to disable inputs is removed for the matrix inputs. Only 3 configurations (4x4, 5x5, and 6x6) can be used for the matrix polling. Standard inputs outside the matrix input group can still be disabled, if desired.
- Detection filter (by configure the DET\_FILTER in the CONFIG register) does not apply to the matrix inputs, but still applies to the standard inputs outside the matrix input group.
- When matrix polling is selected, continuous mode is not available to the standard inputs outside the matrix input group.

Figure 26 illustrates an example of the polling sequence for the 6x6 matrix input configuration:

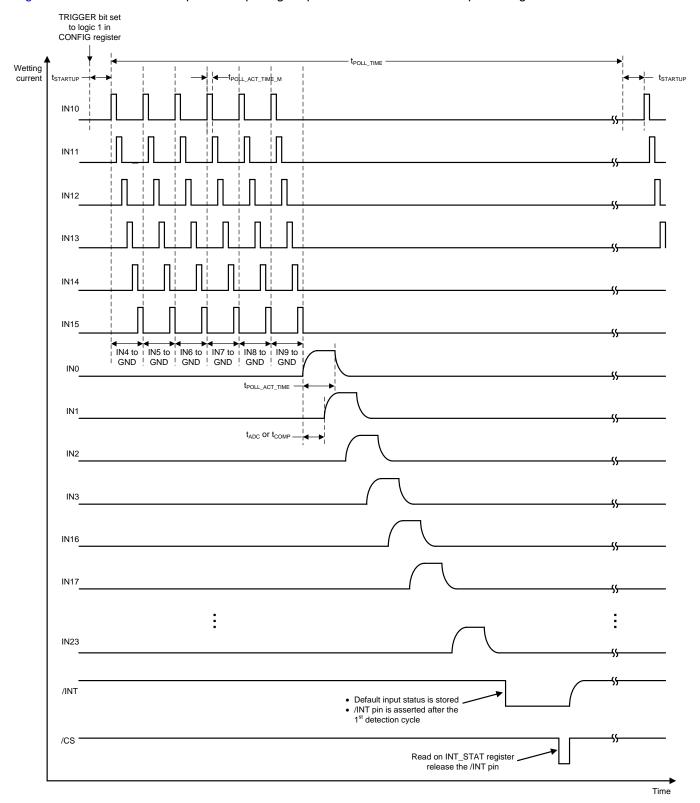


Figure 26. Polling Scheme for 6x6 Matrix Inputs

Figure 27 illustrates an example of the polling sequence for the 5x5 matrix input configuration. Note the input IN9 and IN15 are included in the standard polling sequence.

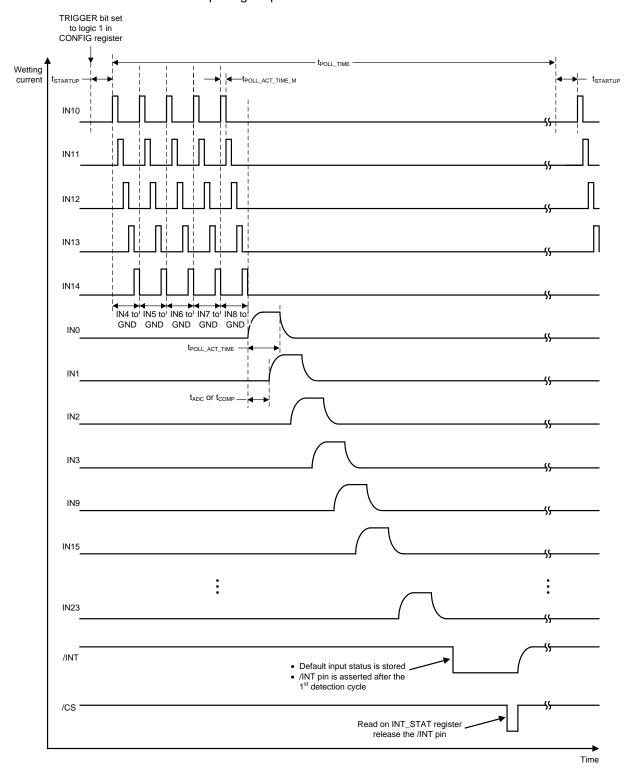


Figure 27. Polling Scheme For 5x5 Matrix Inputs

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Figure 28 illustrates an example of the polling sequence for the 4x4 matrix input configuration. Note inputs IN8, IN9, IN14, and IN15 are included in the standard polling sequence.

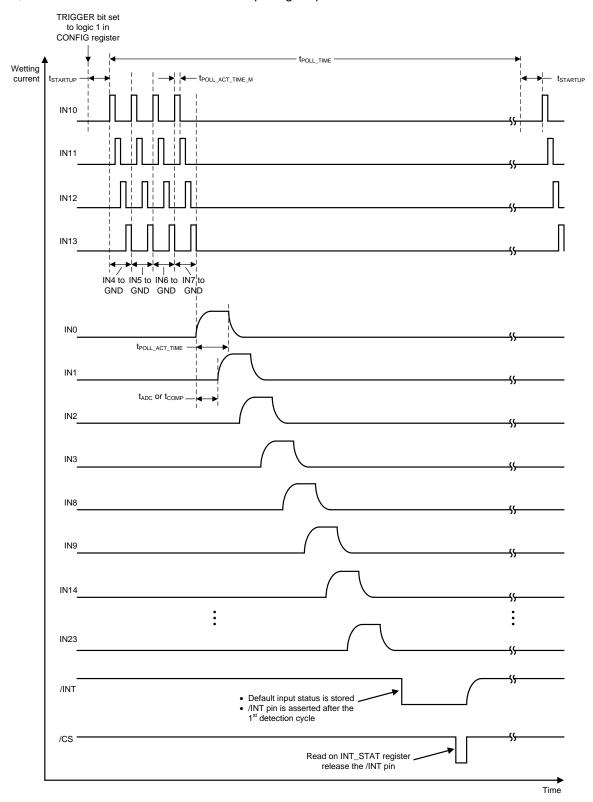


Figure 28. Polling Scheme For 4x4 Matrix Inputs

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#### 8.4.3 Additional Features

There are additional features that can be enabled during continuous and polling mode to increase robustness of device operation or provide more system information. These features are described in detail in the following sections:

#### 8.4.3.1 Clean Current Polling (CCP)

To detect resistor coded switches or reduce overall power consumption of the chip, a lower wetting current setting might be desired. However, certain system design requires 10mA or higher cleaning current to clear oxide build-up on the mechanical switch contact surface when the current is applied to closed switches. A special type of polling, called the Clean Current Polling (CCP) can be used for this application.

If CCP is enabled, each polling cycle consists of two wetting current activation steps. The first step uses the wetting current setting configured in the WC\_CFG0 and WC\_CFG1 registers as in the continuous mode or polling mode. The second step (cleaning cycle) is activated simultaneously for all CCP enabled inputs t<sub>CCP\_TRAN</sub> after the normal polling step of the last enabled input. Interrupt generation and INT pin assertion is not impacted by the clean current pulses.

The wetting current and its active time for the cleaning cycle can be configured in the CCP\_CFG0 register. The cleaning cycle can be disabled, if desired, for each individual input by programming the CCP\_CFG1 register. CCP is available for both continuous mode and the polling mode. To use the CCP feature, at least one input (standard or matrix) or the  $V_S$  measurement has to be enabled.

Note that although CCP can be enabled in Matrix polling mode, it is not an effective way to clean the matrix switch contact, since the current supplied from the TIC12400 is divided and distributed across multiple matrix channels.



Figure 29 illustrates the operation of the CCP when the device is configured to the standard polling mode.

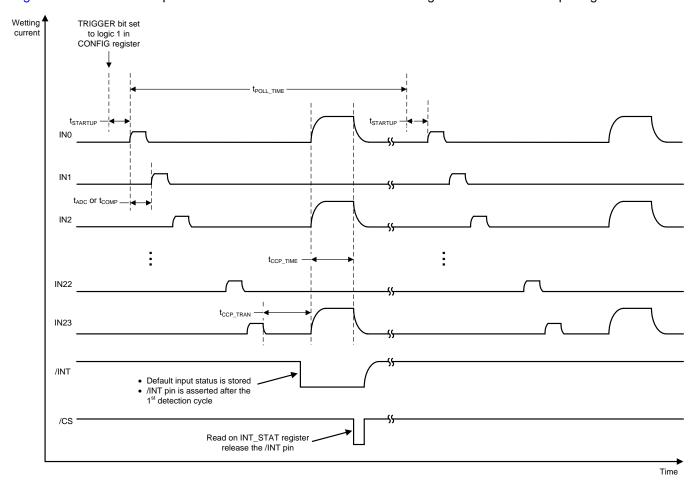


Figure 29. Standard Polling With CCP Enabled

Figure 30 illustrates the operation of the CCP when the device is configured to the continuous mode:

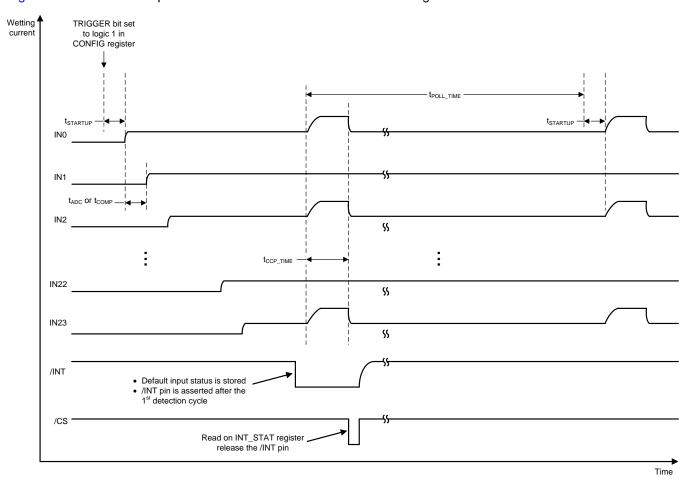


Figure 30. Continue Mode With CCP Enabled

#### 8.4.3.2 Wetting Current Auto-Scaling

The 10 mA and 15 mA wetting current settings are useful to clean oxide build-up on the mechanical switch contact surface when the switch changes state from open to close. After the switch is closed, it might be undesirable to keep the wetting current level at high level if only digital switches are monitored since it results in high current consumption and could potentially heat up the device quickly if multiple inputs are monitored. The wetting current auto-scaling feature help mitigate this issue.

When enabled (AUTO\_SCALE\_DIS\_CSO or AUTO\_SCALE\_DIS\_CSI bit = logic 0 in the WC\_CFG1 register), wetting current is reduced to 2 mA from 10 mA or 15 mA setting after switch closure is detected. The threshold used to determine a switch closure is the threshold configured in the THRES\_COMP register for inputs configured as comparator input mode. For inputs configured as ADC input mode, the threshold used to determine a switch closure depends on the input number, as described in Table 8 below:

Table 8. Threshold Used To Determine A Switch Closure For Wetting Current Auto-scaling For ADC Inputs

Input	Threshold used to determine a switch closure
IN0-IN11	Mapped threshold from THRES0 to THRES7
IN12 to IN17	THRES2B
IN18 to IN22	THRES3C
IN23	THRES9

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The current reduction takes place N cycles after switch closure is detected on an input, where N depends on the setting of the DET\_FILTER bits in the CONFIG register:

- DET\_FILTER= 00: wetting current is reduced immediately in the next detection cycle after a closed switch is detected.
- DET FILTER= 01: wetting current is reduced when a closed switch is detected and the switch status is stable for at least 2 consecutive detection cycles
- DET\_FILTER= 10: wetting current is reduced when a closed switch is detected and the switch status is stable for at least 3 consecutive detection cycles
- DET\_FILTER= 11: when a closed switch is detected and the switch status is stable for at least 4 consecutive detection cycles

The wetting current is adjusted back to the original setting of 10 mA or 15 mA N cycles after an open switch is detected, where N again depends on the DET\_FILTER bit setting in the CONFIG register. Figure 31 depicts the behavior of the wetting current auto-scaling feature.

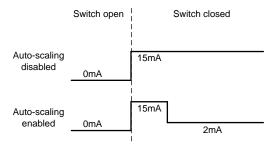


Figure 31. Wetting Current Auto-scaling Behavior

The wetting current auto-scaling only applies to 10 mA and 15 mA settings and is only available in continuous mode. If AUTO\_SCALE\_DIS\_CSO or AUTO\_SCALE\_DIS\_CSI bit is set to logic 1 in the WC\_CFG1 registers, the wetting current stays at its original setting when a closed switch is detected. Power dissipation needs to be closely monitored when wetting current auto-scaling is disabled for multiple inputs as the device could heat up quickly when high wetting current settings are used. If the auto-scaling feature is disabled in continuous mode, total power dissipation can be calculated using Equation 1 below.

$$P_{TOTAL} = V_S \times \left( I_{S\_CONT} + I_{WETT(TOTAL)} \right) \tag{1}$$

where I<sub>WETT (TOTOAL)</sub> is the sum of all wetting currents from all input channels. Increase in device junction temperature can be calculated based on P  $\times R_{\theta,JA}$ . The junction temperature has to be limited below  $T_{TSD}$  for proper device operation. An interrupt will be issued when the junction temperature exceeds T<sub>TW</sub> or T<sub>TSD</sub>. For detailed description of the temperature monitoring, please refer to sections Temperature Warning (TW)and Temperature Shutdown (TSD).

#### 8.4.3.3 V<sub>S</sub> Measurement

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When the TIC12400 is used to monitor resistor-coded switches, the level of V<sub>S</sub> supply voltage becomes very critical. If V<sub>S</sub> is not sufficiently high, the device might not have enough headroom to produce accurate wetting currents. This could impact the accuracy of the switch status monitoring. It is imperative for the microcontroller to have knowledge of the V<sub>S</sub> voltage on a constant basis in such a case.

Measurement of V<sub>S</sub> voltage is a feature in TIC12400 that can be enabled by setting the VS\_MEAS\_EN bit in register CONFIG to logic 1. If enabled, at the end of every detection/polling cycle, the voltage on the V<sub>S</sub> pin is sampled and converted by the ADC to an digital value. The conversion takes one extra tADC, and the converted value is recorded in the ANA STAT12 register.

The V<sub>S</sub> measurement supports two different V<sub>S</sub> voltage ranges that can be configured by the VS\_RATIO bit in the CONFIG register. By default (VS\_RATIO = logic 0), the supported V<sub>S</sub> voltage range is from 6.5 V to 9 V, and V<sub>s</sub> voltage in excess of 9 V results in a saturated ADC raw code of 1023. This setting provides better measurement resolution at lower V<sub>S</sub> voltages. When VS\_RATIO bit is set to logic 1, the supported V<sub>S</sub> voltage range is widened to 6.5V to 30V, and V<sub>S</sub> voltage in excess of 30 V results in a saturated ADC raw code of 1023. This setting allows wider measurement range but more coarse measurement resolution. It is important to adjust the detection thresholds accordingly depending on the V<sub>S</sub> voltage range configured.

Four different thresholds (VS0\_THRES2A/B and VS1\_THRES2A/B) can be programmed to have the TIC12400 notify the microcontroller when the  $V_S$  voltage crosses the thresholds. The value of these thresholds can be programmed by configuring registers THRES\_CFG0 to THRES\_CFG3 and the mapping can be programmed by configuring registers THRESMAP\_VS0\_THRES2A/B and THRESMAP\_VS1\_THRES2A/B bits in the register THRESMAP\_CFG2. When setting the thresholds, follow the rules in Table 9 below:

Table 9. Proper threshold configuration for V<sub>S</sub> measurements

V <sub>S</sub> Threshold	Proper Threshold Configuration
VS0	VS0_THRES2B ≥ VS0_THRES2A
VS1	VS1_THRES2B ≥ VS1_THRES2A

After the  $V_S$  measurement is enabled for the first time, the  $V_S$  measurement interrupt is always generated ( $\overline{\text{INT}}$  pin is asserted low, and the VS0 or VS1 bit in the INT\_STAT register is flagged to logic 1) at the end of the first polling cycle to notify the microcontroller the initial  $V_S$  measurement result is ready to be retrieved . The VS0\_STAT and VS1\_STAT bits from register IN\_STAT\_MISC indicate the status of the  $V_S$  voltage with respect to the thresholds, and the ANA\_STAT12 register stores the converted digital value of the  $V_S$  voltage. The SPI status flag VS\_TH is also asserted to logic 1 during SPI communications. Note the status detected in the first polling cycle becomes the baseline value of comparison for subsequent  $V_S$  measurements and the interrupt will be generated only if threshold crossing is detected.

Similar to regular inputs, interrupt generation condition can be programmed by setting the VS\_TH0\_EN and VS\_TH1\_EN bits in the INT\_EN\_CFG4 register to the following settings:

- Rising edge: an interrupt is generated if the current V<sub>S</sub> measurement is above the corresponding threshold and the previous measurement was below.
- 2. **Falling edge**: an interrupt is generated if the current V<sub>S</sub> measurement is below the corresponding threshold and the previous measurement was above.
- 3. Both edges: changes of the V<sub>S</sub> measurement status in either direction results in an interrupt generation.

Interrupt generation can also be disabled by setting VS\_TH0\_EN or VS\_TH1\_EN to logic 0 in register INT\_EN\_CFG4. Once disabled,  $V_S$  voltage crossing does not flag the VS0 or VS1 bit in INT\_STAT register and does not assert INT pin low. To only mask the INT pin from assertion (while keeping INT\_STAT register updated), configure the VS1\_EN and VS0\_EN bits in register INT\_EN\_CFG0 to logic 0.

Note the  $V_S$  measurement is only intended to be used as part of switch detection sequence to determine the validity of the switch detection states that are reported by the TIC12400. It is not intended to be used for standalone supply monitoring, such as monitoring cranking voltages, due to the potentially delayed response being part of the polling sequence. The  $V_S$  measurement result is accurate for  $V_S$  above 6.5V.

By default, the V<sub>S</sub> voltage measurement is disabled upon device reset.

#### 8.4.3.4 Wetting Current Diagnostic

When the TIC12400 is used to monitor safety-critical switches, it might be valuable for the microcontroller to have knowledge of the wetting current sources/ sinks operating status. This can be achieved by activating the wetting current diagnostic feature provided for inputs IN0 to IN3. IN0 and IN1 can be diagnosed for defective wetting current sources, while IN2 and IN3 can be diagnosed for failed current sinks.

The wetting current diagnostic feature can be activated by setting the WET\_D\_INx\_EN bits in the CONFIG register to 1 for the desired inputs, where x can be 0, 1, 2, or 3. If activated, the TIC12400 checks the status of the wetting current sources/sinks for the configured input periodically as part of the polling sequence. If the wetting current is determined to be flawed, the TIC12400 pulls the INT pin low to notify the host and flag the WET\_DIAG bit in the INT\_STAT register to logic 1. The OI bit in the SPI flag is also asserted during SPI transactions. The microcontroller can then read bits IN0\_D to IN3\_D in register IN\_STAT\_MISC to learn more information on which wetting current source/sink is defective.

The wetting current diagnostic is not performed for inputs that are disabled (IN\_EN\_x bit = 0 in the IN\_EN register) from polling, even if the feature if activated for those inputs. Also, it is critical to configure the current source/sink appropriately (CSO for IN0/IN1 and CSI for IN2/IN3) and program the input to ADC input mode before activating the wetting current diagnostic feature to avoid false interrupt from generation. The wetting current diagnostic feature can be performed regardless of the states of external switches, and it is available in both continuous mode and the polling mode.



Figure 32 shows an example of the feature carried out in a typical polling sequence. In this example, it can be observed that the wetting current is activated for duration of  $t_{POLL\_ACT}$ +  $t_{ADC}$  for each input diagnosed. After IN3 is diagnosed, normal polling sequence resumes and the wetting current is activated for  $t_{POLL\_ACT}$  for the rest of the inputs. The diagnostic is not executed on input IN2 in this example since it is disabled.

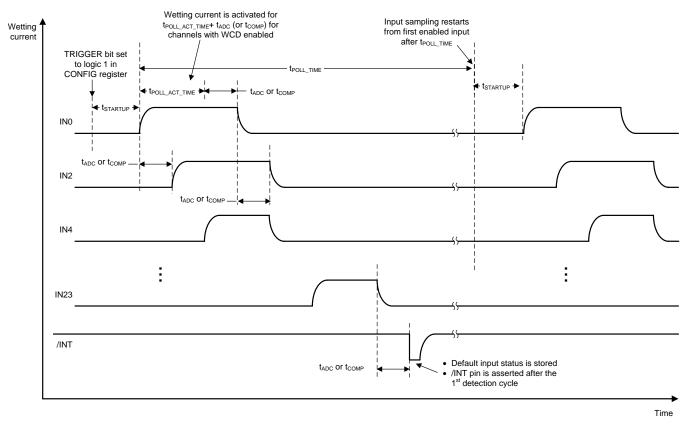


Figure 32. An Example Of The Polling Sequence In Standard Polling Mode With Wetting Current Diagnostic Enabled

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#### 8.4.3.5 ADC Self-Diagnostic

In addition to the wetting current diagnostic, another diagnostic feature, the ADC self-diagnostic, can be enabled to monitor the integrity of the internal ADC.

The ADC self-diagnostic feature is activated by setting the ADC\_DIAG\_T bit in the CONFIG register to logic 1. Once enabled, the TIC12400 periodically sends a test voltage to the ADC. The conversion result is stored in the ADC\_SELF\_ANA bits in the register ANA\_STAT12 and it is compared with a pre-defined code to determine whether the conversion is performed properly. If an error is detected, the TIC12400 pulls the INT pin low to notify the host and flag the ADC\_DIAG bit in the INT\_STAT to logic 1. The bit ADC\_D in register IN\_STAT\_MISC is updated with the result from the self-diagnostic. The ADC self-diagnostic feature is available in both continuous mode and the polling mode.

#### 8.5 Programming

The SPI interface communication consists of the 4 pins:  $\overline{CS}$ , SCLK, SI, and SO. The interface can work with SCLK frequency up to 4MHz.

#### 8.5.1 SPI Communication Interface Buses

#### 8.5.1.1 Chip Select (CS)

The system microcontroller selects the TIC12400 to receive communication using the  $\overline{CS}$  pin. With the  $\overline{CS}$  pin in a logic LOW state, command words may be sent to the TIC12400 via the serial input (SI) pin, and the device information can be retrieved by the microcontroller via the serial output (SO) pin. The falling edge of the  $\overline{CS}$  enables the SO output and latches the content of the interrupt register INT\_STAT. The microcontroller may issue a READ command to retrieve information stored in the registers. Rising edge on the  $\overline{CS}$  pin initiates the following operations:

- 1. Disable the output driver and makes SO high-impedance
- 2.  $\overline{\text{INT}}$  pin is reset to logic HIGH if a READ command to the INT\_STAT register was issued during  $\overline{\text{CS}} = \text{LOW}$ .

To avoid any corrupted data, it is essential the HIGH-to-LOW and LOW-to-HIGH transitions of the  $\overline{CS}$  signal occur only when SCLK is in a logic LOW state. A clean  $\overline{CS}$  signal is needed to ensure no incomplete SPI words are sent to the device. The  $\overline{CS}$  pin should be externally pulled up to VDD by a 10-k $\Omega$  resistor.

#### 8.5.1.2 System Clock (SCLK)

The system clock (SCLK) pin clocks the internal shift register of the TIC12400. The SI data is latched into the input shift register on the falling edge of the SCLK signal. The SO pin shifts the device stored information out on the rising edge of SCLK. The SO data is available for the microcontroller to read on the falling edge of SCLK.

False clocking of the shift register must be avoided to ensure validity of data and it is essential the SCLK pin be in a logic LOW state whenever  $\overline{\text{CS}}$  makes any transition. Therefore, it is recommended that the SCLK pin gets pulled to a logic LOW state as long as the device is not accessed and  $\overline{\text{CS}}$  is in a logic HIGH state. When the  $\overline{\text{CS}}$  is in a logic HIGH state, any signal on the SCLK and SI pins will be ignored and the SO pin remains as a high impedance output. Refer to Figure 33 and Figure 34 for examples of typical SPI read and write sequence.

#### 8.5.1.3 Slave In (SI)

The SI pin is used for serial instruction data input. SI information is latched into the input register on the falling edge of the SCLK. To program a complete word, 32 bits of information must be enter into the device. The SPI logic counts the number of bits clocked into the IC and enables data latching only if exactly 32 bits have been clocked in. In case the word length exceeds or does not meet the required length, the SPI\_FAIL bit of the INT\_STAT register is asserted to logic 1 and the INT pin will be asserted low. The data received is considered invalid. Note the SPI\_FAIL bit is not flagged if SCLK is not present.

#### 8.5.1.4 Slave Out (SO)

The SO pin is the output from the internal shift register. The SO pin remains high-impedance until the  $\overline{\text{CS}}$  pin transitions to a logic LOW state. The negative transition of  $\overline{\text{CS}}$  enables the SO output driver and drive the SO output to the HIGH state (by default). The first positive transition of SCLK makes the status data bit 32 available on the SO pin. Each successive positive clock makes the next status data bit available for the microcontroller to read on the falling edge of SCLK. The SI/SO shifting of the data follows a first-in, first-out scheme, with both input and output words transferring the most significant bit (MSB) first.

#### **Programming (continued)**

#### 8.5.2 SPI Sequence

The following diagrams depict the SPI communication sequence during read and write operations for TIC12400.

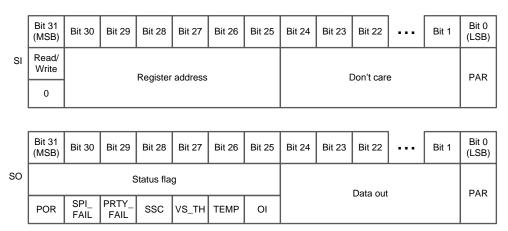


Figure 33. TIC12400 Read SPI Sequence

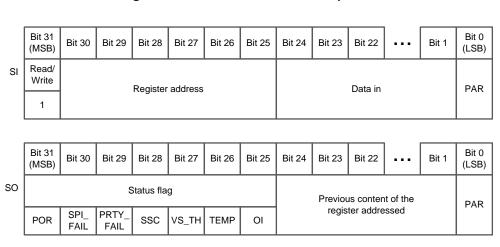


Figure 34. TIC12400 Write SPI Sequence

#### 8.5.2.1 Read Operation

The Read/Write bit (bit 31) of the SI bus needs to be set to logic 0 for a READ operation. The 6-bits address of the register to be accessed follows next on the SI bus. The content from bit 24 to bit 1 does not represent valid command for a read operation and will be ignored. The LSB (bit 0) is the parity bit used to detect communication errors.

On the SO bus, the status flags will be outputted from the TIC12400, followed by the data content in the register that was requested. The LSB is the parity bit used to detect communication errors.

Note there are several test mode registers (not shown in this ASD) used in the TIC12400 in addition to the normal functional registers, and a READ command to these test registers returns the register content. If a READ command is issued to an invalid register address, the TIC12400 will return all 0's.

#### 8.5.2.2 Write Operation

The Read/Write bit (bit 31) on the SI bus needs to be set to 1 for a write operation. The 6-bits address of the register to be accessed follows next on the SI bus. Note the register needs to be a writable configuration register, or otherwise, the command will be ignored. The content from bit 24 to bit 1 represents the data to be written to the register. The LSB (bit 0) is the parity bit used to detect communication errors.

#### **Programming (continued)**

On the SO bus, the status flags will be outputted from the TIC12400, followed by the previous data content of the same register being written to. The previous data content of the register is latched after the full register address is decoded in the SI command (after bit 25 is transmitted). The new data will replace the previous data content at the end of the SPI transaction if the SI write is a valid command (valid register address and no SPI/parity error). If the write command is invalid, the new data will be ignored and the previous data content of the register stays. The LSB is the parity bit used to detect communication errors.

Note there are several test mode registers (not shown in this ASD) used in the TIC12400 in addition to the normal functional registers. A WRITE command to these test registers have no effect on the register content, though the register content is returned on the SO output. If a WRITE command is issued to an invalid register address, the SO output would return all 0's.

#### 8.5.2.3 Status Flag

The status flags are output from SO during every READ or WRITE SPI transaction to indicate system conditions. These bits do not belong to an actual register, but the content is mirrored from the interrupt register INT\_STAT. A READ command executed on the INT\_STAT would clear both the bits inside the register and the status flag. The following table describes the information that can be obtained from each SPI status flag:

Table 10. TIC12400 SPI Status Flag Description

Symbol	Name	Description
POR	Power-on Reset	This flag mirrors the POR bit in the interrupt register INT_STAT and it indicates, if set to 1, that a reset event has occurred. This bit is asserted after a successful power-on=reset, hardware reset or software reset. Refer to section Device Reset for more details.
SPI_FAIL	SPI Error	This flag mirrors the SPI_FAIL bit in the interrupt register INT_STAT and it indicates, if set to 1, that the last SPI Slave In (SI) transaction is invalid. To program a complete word, 32 bits of information must be entered into the device. The SPI logic counts the number of bits clocked into the IC and enables data latching only if exactly 32 bits have been clocked in. In case the word length exceeds or does not meet the required size, the SPI_FAIL bit, which mirrors its value to this SPI_FAIL status flag, of the interrupt register INT_STAT will be set to 1 and the INT pin will be asserted low. The data received will be considered invalid. Once the INT_STAT register is read, its content will be cleared on the rising edge of CS. The SPI_FAIL status flag, which mirrors the SPI_FAIL bit in the INT_STAT register, will also be de-asserted. Note the SPI_FAIL bit is not flagged if SCLK is not present.
PRTY_FAIL	Parity Fail	This flag mirrors the PRTY_FAIL bit in the interrupt register INT_STAT and it indicates, if set to 1, that the last SPI Slave In (SI) transaction has a parity error. The device uses odd parity. If the total number of ones in the received data (including the parity bit) is an even number, the received data is discarded. The INT will be asserted low and the PRTY_FAIL bit in the interrupt register (INT_STAT) is flagged to logic 1, and the PRTY_FAIL status flag, which mirrors the PRTY_FAIL bit in the INT_STAT register, is also set to 1. Once the INT_STAT register is read, its content will be cleared on the rising edge of CS. The PRTY_FAIL status flag, which mirrors the PRTY_FAIL bit in the INT_STAT register, will also be de-asserted.
SSC	Switch State Change	This flag mirrors the SSC bit in the interrupt register INT_STAT and it indicates, if set to 1, that one or more switch input crossed threshold(s). To determine the origin of the state change, the microcontroller can read the content of registers IN_STAT_COMP (if input is set to comparator input mode), IN_STAT_ADC0 to IN_STAT_ADC1 (if input is set to ADC input mode), or IN_STAT_MATRIX0 to IN_STAT_MATRIX1 (if input is set to matrix input). Once the interrupt register (INT_STAT) is read, its content will be cleared on the rising edge of CS. The SSC status flag, which mirrors the SSC bit in the INT_STAT register, will also be de-asserted.
VS_TH	V <sub>S</sub> Threshold Crossing	This flag is set to 1 if either VS0 or VS1 bit in the interrupt register INT_STAT is flagged to 1. It indicates the $V_S$ voltage crosses thresholds defined by VS0_THRES2A, VS0_THRES2B, VS1_THRES2A, or VS1_THRES2A. To determine the origin of the threshold crossing, the microcontroller can read register bits VS0_STAT and VS1_STAT in the register IN_STAT_MISC. Once the interrupt register (INT_STAT) is read, its content will be cleared on the rising edge of $\overline{CS}$ , and the VS_TH status flag will also be de-asserted.
TEMP	Temperature event	This flag is set to 1 if either TW or TSD bit in the interrupt register INT_STAT is flagged to 1. It indicates a Temperature Warning (TW) event or a Temperature Shutdown (TSD) event has occurred. It is also flagged to 1 if a Temperature Warning (TW) event or a Temperature Shutdown (TSD) event cleared. The interrupt register INT_STAT should be read to determine which event occurred. The SPI master can also read the IN_STAT_MISC register to get information on the temperature status of the device. Once the interrupt register (INT_STAT) is read, its content will be cleared on the rising edge of $\overline{\text{CS}}$ , and the TEMP status flag will also be de-asserted.

# **Programming (continued)**

# Table 10. TIC12400 SPI Status Flag Description (continued)

Symbol	Name	Description
OI	Other Interrupt	Other interrupt include interrupts such as OV, UV, CRC_CALC. WET_DIAG, ADC_DIAG and CHK_FAIL. This flag will be asserted 1 when any of the abovementioned bits is flagged in the interrupt register INT_STAT. The interrupt register INT_STAT should be read to determine which event(s) occurred. The SPI master can also read the IN_STAT_MISC register to get information on the latest status of the device. Once the INT_STAT register is read, its content will be cleared on the rising edge of $\overline{CS}$ , and the OI status flag will also be de-asserted.

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#### 8.6 Register Maps

Table 11 lists the memory-mapped registers for the TIC12400. All register offset addresses not listed in Table 11 should be considered as reserved locations and the register contents should not be modified.

Table 11. TIC12400 Registers

Offset	Туре	Reset	Acronym	Register Name	Section
1h	R	20h	DEVICE_ID	Device ID Register	Go
2h	RC	1h	INT_STAT	Interrupt Status Register	Go
3h	R	FFFFh	CRC	CRC Result Register	Go
4h	R	0h	IN_STAT_MISC	Miscellaneous Status Register	Go
5h	R	0h	IN_STAT_COMP	Comparator Status Register	Go
6h-7h	R	0h	IN_STAT_ADC0, IN_STAT_ADC1	ADC Status Register	Go
8h-9h	R	0h	IN_STAT_MATRIX0, IN_STAT_MATRIX1	Matrix Status Register	Go
Ah-16h	R	0h	ANA_STAT0- ANA_STAT12	ADC Raw Code Register	Go
17h- 19h	_	_	RESERVED	RESERVED	_
1Ah	R/W	0h	CONFIG	Device Global Configuration Register	Go
1Bh	R/W	0h	IN_EN	Input Enable Register	Go
1Ch	R/W	0h	CS_SELECT	Current Source/Sink Selection Register	Go
1Dh- 1Eh	R/W	0h	WC_CFG0, WC_CFG1	Wetting Current Configuration Register	Go
1Fh- 20h	R/W	0h	CCP_CFG0, CCP_CFG1	Clean Current Polling Register	Go
21h	R/W	0h	THRES_COMP	Comparator Threshold Control Register	Go
22h- 23h	R/W	0h	INT_EN_COMP1, INT_EN_COMP2	Comparator Input Interrupt Generation Control Register	Go
24h	R/W	0h	INT_EN_CFG0	Global Interrupt Generation Control Register	Go
25h- 28h	R/W	0h	INT_EN_CFG1- INT_EN_CFG4	ADC Input Interrupt Generation Control Register	Go
29h- 2Dh	R/W	0h	THRES_CFG0- THRES_CFG4	ADC Threshold Control Register	Go
2Eh- 30h	R/W	0h	THRESMAP_CFG0- THRESMAP_CFG2	ADC Threshold Mapping Register	Go
31h	R/W	0h	Matrix	Matrix Setting Register	Go
32h	R/W	0h	Mode	Mode Setting Register	Go

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# 8.6.1 DEVICE\_ID register (Offset = 1h) [reset = 20h]

DEVICE\_ID is shown in Figure 35 and described in Table 12.

Return to Summary Table.

This register represents the device ID of the TIC12400.

## Figure 35. DEVICE\_ID Register

23	22	21	20	19	18	17	16	15	14	13	12			
	RESERVED													
	R-0h													
11	10	9	8	7	6	5	4	3	2	1	0			
RESERV ED					MIN	NOR								
R-0h						R-	-0h							

LEGEND: R = Read only

#### Table 12. DEVICE\_ID Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-11	RESERVED	R	0h	RESERVED
10-4	MAJOR	R	2h	These 7 bits represents major revision ID. For TIC12400 the major revision ID is 2h.
3-0	MINOR	R	0h	These 4 bits represents minor revision ID. For TIC12400 the minor revision ID is 0h.

# 8.6.2 INT\_STAT Register (Offset = 2h) [reset = 1h]

INT\_STAT is shown in Figure 36 and described in Table 13.

Return to Summary Table.

This register records the information of the event as it occurs in the device. A READ command executed on this register clears its content and resets the register to its default value. The  $\overline{\text{INT}}$  pin is released at the rising edge of the  $\overline{\text{CS}}$  pin from the READ command.

Figure 36. INT\_STAT Register

23	22	21	20	19	18	17	16							
	RESERVED													
R-0h														
15	14	13	12	11	10	10 9								
RESE	RVED	CHK_FAIL	ADC_DIAG	WET_DIAG VS1		VS0	CRC_CALC							
R	-0h	RC-0h	RC-0h	RC-0h	RC-0h	RC-0h	RC-0h							
7	6	5	4	3	2	1	0							
UV	UV OV TW		TSD	SSC	PRTY_FAIL	SPI_FAIL	POR							
RC-0h	RC-0h RC-0h		RC-0h	RC-0h	RC-0h	RC-0h	RC-1h							

LEGEND: R = Read only; RC = Read to clear

# Table 13. INT\_STAT Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-14	RESERVED	R	0h	RESERVED
13	CHK_FAIL	RC	0h	Oh = Default factory setting is successfully loaded upon device initialization or the event status got cleared after a READ command was executed on the INT_STAT register.
				1h = An error is detected when loading factory settings into the device upon device initialization.
				During device initialization, factory settings are programmed into the device to allow proper device operation. The device performs a self-check after the device is programmed to diagnose whether correct settings are loaded. If the self-check returns an error, the CHK_FAIL bit is flagged to logic 1 along with the POR bit. The host controller is then recommended to initiate a software reset (see section Software Reset) to re-initialize the device and allow correct settings to be reprogrammed.
12	ADC_DIAG	RC	0h	Oh = No ADC self-diagnostic error is detected or the event status got cleared after a READ command was executed on the INT_STAT register.
				1h = ADC self-diagnostic error is detected.
				The ADC Self-Diagnostic feature (see section ADC Self-Diagnostic) can be activated to monitor the integrity of the internal ADC. The ADC_DIAG bit is flagged to logic 1 if an ADC error is diagnosed.
11	WET_DIAG	RC	0h	Oh = No wetting current error is detected, or the event status got cleared after a READ command was executed on the INT_STAT register.
				1h = Wetting current error is detected.
				The Wetting Current Diagnostic feature (see section Wetting Current Diagnostic) can be activated to monitor the integrity of the internal current sources or sinks. The WET_DIAG bit is flagged to logic 1 if an wetting current error is diagnosed.

# Table 13. INT\_STAT Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
10	VS1	RC	0h	0h = No $V_S$ voltage state change occurred with respect to VS1_THRES2A or VS1_THRES2B or the status got cleared after a READ command was executed on the INT_STAT register.
				1h = $V_S$ voltage state change occurred with respect to VS1_THRES2A or VS1_THRES2B.
				The VS1 interrupt bit indicates whether $V_S$ voltage state change occurred with respect to thresholds VS1_THRES2A and VS1_THRES2B if the $V_S$ Measurement feature (see section VS Measurement) is activated.
9	VS0	RC	Oh	0h = No $V_S$ voltage state change occurred with respect to VS0_THRES2A or VS0_THRES2B or the status got cleared after a READ command was executed on the INT_STAT register.
				1h = $V_S$ voltage state change occurred with respect to VS0_THRES2A 10or VS0_THRES2B.
				The VS0 interrupt bit indicates whether $V_S$ voltage state change occurred with respect to thresholds VS0_THRES2A and VS0_THRES2B if the $V_S$ Measurement feature (see section VS Measurement) is activated.
8	CRC_CALC	RC	Oh	Oh = CRC calculation is running, not started, or was acknowledged after a READ command was executed on the INT_STAT register.  1h = CRC calculation is finished.
				CRC calculation (see section Cyclic Redundancy Check (CRC)) can be triggered to make sure correct register values are programmed into the device. Once the calculation is completed, the CRC_CALC bit is flagged to logic 1 to indicate completion of the calculation, and the result can then be accessed from the CRC (offset = 3h) register.
7	UV	RC	0h	0h = No under-voltage condition occurred or cleared on the $V_S$ pin, or the event status got cleared after a READ command was executed on the INT_STAT register.
				$1h = Under-voltage$ condition occurred or cleared on the $V_S$ pin.
				When the UV bit is flagged to logic 1, it indicates the Under-Voltage (UV) event has occurred. The bit is also flagged to logic 1 when the event clears. For more details about the UV operation, please refer to section VS under-voltage (UV) condition.
6	OV	RC	0h	0h = No over-voltage condition occurred or cleared on the $V_S$ pin, or the event status got cleared after a READ command was executed on the INT_STAT register.
				1h = Over-voltage condition occurred or cleared on the $V_{\mbox{\scriptsize S}}$ pin.
				When the OV bit is flagged to logic 1, it indicates the Over-Voltage (OV) event has occurred. The bit is also flagged to logic 1 when the event clears. For more details about the OV operation, please refer to section VS over-voltage (OV) condition.
5	TW	RC	Oh	Oh = No temperature warning event occurred or the event status got cleared after a READ command was executed on the INT_STAT register.
				1h = Temperature warning event occurred or cleared.
				When the TW bit is flagged to logic 1, it indicates the temperature warning event has occurred. The bit is also flagged to logic 1 when the event clears. For more details about the temperature warning operation, please refer to section Temperature Warning (TW)

# Table 13. INT\_STAT Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description						
4	TSD	RC	0h							
		110		Oh = No temperature shutdown event occurred or the event status got cleared after a READ command was executed on the INT_STAT register.						
				1h = Temperature shutdown event occurred or cleared.						
				When the TSD bit is flagged to logic 1, it indicates the temperature shutdown event has occurred. The bit is also flagged to logic 1 when the event clears. For more details about the temperature shutdown operation, please refer to section Temperature shutdown (TSD)						
3	SSC	RC	0h	0h = No switch state change occurred or the status got cleared after a READ command was executed on the INT_STAT register.						
				1h = Switch state change occurred.						
				The Switch State Change (SSC) bit indicates whether input threshold crossing has occurred from switch inputs IN0 to IN23. This bit is also flagged to logic 1 after the first polling cycle is completed after device polling is triggered.						
2	PRTY_FAIL	RC	Oh	0h = No parity error occurred in the last received SI stream or the error status got cleared after a READ command was executed on the INT_STAT register.						
				1h = Parity error occurred.						
				When the PRTY_FAIL bit is flagged to logic 1, it indicates the last SPI Slave In (SI) transaction has a parity error. The device uses odd parity. If the total number of ones in the received data (including the parity bit) is an even number, the received data is discarded. The value of this register bit is mirrored to the PRTY_FLAG SPI status flag.						
1	SPI_FAIL	RC	0h	Oh = 32 clock pulse during a $\overline{\text{CS}}$ = low sequence was detected or the error status got cleared after a READ command was executed on the INT_STAT register.						
				1h = SPI error occurred						
				When the SPI_FAIL bit is flagged to logic 1, it indicates the last SPI Slave In (SI) transaction is invalid. To program a complete word, 32 bits of information must be entered into the device. The SPI logic counts the number of bits clocked into the IC and enables data latching only if exactly 32 bits have been clocked in. In case the word length exceeds or does not meet the required length, the SPI_FAIL bit is flagged to logic 1, and the data received is considered invalid. The value of this register bit is mirrored to the SPI_FLAG SPI status flag. Note the SPI_FAIL bit is not flagged if SCLK is not present.						
0	POR	RC	1h	0h = no Power-On-Reset (POR) event occurred or the status got cleared after a READ command was executed on the INT_STAT register.						
				1h = Power-On-Reset (POR) event occurred.						
				The Power-On-Reset (POR) interrupt bit indicates whether a reset event has occurred. A reset event sets the registers to their default values and re-initializes the device state machine. This bit is asserted after a successful power-on-reset, hardware reset, or software reset. The value of this register bit is mirrored to the POR SPI status flag.						

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#### 8.6.3 CRC Register (Offset = 3h) [reset = FFFFh]

CRC is shown in Figure 37 and described in Table 14.

Return to Summary Table.

This register returns the CRC-16-CCCIT calculation result. The microcontroller can compare this value with its own calculated value to ensure correct register settings are programmed to the device.

## Figure 37. CRC Register

	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RESERVED															CF	RC								
R-0h															R-FF	FFh								

LEGEND: R = Read only

#### **Table 14. CRC Register Field Descriptions**

Bit	Field	Туре	Reset	Description
23-16	RESERVED	R	0h	Reserved
15-0	CRC	R	FFFFh	CRC-16-CCITT calculation result: Bit1: LSB of CRC Bit16: MSB or CRC

# 8.6.4 IN\_STAT\_MISC Register (Offset = 4h) [reset = 0h]

IN\_STAT\_MISC is shown in Figure 38 and described in Table 15.

Return to Summary Table.

This register indicates current device status unrelated to switch input monitoring.

## Figure 38. IN\_STAT\_MISC Register

23	22	21	20	19	18	17	16
			RESE	RVED			
			R	-0h			
15	14	13	12	11	10	9	8
	RESERVED		ADC_D	IN3_D	IN2_D	IN1_D	IN0_D
	R-0h		R-0h	R-0h	R-0h	R-0h	R-0h
7	6	5	4	3	2	1	0
VS1	VS1_STAT VS0_S			UV_STAT	OV_STAT	TW_STAT	TSD_STAT
F	R-0h	R	-0h	R-0h	R-0h	R-0h	R-0h

#### Table 15. IN\_STAT\_MISC Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-13	RESERVED	R	0h	Reserved
12	ADC_D	R	0h	Oh = No error is identified from ADC self-diagnostic.  1h = An error is identified from ADC self-diagnostic.
11	IN3_D	R	0h	0h = Current sink on IN3 is operational. 1h = Current sink on IN3 is abnormal.
10	IN2_D	R	0h	0h = Current sink on IN2 is operational. 1h = Current sink on IN2 is abnormal.
9	IN1_D	R	0h	Oh = Current source on IN1 is operational.  1h = Current source on IN1 is abnormal.
8	INO_D	R	0h	0h = Current source on IN0 is operational. 1h = Current source on IN0 is abnormal.
7-6	VS1_STAT	R	0h	0h = V <sub>S</sub> voltage is below threshold VS1_THRES2A.  1h = V <sub>S</sub> voltage is below threshold VS1_THRES2B and equal to or above threshold VS1_THRES2A.  2h = V <sub>S</sub> voltage is equal to or above threshold VS1_THRES2B.  3h = N/A.
5-4	VS0_STAT	R	0h	0h = V <sub>S</sub> voltage is below threshold VS0_THRES2A.  1h = V <sub>S</sub> voltage is below threshold VS0_THRES2B and equal to or above threshold VS0_THRES2A.  2h = V <sub>S</sub> voltage is equal to or above threshold VS0_THRES2B.  3h = N/A
3	UV_STAT	R	0h	0h = V <sub>S</sub> voltage is above the under-voltage condition threshold.  1h = V <sub>S</sub> voltage is below the under-voltage condition threshold.
2	OV_STAT	R	0h	0h = V <sub>S</sub> voltage is below the over-voltage condition threshold.  1h = V <sub>S</sub> voltage is above the over-voltage condition threshold.
1	TW_STAT	R	0h	0h = Device junction temperature is below the temperature warning threshold $T_{\rm TW}$ .
				1h = Device junction temperature is above the temperature warning threshold $T_{\text{TW}}. \label{eq:TW}$



# Table 15. IN\_STAT\_MISC Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
0	TSD_STAT	R	Oh	$\begin{array}{ll} \mbox{Oh = Device junction temperature is below the temperature shutdown threshold $T_{TSD}$.} \\ \mbox{1h = Device junction temperature is above the temperature shutdown threshold $T_{TSD}$.} \end{array}$

# 8.6.5 IN\_STAT\_COMP Register (Offset = 5h) [reset = 0h]

IN\_STAT\_COMP is shown in Figure 39 and described in Table 16.

Return to Summary Table.

This register indicates whether an input is below or above the comparator threshold when it is configured as comparator input mode.

Figure 39. IN\_STAT\_COMP Register

23	22	21	20	19	18	17	16
INC_23	INC_22	INC_21	INC_20	INC_19	INC_18	INC_17	INC_16
R-0h							
15	14	13	12	11	10	9	8
INC_15	INC_14	INC_13	INC_12	INC_11	INC_10	INC_9	INC_8
R-0h							
7	6	5	4	3	2	1	0
INC_7	INC_6	INC_5	INC_4	INC_3	INC_2	INC_1	INC_0
R-0h							

LEGEND: R = Read only

#### Table 16. IN\_STAT\_COMP Register Field Descriptions

Bit	Field	Туре	Reset	Description
				Description
23	INC_23	R	0h	0h = Input IN23 is below the comparator threshold.
				1h = Input IN23 is above the comparator threshold.
22	INC_22	R	0h	0h = Input IN22 is below the comparator threshold.
				1h = Input IN22 is above the comparator threshold.
21	INC_21	R	0h	0h = Input IN21 is below the comparator threshold.
				1h = Input IN21 is above the comparator threshold.
20	INC_20	R	0h	·
20	1110_20	K	OII	0h = Input IN20 is below the comparator threshold.
				1h = Input IN20 is above the comparator threshold.
19	INC_19	R	0h	0h = Input IN19 is below the comparator threshold.
				1h = Input IN19 is above the comparator threshold.
18	INC_18	R	0h	0h = Input IN18 is below the comparator threshold.
				1h = Input IN18 is above the comparator threshold.
17	INC_17	R	0h	
			011	0h = Input IN17 is below the comparator threshold.
				1h = Input IN17 is above the comparator threshold.
16	INC_16	R	0h	0h = Input IN16 is below the comparator threshold.
				1h = Input IN16 is above the comparator threshold.
15	INC_15	R	0h	0h = Input IN15 is below the comparator threshold.
				1h = Input IN15 is above the comparator threshold.
14	INC_14	R	0h	Oh = Input IN14 is below the comparator threshold.
	_			1h = Input IN14 is above the comparator threshold.
13	INC 12	R	0h	
13	INC_13	K	On	0h = Input IN13 is below the comparator threshold.
				1h = Input IN13 is above the comparator threshold.
12	INC_12	R	0h	0h = Input IN12 is below the comparator threshold.
				1h = Input IN12 is above the comparator threshold.
11	INC_11	R	0h	0h = Input IN11 is below the comparator threshold.
				1h = Input IN11 is above the comparator threshold.
10	INC_10	R	0h	
10	1140_10	IX.	OII	0h = Input IN10 is below the comparator threshold.
				1h = Input IN10 is above the comparator threshold.

# Table 16. IN\_STAT\_COMP Register Field Descriptions (continued)

Field	Туре	Reset	Description
INC_9	R	0h	0h = Input IN9 is below the comparator threshold.
			1h = Input IN9 is above the comparator threshold.
INC_8	R	0h	0h = Input IN8 is below the comparator threshold.
			1h = Input IN8 is above the comparator threshold.
INC_7	R	0h	0h = Input IN7 is below the comparator threshold.
			1h = Input IN7 is above the comparator threshold.
INC_6	R	0h	0h = Input IN6 is below the comparator threshold.
			1h = Input IN6 is above the comparator threshold.
INC_5	R	0h	0h = Input IN5 is below the comparator threshold.
			1h = Input IN5 is above the comparator threshold.
INC_4	R	0h	0h = Input IN4 is below the comparator threshold.
			1h = Input IN4 is above the comparator threshold.
INC_3	R	0h	0h = Input IN3 is below the comparator threshold.
			1h = Input IN3 is above the comparator threshold.
INC_2	R	0h	0h = Input IN2 is below the comparator threshold.
			1h = Input IN2 is above the comparator threshold.
INC_1	R	0h	0h = Input IN1 is below the comparator threshold.
			1h = Input IN1 is above the comparator threshold.
INC_0	R	0h	0h = Input IN0 is below the comparator threshold.
			1h = Input IN0 is above the comparator threshold.
	INC_9 INC_8 INC_7 INC_6 INC_5 INC_4 INC_3 INC_2 INC_1	INC_9 R INC_8 R INC_7 R INC_6 R INC_5 R INC_4 R INC_3 R INC_2 R INC_1 R	INC_9 R 0h INC_8 R 0h INC_7 R 0h INC_6 R 0h INC_5 R 0h INC_4 R 0h INC_3 R 0h INC_3 R 0h INC_2 R 0h INC_2 R 0h

# 8.6.6 IN\_STAT\_ADC0 Register (Offset = 6h) [reset = 0h]

IN\_STAT\_ADC0 is shown in Figure 40 and described in Table 17.

Return to Summary Table.

This register indicates whether an input is below or above the programmed threshold (for IN0-IN11) when it is configured as ADC input mode. For IN12-IN17, there are 2 thresholds and the register bits indicate whether the input is below, above or in-between the 2 thresholds.

Figure 40. IN\_STAT\_ADC0 Register

23	22	21	20	19	18	17	16	
INA	_17	INA	<u>16</u>	INA	_15	INA_14		
R-	-0h	R	-0h	R-	0h	R-0h		
15	14	13	12	11	10	9	8	
INA	_13	INA	A_12	INA_11	INA_10	INA_9	INA_8	
R-	-0h	R	-0h	R-0h	R-0h	R-0h	R-0h	
7	6	5	4	3	2	1	0	
INA_7	INA_6	INA_5	INA_4	INA_3	INA_2	INA_1	INA_0	
R-0h	R-0h	R-0h	R-0h	R-0h	R-0h	R-0h	R-0h	

LEGEND: R = Read only

#### Table 17. IN\_STAT\_ADC0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-22	INA_17	R	0h	Oh = Input IN17 is below threshold 2A.  1h = Input IN17 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN17 is equal to or above threshold 2B.  3h = N/A
21-20	INA_16	R	0h	0h = Input IN16 is below threshold 2A.  1h = Input IN16 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN16 is equal to or above threshold 2B.  3h = N/A
19-18	INA_15	R	0h	0h = Input IN15 is below threshold 2A.  1h = Input IN15 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN15 is equal to or above threshold 2B.  3h = N/A
17-16	INA_14	R	0h	0h = Input IN14 is below threshold 2A.  1h = Input IN14 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN14 is equal to or above threshold 2B.  3h = N/A
15-14	INA_13	R	0h	0h = Input IN13 is below threshold 2A.  1h = Input IN13 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN13 is equal to or above threshold 2B.  3h = N/A
13-12	INA_12	R	0h	0h = Input IN12 is below threshold 2A.  1h = Input IN12 is below threshold 2B and equal to or above threshold 2A.  2h = Input IN12 is equal to or above threshold 2B.  3h = N/A

# Table 17. IN\_STAT\_ADC0 Register Field Descriptions (continued)

	1		1_	· · · ,
Bit	Field	Туре	Reset	Description
11	INA_11	R	0h	0h = Input IN11 is below configured threshold.
				1h = Input IN11 is above configured threshold.
10	INA_10	R	0h	0h = Input IN10 is below configured threshold.
				1h = Input IN10 is above configured threshold.
9	INA_9	R	0h	0h = Input IN9 is below configured threshold.
	_			1h = Input IN9 is above configured threshold.
8	INA_8	R	0h	· · · · · · · · · · · · · · · · · · ·
0	IIV/_0		OII	0h = Input IN8 is below configured threshold.
				1h = Input IN8 is above configured threshold.
7	INA_7	R	0h	0h = Input IN7 is below configured threshold.
				1h = Input IN7 is above configured threshold.
6	INA_6	R	0h	0h = Input IN6 is below configured threshold.
				1h = Input IN6 is above configured threshold.
5	INA_5	R	0h	0h = Input IN5 is below configured threshold.
				1h = Input IN5 is above configured threshold.
4	INA_4	R	0h	· · · · · · · · · · · · · · · · · · ·
				0h = Input IN4 is below configured threshold.
2	INIA O	D.	O.b.	1h = Input IN4 is above configured threshold.
3	INA_3	R	0h	0h = Input IN3 is below configured threshold.
				1h = Input IN3 is above configured threshold.
2	INA_2	R	0h	0h = Input IN2 is below configured threshold.
				1h = Input IN2 is above configured threshold.
1	INA_1	R	0h	0h = Input IN1 is below configured threshold.
				1h = Input IN1 is above configured threshold.
0	INA_0	R	0h	0h = Input IN0 is below configured threshold.
	_			1h = Input IN0 is above configured threshold.
				III = IIIput IIIV is above configured threshold.

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# 8.6.7 IN\_STAT\_ADC1 Register (Offset = 7h) [reset = 0h]

IN\_STAT\_ADC1 is shown in Figure 41 and described in Table 18.

Return to Summary Table.

This register indicates whether an input is above or below the programmed thresholds 3A, 3B, and 3C when it is configured as ADC input mode. For IN23, there are 5 thresholds that can be programmed.

Figure 41. IN\_STAT\_ADC1 Register

23	22	21	20	19	18	17	16	15	14	13	12
					RESERVED	)					INA_23
					R-0h						R-0h
11	10	9	8	7	6	5	4	3	2	1	0
INA	_23	INA	_22	INA	\_21	INA	_20	INA <sub>.</sub>	_19	INA	_18
R-	0h	R-	0h	R	-0h	R-	0h	R-0	0h	R-	0h

LEGEND: R = Read only

#### Table 18. IN\_STAT\_ADC1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-13	RESERVED	R	0h	Reserved
12-10	INA_23	R	0h	0h = Input IN23 is below threshold 3A.
				1h = Input IN23 is below threshold 3B and equal to or above threshold 3A.
				2h = Input IN23 is below threshold 3C and equal to or above threshold 3B.
				3h = Input IN23 is below threshold THRES8 and equal to or above threshold 3C.
				4h = Input IN23 is below threshold THRES9 and equal to or above threshold THRES8.
				5h = Input IN23 is equal to or above threshold THRES9.
9-8	INA_22	R	0h	0h = Input IN22 is below threshold 3A.
				1h = Input IN22 is below threshold 3B and equal to or above threshold 3A.
				2h = Input IN22 is below threshold 3C and equal to or above threshold 3B.
				3h = Input IN22 is equal to or above threshold 3C.
7-6	INA_21	R	0h	0h = Input IN21 is below threshold 3A.
				1h = Input IN21 is below threshold 3B and equal to or above threshold 3A.
				2h = Input IN21 is below threshold 3C and equal to or above threshold 3B.
				3h = Input IN21 is equal to or above threshold 3C.
5-4	INA_20	R	0h	0h = Input IN20 is below threshold 3A.
				1h = Input IN20 is below threshold 3B and equal to or above threshold 3A.
				2h = Input IN20 is below threshold 3C and equal to or above threshold 3B.
				3h = Input IN20 is equal to or above threshold 3C.
3-2	INA_19	R	0h	0h = Input IN19 is below threshold 3A.
				1h = Input IN19 is below threshold 3B and equal to or above threshold 3A.
				2h = Input IN19 is below threshold 3C and equal to or above threshold 3B.
				3h = Input IN19 is equal to or above threshold 3C.



# Table 18. IN\_STAT\_ADC1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
1-0	INA_18	R	0h	0h = Input is IN18 is below threshold 3A.
				1h = Input is IN18 is below threshold 3B and equal to or above threshold 3A.
				2h = Input is IN18 is below threshold 3C and equal to or above threshold 3B.
				3h = Input is IN18 is equal to or above threshold 3C.

## 8.6.8 IN\_STAT\_MATRIX0 Register (Offset = 8h) [reset = 0h]

IN\_STAT\_MATRIX0 is shown in Figure 42 and described in Table 19.

Return to Summary Table.

This register indicates whether an input is below or above the programmed threshold in the matrix polling mode for switches connected to IN10-IN13.

Figure 42. IN\_STAT\_MATRIX0 Register

23	22	21	20	19	18	17	16
INMAT_13_IN9	INMAT_13_IN8	INMAT_13_IN7	INMAT_13_IN6	INMAT_13_IN5	INMAT_13_IN4	INMAT_12_IN9	INMAT_12_IN8
R-0h							
15	14	13	12	11	10	9	8
INMAT_12_IN7	INMAT_12_IN6	INMAT_12_IN5	INMAT_12_IN4	INMAT_11_IN9	INMAT_11_IN8	INMAT_11_IN7	INMAT_11_IN6
R-0h							
7	6	5	4	3	2	1	0
INMAT_11_IN5	INMAT_11_IN4	INMAT_10_IN9	INMAT_10_IN8	INMAT_10_IN7	INMAT_10_IN6	INMAT_10_IN5	INMAT_10_IN4
R-0h							

LEGEND: R = Read only

#### Table 19. IN\_STAT\_MATRIX0 Register Field Descriptions

Field	Туре	Reset	Description
INMAT_13_IN9	R	Oh	0h = Input IN13 is below threshold while IN9 pulled to GND. 1h = Input IN13 is above threshold while IN9 pulled to GND.
INMAT_13_IN8	R	Oh	0h = Input IN13 is below threshold while IN8 pulled to GND. 1h = Input IN13 is above threshold while IN8 pulled to GND.
INMAT_13_IN7	R	0h	0h = Input IN13 is below threshold while IN7 pulled to GND. 1h = Input IN13 is above threshold while IN7 pulled to GND.
INMAT_13_IN6	R	0h	0h = Input IN13 is below threshold while IN6 pulled to GND. 1h = Input IN13 is above threshold while IN6 pulled to GND.
INMAT_13_IN5	R	Oh	0h = Input IN13 is below threshold while IN5 pulled to GND. 1h = Input IN13 is above threshold while IN5 pulled to GND.
INMAT_13_IN4	R	Oh	0h = Input IN13 is below threshold while IN4 pulled to GND. 1h = Input IN13 is above threshold while IN4 pulled to GND.
INMAT_12_IN9	R	Oh	0h = Input IN12 is below threshold while IN9 pulled to GND. 1h = Input IN12 is above threshold while IN9 pulled to GND.
INMAT_12_IN8	R	0h	0h = Input IN12 is below threshold while IN8 pulled to GND. 1h = Input IN12 is above threshold while IN8 pulled to GND.
INMAT_12_IN7	R	0h	0h = Input IN12 is below threshold while IN7 pulled to GND. 1h = Input IN12 is above threshold while IN7 pulled to GND.
INMAT_12_IN6	R	0h	0h = Input IN12 is below threshold while IN6 pulled to GND. 1h = Input IN12 is above threshold while IN6 pulled to GND.
INMAT_12_IN5	R	0h	0h = Input IN12 is below threshold while IN5 pulled to GND. 1h = Input IN12 is above threshold while IN5 pulled to GND.
INMAT_12_IN4	R	0h	0h = Input IN12 is below threshold while IN4 pulled to GND. 1h = Input IN12 is above threshold while IN4 pulled to GND.
INMAT_11_IN9	R	Oh	0h = Input IN11 is below threshold while IN9 pulled to GND. 1h = Input IN11 is above threshold while IN9 pulled to GND.
INMAT_11_IN8	R	0h	0h = Input IN11 is below threshold while IN8 pulled to GND. 1h = Input IN11 is above threshold while IN8 pulled to GND.
	INMAT_13_IN9  INMAT_13_IN8  INMAT_13_IN7  INMAT_13_IN6  INMAT_13_IN5  INMAT_13_IN4  INMAT_12_IN9  INMAT_12_IN9  INMAT_12_IN7  INMAT_12_IN6  INMAT_12_IN6  INMAT_12_IN5  INMAT_112_IN9	INMAT_13_IN9   R   R   INMAT_13_IN8   R   R   INMAT_13_IN7   R   INMAT_13_IN6   R   INMAT_13_IN5   R   INMAT_13_IN4   R   INMAT_12_IN9   R   INMAT_12_IN8   R   INMAT_12_IN6   R   INMAT_12_IN6   R   INMAT_12_IN5   R   INMAT_12_IN5   R   INMAT_12_IN4   R   INMAT_12_IN9   R   INMAT_12_IN9   R   INMAT_112_IN9   R   INMAT_112_IN9   R   INMAT_111_IN9   R   INMAT_111_I	INMAT_13_IN9

# Table 19. IN\_STAT\_MATRIX0 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
9	INMAT_11_IN7	R	0h	0h = Input IN11 is below threshold while IN7 pulled to GND. 1h = Input IN11 is above threshold while IN7 pulled to GND.
8	INMAT_11_IN6	R	0h	0h = Input IN11 is below threshold while IN6 pulled to GND. 1h = Input IN11 is above threshold while IN6 pulled to GND.
7	INMAT_11_IN5	R	0h	0h = Input IN11 is below threshold while IN5 pulled to GND. 1h = Input IN11 is above threshold while IN5 pulled to GND.
6	INMAT_11_IN4	R	0h	0h = Input IN11 is below threshold while IN4 pulled to GND. 1h = Input IN11 is above threshold while IN4 pulled to GND.
5	INMAT_10_IN9	R	0h	0h = Input IN10 is below threshold while IN9 pulled to GND. 1h = Input IN10 is above threshold while IN9 pulled to GND.
4	INMAT_10_IN8	R	0h	0h = Input IN10 is below threshold while IN8 pulled to GND. 1h = Input IN10 is above threshold while IN8 pulled to GND.
3	INMAT_10_IN7	R	0h	0h = Input IN10 is below threshold while IN7 pulled to GND. 1h = Input IN10 is above threshold while IN7 pulled to GND.
2	INMAT_10_IN6	R	0h	0h = Input IN10 is below threshold while IN6 pulled to GND. 1h = Input IN10 is above threshold while IN6 pulled to GND.
1	INMAT_10_IN5	R	0h	0h = Input IN10 is below threshold while IN5 pulled to GND. 1h = Input IN10 is above threshold while IN5 pulled to GND.
0	INMAT_10_IN4	R	0h	0h = Input IN10 is below threshold while IN4 pulled to GND. 1h = Input IN10 is above threshold while IN4 pulled to GND.

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#### 8.6.9 IN\_STAT\_MATRIX1 Register (Offset = 9h) [reset = 0h]

IN\_STAT\_MATRIX1 is shown in Figure 43 and described in Table 20.

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This register indicates whether an input is below or above the programmed threshold in the matrix polling mode for switches connected to IN14-IN15. This register also indicates the status of IN0-IN11 with respect to. the common threshold THRES\_COM.

Figure 43. IN\_STAT\_MATRIX1 Register

23	22	21	20	19	18	17	16
IN11_COM	IN10_COM	IN9_COM	IN8_COM	IN7_COM	IN6_COM	IN5_COM	IN4_COM
R-0h							
15	14	13	12	11	10	9	8
IN3_COM	IN2_COM	IN1_COM	IN0_COM	INMAT_15_IN9	INMAT_15_IN8	INMAT_15_IN7	INMAT_15_IN6
R-0h							
7	6	5	4	3	2	1	0
INMAT_15_IN5	INMAT_15_IN4	INMAT_14_IN9	INMAT_14_IN8	INMAT_14_IN7	INMAT_14_IN6	INMAT_14_IN5	INMAT_14_IN4
R-0h							

LEGEND: R = Read only

#### Table 20. IN\_STAT\_MATRIX1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23	IN11_COM	R	0h	0h = Input IN11 below threshold THRES_COM 1h = Input IN11 equal to or above threshold THRES_COM
22	IN10_COM	R	0h	0h = Input IN10 below threshold THRES_COM 1h = Input IN10 equal to or above threshold THRES_COM
21	IN9_COM	R	0h	0h = Input IN9 below threshold THRES_COM 1h = Input IN9 equal to or above threshold THRES_COM
20	IN8_COM	R	0h	0h = Input IN8 below threshold THRES_COM 1h = Input IN8 equal to or above threshold THRES_COM
19	IN7_COM	R	0h	0h = Input IN7 below threshold THRES_COM 1h = Input IN7 equal to or above threshold THRES_COM
18	IN6_COM	R	0h	0h = Input IN6 below threshold THRES_COM 1h = Input IN6 equal to or above threshold THRES_COM
17	IN5_COM	R	0h	0h = Input IN5 below threshold THRES_COM 1h = Input IN5 equal to or above threshold THRES_COM
16	IN4_COM	R	0h	0h = Input IN4 below threshold THRES_COM 1h = Input IN4 equal to or above threshold THRES_COM
15	IN3_COM	R	Oh	0h = Input IN3 below threshold THRES_COM 1h = Input IN3 equal to or above threshold THRES_COM
14	IN2_COM	R	0h	0h = Input IN2 below threshold THRES_COM 1h = Input IN2 equal to or above threshold THRES_COM
13	IN1_COM	R	Oh	0h = Input IN1 below threshold THRES_COM 1h = Input IN1 equal to or above threshold THRES_COM
12	IN0_COM	R	0h	0h = Input IN0 below threshold THRES_COM 1h = Input IN0 equal to or above threshold THRES_COM
11	INMAT_15_IN9	R	0h	0h = Input IN15 below threshold while IN9 pulled to GND 1h = Input IN15 above threshold while IN9 pulled to GND

# Table 20. IN\_STAT\_MATRIX1 Register Field Descriptions (continued)

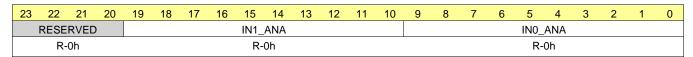
Bit	Field	Туре	Reset	Description
10	INMAT_15_IN8	R	0h	Oh = Input IN15 below threshold while IN8 pulled to GND  1h = Input IN15 above threshold while IN8 pulled to GND
9	INMAT_15_IN7	R	0h	0h = Input IN15 below threshold while IN7 pulled to GND 1h = Input IN15 above threshold while IN7 pulled to GND
8	INMAT_15_IN6	R	0h	0h = Input IN15 below threshold while IN6 pulled to GND 1h = Input IN15 above threshold while IN6 pulled to GND
7	INMAT_15_IN5	R	Oh	0h = Input IN15 below threshold while IN5 pulled to GND 1h = Input IN15 above threshold while IN5 pulled to GND
6	INMAT_15_IN4	R	Oh	0h = Input IN15 below threshold while IN4 pulled to GND 1h = Input IN15 above threshold while IN4 pulled to GND
5	INMAT_14_IN9	R	0h	0h = Input IN14 below threshold while IN9 pulled to GND 1h = Input IN14 above threshold while IN9 pulled to GND
4	INMAT_14_IN8	R	0h	0h = Input IN14 below threshold while IN8 pulled to GND 1h = Input IN14 above threshold while IN8 pulled to GND
3	INMAT_14_IN7	R	0h	0h = Input IN14 below threshold while IN7 pulled to GND 1h = Input IN14 above threshold while IN7 pulled to GND
2	INMAT_14_IN6	R	0h	0h = Input IN14 below threshold while IN6 pulled to GND 1h = Input IN14 above threshold while IN6 pulled to GND
1	INMAT_14_IN5	R	0h	0h = Input IN14 below threshold while IN5 pulled to GND 1h = Input IN14 above threshold while IN5 pulled to GND
0	INMAT_14_IN4	R	0h	0h = Input IN14 below threshold while IN4 pulled to GND 1h = Input IN14 above threshold while IN4 pulled to GND

8.6.10 ANA\_STAT0 Register (Offset = Ah) [reset = 0h]

ANA\_STAT0 is shown in Figure 44 and described in Table 21.

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# Figure 44. ANA\_STAT0 Register



LEGEND: R = Read only

## Table 21. ANA\_STAT0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN1_ANA	R	Oh	10-bits value of IN1 Bit 10: LSB Bit 19: MSB
9-0	INO_ANA	R	Oh	10-bits value of IN0 Bit 0: LSB Bit 9: MSB

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## 8.6.11 ANA\_STAT1 Register (Offset = Bh) [reset = 0h]

ANA\_STAT1 is shown in Figure 45 and described in Table 22.

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#### Figure 45. ANA\_STAT1 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED			IN5_ANA								IN4_ANA										
	R-	0h						R-	0h									R-	0h				

LEGEND: R = Read only

## Table 22. ANA\_STAT1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN3_ANA	R	Oh	10-bits value of IN3 Bit 10: LSB Bit 19: MSB
9-0	IN2_ANA	R	Oh	10-bits value of IN2 Bit 0: LSB Bit 9: MSB

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## 8.6.12 ANA\_STAT2 Register (Offset = Ch) [reset = 0h]

ANA\_STAT2 is shown in Figure 46 and described in Table 23.

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#### Figure 46. ANA\_STAT2 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED	)		IN5_ANA								IN4_ANA										
	R-	0h			R-0h												R-	0h					

LEGEND: R = Read only

# Table 23. ANA\_STAT2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN5_ANA	R	Oh	10-bits value of IN5 Bit 10: LSB Bit 19: MSB
9-0	IN4_ANA	R	Oh	10-bits value of IN4 Bit 0: LSB Bit 9: MSB

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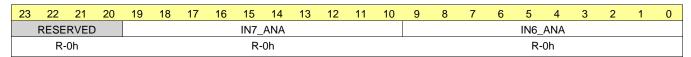
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## 8.6.13 ANA\_STAT3 Register (Offset = Dh) [reset = 0h]

ANA\_STAT3 is shown in Figure 47 and described in Table 24.

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## Figure 47. ANA\_STAT3 Register



LEGEND: R = Read only

## Table 24. ANA\_STAT3 Register Field Descriptions

Bit	Field	Туре	Reset	Description		
23-20	RESERVED	R	0h	Reserved		
19-10	IN7_ANA	R	Oh	10-bits value of IN7 Bit 10: LSB Bit 19: MSB		
9-0	IN6_ANA	R	Oh	10-bits value of IN6 Bit 0: LSB Bit 9: MSB		

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## 8.6.14 ANA\_STAT4 Register (Offset = Eh) [reset = 0h]

ANA\_STAT4 is shown in Figure 48 and described in Table 25.

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#### Figure 48. ANA\_STAT4 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
RESERVED IN9_ANA									IN8_ANA														
R-0h R-0h												R-	0h										

LEGEND: R = Read only

# Table 25. ANA\_STAT4 Register Field Descriptions

Bit	Field	Туре	Reset	Description		
23-20	RESERVED	R	0h	Reserved		
19-10	IN9_ANA	R	Oh	10-bits value of IN9 Bit 10: LSB Bit 19: MSB		
9-0	IN8_ANA	R	Oh	10-bits value of IN8 Bit 0: LSB Bit 9: MSB		

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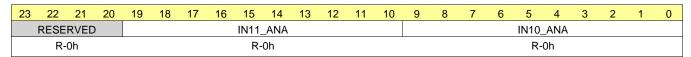
#### TEXAS INSTRUMENTS

## 8.6.15 ANA\_STAT5 Register (Offset = Fh) [reset = 0h]

ANA\_STAT5 is shown in Figure 49 and described in Table 26.

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## Figure 49. ANA\_STAT5 Register



LEGEND: R = Read only

## Table 26. ANA\_STAT5 Register Field Descriptions

Bit	Field	Туре	Reset	Description		
23-20	RESERVED	R	0h	Reserved		
19-10	IN11_ANA	R	Oh	10-bits value of IN11 Bit 10: LSB Bit 19: MSB		
9-0	IN10_ANA	R	Oh	10-bits value of IN10 Bit 0: LSB Bit 9: MSB		

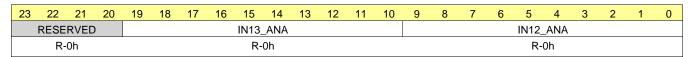
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#### 8.6.16 ANA\_STAT6 Register (Offset = 10h) [reset = 0h]

ANA\_STAT6 is shown in Figure 50 and described in Table 27.

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#### Figure 50. ANA\_STAT6 Register



LEGEND: R = Read only

#### Table 27. ANA\_STAT6 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN13_ANA	R	Oh	10-bits value of IN13 Bit 10: LSB Bit 19: MSB
9-0	IN12_ANA	R	Oh	10-bits value of IN12 Bit 0: LSB Bit 9: MSB

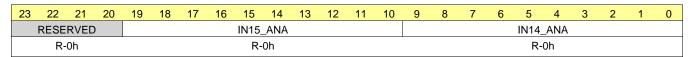
#### TEXAS INSTRUMENTS

#### 8.6.17 ANA\_STAT7 Register (Offset = 11h) [reset = 0h]

ANA\_STAT7 is shown in Figure 51 and described in Table 28.

Return to Summary Table.

#### Figure 51. ANA\_STAT7 Register



LEGEND: R = Read only

#### Table 28. ANA\_STAT7 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN15_ANA	R	Oh	10-bits value of IN15 Bit 10: LSB Bit 19: MSB
9-0	IN14_ANA	R	Oh	10-bits value of IN14 Bit 0: LSB Bit 9: MSB

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#### 8.6.18 ANA\_STAT8 Register (Offset = 12h) [reset = 0h]

ANA\_STAT8 is shown in Figure 52 and described in Table 29.

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#### Figure 52. ANA\_STAT8 Register



LEGEND: R = Read only

### Table 29. ANA\_STAT8 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN17_ANA	R	Oh	10-bits value of IN17 Bit 10: LSB Bit 19: MSB
9-0	IN16_ANA	R	Oh	10-bits value of IN16 Bit 0: LSB Bit 9: MSB

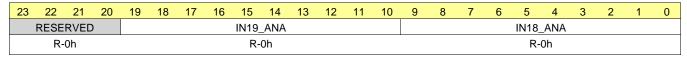


#### 8.6.19 ANA\_STAT9 Register (Offset = 13h) [reset = 0h]

ANA\_STAT9 is shown in Figure 53 and described in Table 30.

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#### Figure 53. ANA\_STAT9 Register



LEGEND: R = Read only

#### Table 30. ANA\_STAT9 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN19_ANA	R	Oh	10-bits value of IN19 Bit 10: LSB Bit 19: MSB
9-0	IN18_ANA	R	Oh	10-bits value of IN18 Bit 0: LSB Bit 9: MSB

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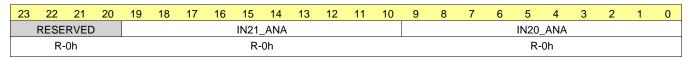


#### 8.6.20 ANA\_STAT10 Register (Offset = 14h) [reset = 0h]

ANA\_STAT10 is shown in Figure 54 and described in Table 31.

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### Figure 54. ANA\_STAT10 Register



LEGEND: R = Read only

### Table 31. ANA\_STAT10 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	IN21_ANA	R	Oh	10-bits value of IN21 Bit 10: LSB Bit 19: MSB
9-0	IN20_ANA	R	Oh	10-bits value of IN20 Bit 0: LSB Bit 9: MSB

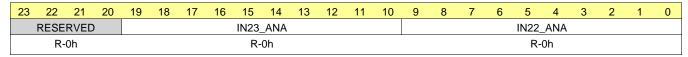


#### 8.6.21 ANA\_STAT11 Register (Offset = 15h) [reset = 0h]

ANA\_STAT11 is shown in Figure 55 and described in Table 32.

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#### Figure 55. ANA\_STAT11 Register



LEGEND: R = Read only

#### Table 32. ANA\_STAT11 Register Field Descriptions

Bit	Field	Туре	Reset	Description	
23-20	RESERVED	R	0h	Reserved	
19-10	IN23_ANA	R	Oh	10-bits value of IN23 Bit 10: LSB Bit 19: MSB	
9-0	IN22_ANA	R	Oh	10-bits value of IN22 Bit 0: LSB Bit 9: MSB	

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8.6.22 ANA\_STAT12 Register (Offset = 16h) [reset = 0h]

ANA\_STAT12 is shown in Figure 56 and described in Table 33.

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#### Figure 56. ANA\_STAT12 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED			ADC_SELF_ANA							V <sub>S</sub> _ANA											
	R-	0h			R-0h											R-	0h						

LEGEND: R = Read only

#### Table 33. ANA\_STAT12 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	ADC_SELF_ANA	R	Oh	10-bits value of the ADC self-diagnosis Bit 10: LSB Bit 19: MSB
9-0	V <sub>S</sub> _ANA	R	Oh	10-bits value of V <sub>S</sub> measurement Bit 0: LSB Bit 9: MSB

# 8.6.23 CONFIG Register (Offset = 1Ah) [reset = 0h]

CONFIG is shown in Figure 57 and described in Table 34.

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### Figure 57. CONFIG Register

23	22	21	20	19	18	17	16		
VS_RATIO	ADC_DIAG_T	WET_D_IN3_E N	WET_D_IN2_E N	WET_D_IN1_E N	WET_D_IN0_E N	VS_MEAS_EN	TW_CUR_DIS_ CSI		
R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h		
15	14	13	12	11	10	9	8		
DET_F	ILTER	TW_CUR_DIS_ CSO	INT_CONFIG	TRIGGER	POLL_EN	CRC_T	POLL_ACT_TI ME		
R/W	/-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h	R/W-0h		
7	6	5	4	3	2	1	0		
	POLL_ACT_TIME			POLL_TIME					
	R/W-0h			R/W-0h					

LEGEND: R/W = Read/Write

#### **Table 34. CONFIG Register Field Descriptions**

Bit	Field		Reset	Pagarintian
	- 1010	Туре		Description
23	VS_RATIO	R/W	0h	0h = Use voltage divider factor of 3 for the V <sub>S</sub> measurement
				1h = Use voltage divider factor of 10 for the V <sub>S</sub> measurement
22	ADC_DIAG_T	R/W	0h	For detailed descriptions for the ADC self-diagnostic feature, refer to section ADC Self-Diagnostic
				0h = Disable ADC self-diagnostic feature
				1h = Enable ADC self-diagnostic feature
21	WET_D_IN3_EN	R/W	0h	0h = Disable wetting current diagnostic for input IN3
				1h = Enable wetting current diagnostic for input IN3
20	WET_D_IN2_EN	R/W	0h	
			0	0h = Disable wetting current diagnostic for input IN2
				1h = Enable wetting current diagnostic for input IN2
19	WET_D_IN1_EN	R/W	0h	0h = Disable wetting current diagnostic for input IN1
				1h = Enable wetting current diagnostic for input IN1
18	WET_D_IN0_EN	R/W	0h	0h = Disable wetting current diagnostic for input IN0
				1h = Enable wetting current diagnostic for input IN0
17	VS_MEAS_EN	R/W	0h	For detailed descriptions for the V <sub>S</sub> measurement, refer to section VS Measurement.
				0h = Disable V <sub>S</sub> measurement at the end of every polling cycle
				1h = Enable V <sub>S</sub> measurement at the end of every polling cycle
16	TW_CUR_DIS_CSI	R/W	0h	0h = Enable wetting current reduction (to 2 mA) for 10mA and 15mA settings upon TW event for all inputs enabled with CSI.
				1h = Disable wetting current reduction (to 2 mA) for 10mA and 15mA settings upon TW event for all inputs enabled with CSI.
15-14	DET_FILTER	R/W	0h	For detailed descriptions for the detection filter, refer to section Detection Filter.
				0h = every sample is valid and taken for threshold evaluation
				1h = 2 consecutive and equal samples required to be valid data
				2h = 3 consecutive and equal samples required to be valid data
				3h = 4 consecutive and equal samples required to be valid data
13	TW_CUR_DIS_CSO	R/W	0h	0h = Enable wetting current reduction (to 2mA) for 10mA and 15mA settings upon TW event for all inputs enabled with CSO.
				1h = Disable wetting current reduction (to 2mA) for 10mA and 15mA settings upon TW event for all inputs enabled with CSO.

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# **Table 34. CONFIG Register Field Descriptions (continued)**

Bit	Field	Туре	Reset	Description
12	INT_CONFIG	R/W	0h	For detailed descriptions for the $\overline{\text{INT}}$ pin assertion scheme, refer to section Interrupt Generation and /INT Assertion.
				$0h = \overline{INT}$ pin assertion scheme set to static
				1h = $\overline{INT}$ pin assertion scheme set to dynamic
11	TRIGGER	R/W	Oh	When the TRIGGER bit is set to logic 1, normal device operation (wetting current activation and polling) starts. To stop device operation and keep the device in an idle state, de-assert this bit to 0. After device normal operation is triggered, if at any time the device setting needs to be re-configured, the microcontroller is required to first set the bit TRIGGER to logic 0 to stop device operation. Once the re-configuration is completed, the microcontroller can set the TRIGGER bit back to logic 1 to re-start device operation. If reconfiguration is done on the fly without first stopping the device operation, false switch status could be reported and accidental interrupt might be issued. The following register bits are the exception and can be configured when TRIGGER bit is set to logic 1:
				TRIGGER (bit 11 of the CONFIG register)
				CRC_T (bit 9 of the CONFIG register)
				RESEST (bit 0 of the CONFIG register)
				The CCP_CFG1 register
				0h = Stop TIC12400 from normal operation.
				1h = Trigger TIC12400 normal operation
10	POLL_EN	R/W	0h	0h = Polling disabled. Device operates in continuous mode.
				1h = Polling enabled and the device operates in one of the polling modes.
9	CRC_T	R/W	Oh	Set this bit to 1 to trigger a CRC calculation on all the configuration register bits. Once triggered, it is strongly recommended the SPI master does not change the content of the configuration registers until the CRC calculation is completed to avoid erroneous CRC calculation result. The TIC12400 sets the CRC_CALC interrupt bit and asserts the INT pin low when the CRC calculation is completed. The calculated result will be available in the CRC register. This bit self-clears back to 0 after CRC calculation is executed.
				0h = no CRC calculation triggered
				1h = trigger CRC calculation
8-5	POLL_ACT_TIME	R/W	0h	$0h = 64\mu s$
				1h = 128μs
				$2h = 192\mu s$
				3h = 256µs
				4h = 320µs
				5h = 384µs 6h = 448µs
				$6n = 448 \mu s$ $7h = 512 \mu s$
				8h = 640µs
				9h = 768µs
				Ah = 896µs
				Bh = 1024μs
				Ch = 2048μs
				Dh-15h = 512μs (most frequently-used setting)

# **Table 34. CONFIG Register Field Descriptions (continued)**

Bit	Field	Туре	Reset	Description
4-1	POLL_TIME	R/W	0h	0h = 2ms
				1h = 4ms
				2h = 8ms
				3h = 16ms
				4h = 32ms
				5h = 48ms
				6h = 64ms
				7h = 128ms
				8h = 256ms
				9h = 512ms
				Ah = 1024ms
				Bh = 2048ms
				Ch = 4096ms
				Dh-15h = 8ms (most frequently-used setting)
0	RESET	R/W	0h	0h = No reset
				1h = Trigger software reset of the device.

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### 8.6.24 IN\_EN Register (Offset = 1Bh) [reset = 0h]

IN\_EN is shown in Figure 58 and described in Table 35.

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#### Figure 58. IN\_EN Register

23	22	21	20	19	18	17	16
IN_EN_23	IN_EN_22	IN_EN_21	IN_EN_20	IN_EN_19	IN_EN_18	IN_EN_17	IN_EN_16
R/W-0h							
15	14	13	12	11	10	9	8
IN_EN_15	IN_EN_14	IN_EN_13	IN_EN_12	IN_EN_11	IN_EN_10	IN_EN_9	IN_EN_8
R/W-0h							
7	6	5	4	3	2	1	0
IN_EN_7	IN_EN_6	IN_EN_5	IN_EN_4	IN_EN_3	IN_EN_2	IN_EN_1	IN_EN_0
R/W-0h							

LEGEND: R/W = Read/Write

#### Table 35. IN\_EN Register Field Descriptions

R/W   Oh   Oh = Input channel IN23 disabled. Polling se channel   1h = Input channel IN23 enabled.   Polling se channel   1h = Input channel IN23 enabled.   Polling se channel   1h = Input channel IN22 disabled.   Polling se channel   1h = Input channel IN22 enabled.   Polling se channel   1h = Input channel IN21 disabled.   Polling se channel   1h = Input channel IN21 enabled.   Polling se channel   1h = Input channel IN20 disabled.   Polling se channel   1h = Input channel IN20 enabled.   Polling se channel   1h = Input channel IN19 disabled.   Polling se channel   IN_EN_19   R/W   Oh   Oh = Input channel IN19 enabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN18 disabled.   Polling se channel   IN_EN_18   R/W   Oh   Oh = Input channel IN218	quence skips thi	his
R/W   Oh   Oh = Input channel IN22 disabled. Polling se channel   1h = Input channel IN22 enabled.	quence skips thi	his
Second   Channel   INZ   disabled. Polling second   The Input channel   INZ   disabled. Polling   The Input channel   The I	quence skips thi	his
21 IN_EN_21 R/W Oh Oh = Input channel IN21 disabled. Polling se channel 1h = Input channel IN21 enabled.  20 IN_EN_20 R/W Oh Oh = Input channel IN20 disabled. Polling se channel 1h = Input channel IN20 enabled.  19 IN_EN_19 R/W Oh Oh = Input channel IN19 disabled. Polling se channel 1h = Input channel IN19 disabled. Polling se channel 1h = Input channel IN19 enabled.		
10		
20 IN_EN_20 R/W 0h 0h = Input channel IN20 disabled. Polling se channel 1h = Input channel IN20 enabled.  19 IN_EN_19 R/W 0h 0h = Input channel IN19 disabled. Polling se channel 1h = Input channel IN19 enabled.	quence skips thi	nis
19 IN_EN_19 R/W Oh Oh IN_EN_19	quence skips th	nis
19 IN_EN_19 R/W 0h 0h = Input channel IN19 disabled. Polling se channel 1h = Input channel IN19 enabled.		
channel  1h = Input channel IN19 disabled. Polling se channel  1h = Input channel IN19 enabled.		
40 IN 5N 40 PAW OF	quence skips thi	nis
18 IN FN 18 R/W Oh		
18 IN_EN_18 On Oh = Input channel IN18 disabled. Polling se channel	quence skips thi	nis
1h = Input channel IN18 enabled.		
17 IN_EN_17 R/W 0h = Input channel IN17 disabled. Polling se channel	quence skips thi	nis
1h = Input channel IN17 enabled.		
16 IN_EN_16 R/W 0h 0h = Input channel IN16 disabled. Polling se channel	uence skips thi	nis
1h = Input channel IN16 enabled.		
15 IN_EN_15 R/W 0h 0h = Input channel IN15 disabled. Polling se channel	quence skips thi	nis
1h = Input channel IN15 enabled.		
14 IN_EN_14 R/W 0h 0h = Input channel IN14 disabled. Polling se channel	quence skips thi	nis
1h = Input channel IN14 enabled.		
13 IN_EN_13 R/W 0h 0h = Input channel IN13 disabled. Polling se channel	uence skips thi	nis
1h = Input channel IN13 enabled.		

# Table 35. IN\_EN Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
12	IN_EN_12	R/W	0h	Oh = Input channel IN12 disabled. Polling sequence skips this channel  1h = Input channel IN12 enabled.
11	IN_EN_11	R/W	Oh	Oh = Input channel IN11 disabled. Polling sequence skips this channel  1h = Input channel IN11 enabled.
10	IN_EN_10	R/W	0h	Oh = Input channel IN10 disabled. Polling sequence skips this channel  1h = Input channel IN10 enabled.
9	IN_EN_9	R/W	0h	0h = Input channel IN9 disabled. Polling sequence skips this channel 1h = Input channel IN9 enabled.
8	IN_EN_8	R/W	0h	0h = Input channel IN8 disabled. Polling sequence skips this channel 1h = Input channel IN8 enabled.
7	IN_EN_7	R/W	0h	0h = Input channel IN7 disabled. Polling sequence skips this channel 1h = Input channel IN7 enabled.
6	IN_EN_6	R/W	0h	0h = Input channel IN6 disabled. Polling sequence skips this channel 1h = Input channel IN6 enabled.
5	IN_EN_5	R/W	0h	0h = Input channel IN5 disabled. Polling sequence skips this channel 1h = Input channel IN5 enabled.
4	IN_EN_4	R/W	0h	0h = Input channel IN4 disabled. Polling sequence skips this channel 1h = Input channel IN4 enabled.
3	IN_EN_3	R/W	0h	0h = Input channel IN3 disabled. Polling sequence skips this channel 1h = Input channel IN3 enabled.
2	IN_EN_2	R/W	0h	0h = Input channel IN2 disabled. Polling sequence skips this channel 1h = Input channel IN2 enabled.
1	IN_EN_1	R/W	0h	Oh = Input channel IN1 disabled. Polling sequence skips this channel 1h = Input channel IN1 enabled.
0	IN_EN_0	R/W	0h	Oh = Input channel INO disabled. Polling sequence skips this channel 1h = Input channel INO enabled.

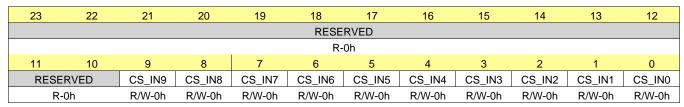


#### 8.6.25 CS\_SELECT Register (Offset = 1Ch) [reset = 0h]

CS\_SELECT is shown in Figure 59 and described in Table 36.

Return to Summary Table.

### Figure 59. CS\_SELECT Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 36. CS\_SELECT Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-10	RESERVED	R	0h	Reserved
9	CS_IN9	R/W	Oh	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
8	CS_IN8	R/W	Oh	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
7	CS_IN7	R/W	Oh	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
6	CS_IN6	R/W	0h	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
5	CS_IN5	R/W	0h	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
4	CS_IN4	R/W	0h	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
3	CS_IN3	R/W	0h	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
2	CS_IN2	R/W	0h	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
1	CS_IN1	R/W	Oh	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected
0	CS_IN0	R/W	Oh	0h = Current Source (CSO) selected 1h = Current Sink (CSI) selected

WC\_CFG0 is shown in Figure 60 and described in Table 37.

8.6.26 WC\_CFG0 Register (Offset = 1Dh) [reset = 0h]

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#### Figure 60. WC\_CFG0 Register

23	22	21	20	19 18 17 16 15				14	13	12	
	WC_IN11			WC_IN10			WC_IN8_IN9	9	WC_IN6_IN7		
	R/W-0h			R/W-0h			R/W-0h R/W-0h				
11	10	9	8	7	7 6 5 4 3		2	1	0		
	WC_IN5			WC_IN4			WC_IN2_IN3 WC_IN0_IN1				
	R/W-0h			R/W-0h		R/W-0h R/W-0h					

LEGEND: R/W = Read/Write

#### Table 37. WC\_CFG0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-21	WC_IN11	R/W	0h	0h = no wetting current 1h = 1mA (typ.) wetting current 2h = 2mA (typ.) wetting current 3h = 5mA (typ.) wetting current 4h = 10mA (typ.) wetting current 5h-7h = 15mA (typ.) wetting current
20-18	WC_IN10	R/W	Oh	0h = no wetting current 1h = 1mA (typ.) wetting current 2h = 2mA (typ.) wetting current 3h = 5mA (typ.) wetting current 4h = 10mA (typ.) wetting current 5h-7h = 15mA (typ.) wetting current
17-15	WC_IN8_IN9	R/W	0h	0h = no wetting current 1h = 1mA (typ.) wetting current 2h = 2mA (typ.) wetting current 3h = 5mA (typ.) wetting current 4h = 10mA (typ.) wetting current 5h-7h = 15mA (typ.) wetting current
14-12	WC_IN6_IN7	R/W	Oh	0h = no wetting current 1h = 1mA (typ.) wetting current 2h = 2mA (typ.) wetting current 3h = 5mA (typ.) wetting current 4h = 10mA (typ.) wetting current 5h-7h = 15mA (typ.) wetting current
11-9	WC_IN5	R/W	Oh	Oh = no wetting current  1h = 1mA (typ.) wetting current  2h = 2mA (typ.) wetting current  3h = 5mA (typ.) wetting current  4h = 10mA (typ.) wetting current  5h-7h = 15mA (typ.) wetting current
8-6	WC_IN4	R/W	Oh	0h = no wetting current 1h = 1mA (typ.) wetting current 2h = 2mA (typ.) wetting current 3h = 5mA (typ.) wetting current 4h = 10mA (typ.) wetting current 5h-7h = 15mA (typ.) wetting current

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## Table 37. WC\_CFG0 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
5-3	WC_IN2_IN3	R/W	0h	Oh = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current
2-0	WC_IN0_IN1	R/W	0h	Oh = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current

#### TEXAS INSTRUMENTS

#### 8.6.27 WC\_CFG1 Register (Offset = 1Eh) [reset = 0h]

WC\_CFG1 is shown in Figure 61 and described in Table 38.

Return to Summary Table.

#### Figure 61. WC\_CFG1 Register

23	22	21	20	19	18	17	16	15	14	13	12	
RESERV ED	AUTO_S CALE_DI S_CSI	AUTO_S CALE_DI S_CSO		WC_IN23			WC_IN22			WC_IN20_IN21		
R-0h	R/W-0h	R/W-0h		R/W-0h			R/W-0h			R/W-0h		
11	10	9	8	7	6	5	4	3	2	1	0	
W	WC_IN18_IN19 WC_IN16_IN17			WC_IN14_IN15			WC_IN12_IN13					
	R/W-0h R/W-0h			R/W-0h			R/W-0h					

LEGEND: R/W = Read/Write; R = Read only

#### Table 38. WC\_CFG1 Register Field Descriptions

Bit         Field         Type         Reset         Description           24-23         RESERVED         R         0h         Reserved           22         AUTO_SCALE_DIS_CSI         R/W         0h         0h = Enable wetting current auto-scaling (to mode for 10mA and 15mA settings upon switch enabled with CSI           1h = Disable wetting current auto-scaling (to mode for 10mA and 15mA settings upon switch enabled with CS           For detailed descriptions for the wetting current section Wetting Current Auto-Scaling.	closure for all inputs 2mA) in continuous closure for all inputs
22 AUTO_SCALE_DIS_CSI R/W 0h	closure for all inputs 2mA) in continuous closure for all inputs
mode for 10mA and 15mA settings upon switch enabled with CSI  1h = Disable wetting current auto-scaling (to mode for 10mA and 15mA settings upon switch enabled with CS  For detailed descriptions for the wetting current	closure for all inputs 2mA) in continuous closure for all inputs
mode for 10mA and 15mA settings upon switch enabled with CS  For detailed descriptions for the wetting current	closure for all inputs
	auto-scaling, refer to
	G.
AUTO_SCALE_DIS_CSO R/W 0h = Enable wetting current auto-scaling (to mode for 10mA and 15mA settings upon switch enabled with CSO	
1h = Disable wetting current auto-scaling (to mode for 10mA and 15mA settings upon switch enabled with CSO	
For detailed descriptions for the wetting current section Wetting Current Auto-Scaling.	auto-scaling, refer to
20-18 WC_IN23 R/W 0h oh = no wetting current	
1h = 1mA (typ.) wetting current	
2h = 2mA (typ.) wetting current	
3h = 5mA (typ.) wetting current	
4h = 10mA (typ.) wetting current	
5h-7h = 15mA (typ.) wetting current	
17-15 WC_IN22 R/W 0h 0h = no wetting current	
1h = 1mA (typ.) wetting current	
2h = 2mA (typ.) wetting current	
3h = 5mA (typ.) wetting current	
4h = 10mA (typ.) wetting current	
5h-7h = 15mA (typ.) wetting current	
14-12 WC_IN20_IN21 R/W 0h 0h = no wetting current	
1h = 1mA (typ.) wetting current	
2h = 2mA (typ.) wetting current	
3h = 5mA (typ.) wetting current	
4h = 10mA (typ.) wetting current	
5h-7h = 15mA (typ.) wetting current	



# Table 38. WC\_CFG1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
11-9	WC_IN18_IN19	R/W	0h	0h = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current
8-6	WC_IN16_IN17	R/W	0h	0h = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current
5-3	WC_IN14_IN15	R/W	0h	0h = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current
2-0	WC_IN12_IN13	R/W	0h	0h = no wetting current
				1h = 1mA (typ.) wetting current
				2h = 2mA (typ.) wetting current
				3h = 5mA (typ.) wetting current
				4h = 10mA (typ.) wetting current
				5h-7h = 15mA (typ.) wetting current

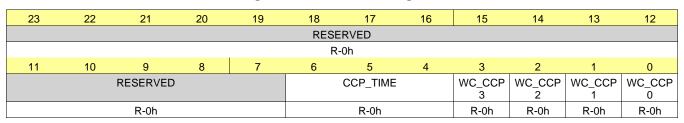
# Instruments

#### 8.6.28 CCP\_CFG0 Register (Offset = 1Fh) [reset = 0h]

CCP\_CFG0 is shown in Figure 62 and described in Table 39.

Return to Summary Table.

#### Figure 62. CCP\_CFG0 Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 39. CCP\_CFG0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-7	RESERVED	R	0h	Reserved
6-4	CCP_TIME	R/W	Oh	Wetting current activation time in CCP mode $0h = 64\mu s$ $1h = 128\mu s$ $2h = 192\mu s$ $3h = 256\mu s$ $4h = 320\mu s$ $5h = 384\mu s$ $6h = 448\mu s$ $7h = 512\mu s$
3	WC_CCP3	R/W	Oh	Wetting current setting for IN18 to IN23 in CCP mode 0h = 10mA (typ.) wetting current 1h = 15mA (typ.) wetting current
2	WC_CCP2	R/W	0h	Wetting current setting for IN12 to IN17 in CCP mode 0h = 10mA (typ.) wetting current 1h = 15mA (typ.) wetting current
1	WC_CCP1	R/W	0h	Wetting current setting for IN6 to IN11 in CCP mode  0h = 10mA (typ.) wetting current  1h = 15mA (typ.) wetting current
0	WC_CCP0	R/W	0h	Wetting current setting for IN0 to IN5 in CCP mode 0h = 10mA (typ.) wetting current 1h = 15mA (typ.) wetting current

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#### 8.6.29 CCP\_CFG1 Register (Offset = 20h) [reset = 0h]

CCP\_CFG1 is shown in Figure 63 and described in Table 40.

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Figure 63. CCP\_CFG1 Register

23	22	21	20	19	18	17	16
CCP_IN23	CCP_IN22	CCP_IN21	CCP_IN20	CCP_IN19	CCP_IN18	CCP_IN17	CCP_IN16
R/W-0h							
15	14	13	12	11	10	9	8
CCP_IN15	CCP_IN14	CCP_IN13	CCP_IN12	CCP_IN11	CCP_IN10	CCP_IN9	CCP_IN8
R/W-0h							
7	6	5	4	3	2	1	0
CCP_IN7	CCP_IN6	CCP_IN5	CCP_IN4	CCP_IN3	CCP_IN2	CCP_IN1	CCP_IN0
R/W-0h							

LEGEND: R/W = Read/Write

#### Table 40. CCP\_CFG1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23	CCP_IN23	R/W	Oh	0h = no CCP wetting current 1h = CCP wetting current activated
22	CCP_IN22	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
21	CCP_IN21	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
20	CCP_IN20	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
19	CCP_IN19	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
18	CCP_IN18	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
17	CCP_IN17	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
16	CCP_IN16	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
15	CCP_IN15	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
14	CCP_IN14	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
13	CCP_IN13	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
12	CCP_IN12	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated
11	CCP_IN11	R/W	Oh	0h = no CCP wetting current 1h = CCP wetting current activated
10	CCP_IN10	R/W	0h	0h = no CCP wetting current 1h = CCP wetting current activated

# Table 40. CCP\_CFG1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
9	CCP_IN9	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
8	CCP_IN8	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
7	CCP_IN7	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
6	CCP_IN6	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
5	CCP_IN5	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
4	CCP_IN4	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
3	CCP_IN3	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
2	CCP_IN2	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
1	CCP_IN1	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated
0	CCP_IN0	R/W	0h	0h = no CCP wetting current
				1h = CCP wetting current activated

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# 8.6.30 THRES\_COMP Register (Offset = 21h) [reset = 0h]

THRES\_COMP is shown in Figure 64 and described in Table 41.

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#### Figure 64. THRES\_COMP Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 41. THRES\_COMP Register Field Descriptions

Bit	Field	Туре	Reset	Description
31-12	RESERVED	R	0h	Reserved
11-10	THRES_COMP_IN20_IN2	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN20 to IN23
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V
9-8	THRES_COMP_IN16_IN1	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN16 to IN19
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V
7-6	THRES_COMP_IN12_IN1 5	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN12 to IN15
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V
5-4	THRES_COMP_IN8_IN11	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN8 to IN11
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V
3-2	THRES_COMP_IN4_IN7	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN4 to IN7
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V

# Table 41. THRES\_COMP Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
1-0	THRES_COMP_IN0_IN3	R/W	0h	These 2 bits configures the comparator thresholds for input channels IN0 to IN3
				0h = comparator threshold set to 2V
				1h = comparator threshold set to 2.7V
				2h = comparator threshold set to 3V
				3h = comparator threshold set to 4V



#### 8.6.31 INT\_EN\_COMP1 Register (Offset = 22h) [reset = 0h]

INT\_EN\_COMP1 is shown in Figure 65 and described in Table 42.

Return to Summary Table.

### Figure 65. INT\_EN\_COMP1 Register

23	22	21	20	19	18	17	16	15	14	13	12
INC_E	N_11	INC_E	N_10	INC_I	EN_9	INC_I	EN_8	INC_	EN_7	INC_I	EN_6
R/W	'-0h	R/W	-0h	R/W	/-0h	R/W-0h		R/W-0h		R/W-0h	
11	10	9	8	7	6	5	4	3	2	1	0
INC_E	EN_5	INC_E	EN_4	INC_I	EN_3	INC_I	EN_2	INC_	EN_1	INC_EN_0	
R/W	'-0h	R/W	-0h	R/W	/-0h	R/W	/-0h	R/W	/-0h	R/W-0h	

LEGEND: R/W = Read/Write

#### Table 42. INT\_EN\_COMP1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-22	INC_EN_11	R/W	0h	Oh = no interrupt generation for IN11  1h = interrupt generation on rising edge above THRES_COMP_IN8_IN11 for IN11
				2h = interrupt generation on falling edge below THRES_COMP_IN8_IN11 for IN11
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN8_IN11 for IN11
21-20	INC_EN_10	R/W	0h	0h = no interrupt generation for IN10
				1h = interrupt generation on rising edge above THRES_COMP_IN8_IN11 for IN10
				2h = interrupt generation on falling edge below THRES_COMP_IN8_IN11 for IN10
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN8_IN11 for IN10
19-18	INC_EN_9	R/W	0h	0h = no interrupt generation for IN9
				1h = interrupt generation on rising edge above THRES_COMP_IN8_IN11 for IN9
				2h = interrupt generation on falling edge below THRES_COMP_IN8_IN11 for IN9
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN8_IN11 for IN9
17-16	INC_EN_8	R/W	0h	0h = no interrupt generation for IN8
				1h = interrupt generation on rising edge above THRES_COMP_IN8_IN11 for IN8
				2h = interrupt generation on falling edge below THRES_COMP_IN8_IN11 for IN8
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN8_IN11 for IN8
15-14	INC_EN_7	R/W	0h	0h = no interrupt generation for IN7
				1h = interrupt generation on rising edge above THRES_COMP_IN4_IN7 for IN7
				2h = interrupt generation on falling edge below THRES_COMP_IN4_IN7 for IN7
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN4_IN7 for IN7

# Table 42. INT\_EN\_COMP1 Register Field Descriptions (continued)

THRES_COMP_IN4_IN7 for IN6  2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN6  3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN6  11-10 INC_EN_5 R/W 0h 0h = no interrupt generation for IN5  1h = interrupt generation on ris THRES_COMP_IN4_IN7 for IN5  2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN5  3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4 R/W 0h 0h = no interrupt generation for IN4	
11-10 INC_EN_5  R/W  Oh  Oh = no interrupt generation on rist THRES_COMP_IN4_IN7 for IN6  11-10 INC_EN_5  R/W  Oh  Oh = no interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  1h = interrupt generation for IN5  1h = interrupt generation on rist THRES_COMP_IN4_IN7 for IN5  2h = interrupt generation on rist THRES_COMP_IN4_IN7 for IN5  2h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4  R/W  Oh  Oh = no interrupt generation for IN4  1h = interrupt generation on rist generation genera	
2h = interrupt generation on far THRES_COMP_IN4_IN7 for IN6 3h = interrupt generation on falling at THRES_COMP_IN4_IN7 for IN6  11-10 INC_EN_5 R/W Oh Oh = no interrupt generation for IN5 1h = interrupt generation on ris THRES_COMP_IN4_IN7 for IN5 2h = interrupt generation on far THRES_COMP_IN4_IN7 for IN5 3h = interrupt generation on falling at THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4 R/W Oh Oh = no interrupt generation for IN4 1h = interrupt generation on ris	sing edge above
THRES_COMP_IN4_IN7 for IN6  11-10 INC_EN_5 R/W 0h 0h = no interrupt generation for IN5 1h = interrupt generation on ris THRES_COMP_IN4_IN7 for IN5 2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN5 3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4 R/W 0h 0h = no interrupt generation for IN4 1h = interrupt generation on ris	alling edge below
1h = interrupt generation on ris THRES_COMP_IN4_IN7 for IN5 2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN5 3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4 R/W 0h 0h = no interrupt generation for IN4 1h = interrupt generation on ris	and rising edge of
THRES_COMP_IN4_IN7 for IN5  2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN5  3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  9-8 INC_EN_4 R/W 0h 0h = no interrupt generation for IN4  1h = interrupt generation on ris	
9-8 INC_EN_4  R/W  THRES_COMP_IN4_IN7 for IN5  3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN5  Oh = no interrupt generation for IN4  1h = interrupt generation on ris	sing edge above
9-8 INC_EN_4 R/W 0h 0h = no interrupt generation for IN4 1h = interrupt generation on ris	alling edge below
1h = interrupt generation on ris	and rising edge of
	sing edge above
2h = interrupt generation on fa THRES_COMP_IN4_IN7 for IN4	alling edge below
3h = interrupt generation on falling a THRES_COMP_IN4_IN7 for IN4	and rising edge of
7-6 INC_EN_3 R/W 0h 0h = no interrupt generation for IN3	
1h = interrupt generation on ris THRES_COMP_IN0_IN3 for IN3	sing edge above
2h = interrupt generation on fa THRES_COMP_IN0_IN3 for IN3	alling edge below
3h = interrupt generation on falling a THRES_COMP_IN0_IN3 for IN3	and rising edge of
5-4 INC_EN_2 R/W 0h 0h = no interrupt generation for IN2	
1h = interrupt generation on ris THRES_COMP_IN0_IN3 for IN2	sing edge above
2h = interrupt generation on fa THRES_COMP_IN0_IN3 for IN2	alling edge below
3h = interrupt generation on falling a THRES_COMP_IN0_IN3 for IN2	and rising edge of
3-2 INC_EN_1 R/W 0h 0h = no interrupt generation for IN1	
1h = interrupt generation on ris THRES_COMP_IN0_IN3 for IN1	sing edge above
	alling edge below
3h = interrupt generation on falling a THRES_COMP_IN0_IN3 for IN1	and rising edge of
1-0 INC_EN_0 R/W 0h 0h = no interrupt generation for IN0	
	sing edge above
2h = interrupt generation on fa THRES_COMP_IN0_IN3 for IN0	alling edge below
3h = interrupt generation on falling a THRES_COMP_IN0_IN3 for IN0	and rising edge of



#### 8.6.32 INT\_EN\_COMP2 Register (Offset = 23h) [reset = 0h]

INT\_EN\_COMP2 is shown in Figure 66 and described in Table 43.

Return to Summary Table.

#### Figure 66. INT\_EN\_COMP2 Register

23	22	21	20	19	18	17	16	15	14	13	12
INC_E	N_23	INC_E	N_22	INC_E	N_21	INC_E	N_20	INC_E	N_19	INC_E	N_18
R/W	/-0h	R/W	-0h	R/W	/-0h	R/W	/-0h	R/W-0h		R/W-0h	
11	10	9	8	7	6	5	4	3	2	1	0
INC_E	N_17	INC_E	N_16	INC_E	N_15	INC_E	N_14	INC_E	N_13	INC_EN_12	
R/W	′-0h	R/W	-0h	R/W	/-0h	R/W-0h		R/W	/-0h	R/W-0h	

LEGEND: R/W = Read/Write

#### Table 43. INT\_EN\_COMP2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-22	INC_EN_23	R/W	0h	0h = no interrupt generation for IN23  1h = interrupt generation on rising edge above THRES_COMP_IN20_IN23 for IN23
				2h = interrupt generation on falling edge below THRES_COMP_IN20_IN23 for IN23
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN20_IN23 for IN23
21-20	INC_EN_22	R/W	0h	0h = no interrupt generation for IN22
				1h = interrupt generation on rising edge above THRES_COMP_IN20_IN23 for IN22
				2h = interrupt generation on falling edge below THRES_COMP_IN20_IN23 for IN22
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN20_IN23 for IN22
19-18	INC_EN_21	R/W	0h	0h = no interrupt generation for IN21
				1h = interrupt generation on rising edge above THRES_COMP_IN20_IN23 for IN21
				2h = interrupt generation on falling edge below THRES_COMP_IN20_IN23 for IN21
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN20_IN23 for IN21
17-16	INC_EN_20	R/W	0h	0h = no interrupt generation for IN20
				1h = interrupt generation on rising edge above THRES_COMP_IN20_IN23 for IN20
				2h = interrupt generation on falling edge below THRES_COMP_IN20_IN23 for IN20
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN20_IN23 for IN20
15-14	INC_EN_19	R/W	0h	0h = no interrupt generation for IN19
				1h = interrupt generation on rising edge above THRES_COMP_IN16_IN19 for IN19
				2h = interrupt generation on falling edge below THRES_COMP_IN16_IN19 for IN19
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN16_IN19 for IN19

# Table 43. INT\_EN\_COMP2 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
13-12	INC_EN_18	R/W	0h	0h = no interrupt generation for IN18
				1h = interrupt generation on rising edge above THRES_COMP_IN16_IN19 for IN18
				2h = interrupt generation on falling edge below THRES_COMP_IN16_IN19 for IN18
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN16_IN19 for IN18
11-10	INC_EN_17	R/W	0h	0h = no interrupt generation for IN17
				1h = interrupt generation on rising edge above THRES_COMP_IN16_IN19 for IN17
				2h = interrupt generation on falling edge below THRES_COMP_IN16_IN19 for IN17
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN16_IN19 for IN17
9-8	INC_EN_16	R/W	0h	0h = no interrupt generation for IN16
				1h = interrupt generation on rising edge above THRES_COMP_IN16_IN19 for IN16
				2h = interrupt generation on falling edge below THRES_COMP_IN16_IN19 for IN16
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN16_IN19 for IN16
7-6	INC_EN_15	R/W	0h	0h = no interrupt generation for IN15
				1h = interrupt generation on rising edge above THRES_COMP_IN12_IN15 for IN15
				2h = interrupt generation on falling edge below THRES_COMP_IN12_IN15 for IN15
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN12_IN15 for IN15
5-4	INC_EN_14	R/W	0h	0h = no interrupt generation for IN14
				1h = interrupt generation on rising edge above THRES_COMP_IN12_IN15 for IN14
				2h = interrupt generation on falling edge below THRES_COMP_IN12_IN15 for IN14
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN12_IN15 for IN14
3-2	INC_EN_13	R/W	0h	0h = no interrupt generation for IN13
				1h = interrupt generation on rising edge above THRES_COMP_IN12_IN15 for IN13
				2h = interrupt generation on falling edge below THRES_COMP_IN12_IN15 for IN13
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN12_IN15 for IN13
1-0	INC_EN_12	R/W	0h	Oh = no interrupt generation for IN12
				1h = interrupt generation on rising edge above THRES_COMP_IN12_IN15 for IN12
				2h = interrupt generation on falling edge below THRES_COMP_IN12_IN15 for IN12
				3h = interrupt generation on falling and rising edge of THRES_COMP_IN12_IN15 for IN12

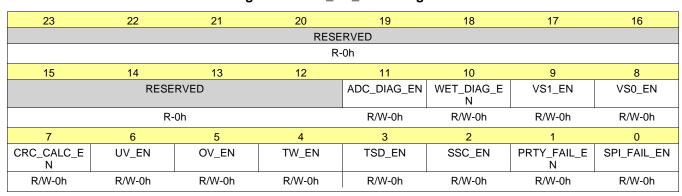
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8.6.33 INT\_EN\_CFG0 Register (Offset = 24h) [reset = 0h]

INT\_EN\_CFG0 is shown in Figure 67 and described in Table 44.

Return to Summary Table.

#### Figure 67. INT\_EN\_CFG0 Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 44. INT\_EN\_CFG0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-12	RESERVED	R	0h	Reserved
11	ADC_DIAG_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to ADC error disabled.  1h = $\overline{\text{INT}}$ pin assertion due to ADC error enabled.
10	WET_DIAG_EN	R/W	0h	0h = INT pin assertion due to wetting current error disabled.  1h = INT pin assertion due to wetting current error enabled.
9	VS1_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to VS1 threshold crossing disabled.  1h = $\overline{\text{INT}}$ pin assertion due to VS1 threshold crossing enabled.
8	VS0_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to VS0 threshold crossing disabled.  1h = $\overline{\text{INT}}$ pin assertion due to VS0 threshold crossing enabled.
7	CRC_CALC_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to CRC calculation completion disabled.  1h = $\overline{\text{INT}}$ pin assertion due to CRC calculation completion enabled.
6	UV_EN	R/W	0h	0h = INT pin assertion due to UV event disabled.  1h = INT pin assertion due to UV event enabled.
5	OV_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to OV event disabled.  1h = $\overline{\text{INT}}$ pin assertion due to OV event enabled.
4	TW_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to TW event disabled.  1h = $\overline{\text{INT}}$ pin assertion due to TW event enabled.
3	TSD_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to TSD event disabled.  1h = $\overline{\text{INT}}$ pin assertion due to TSD event enabled.
2	SSC_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to SSC event disabled.  1h = $\overline{\text{INT}}$ pin assertion due to SSC event enabled.
1	PRTY_FAIL_EN	R/W	0h	0h = $\overline{\text{INT}}$ pin assertion due to parity fail event disabled.  1h = $\overline{\text{INT}}$ pin assertion due to parity fail event enabled.
0	SPI_FAIL_EN	R/W	0h	0h = INT pin assertion due to SPI fail event disabled. 1h = INT pin assertion due to SPI fail event enabled.

# Instruments

#### 8.6.34 INT\_EN\_CFG1 Register (Offset = 25h) [reset = 0h]

INT\_EN\_CFG1 is shown in Figure 68 and described in Table 45.

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#### Figure 68. INT\_EN\_CFG1 Register

23	22	21	20	19	18	17	16	15	14	13	12
IN11	_EN	IN10	_EN	IN9_	_EN	IN8_	_EN	IN7	_EN	IN6_	_EN
R/W	/-0h	R/W	-0h	R/W	/-0h	R/W	/-0h	R/W	V-0h	R/W-0h	
11	10	9	8	7	6	5	4	3	2	1	0
IN5_	EN	IN4_	EN	IN3_	_EN	IN2_	_EN	IN1	_EN	INO_	_EN
R/W	R/W-0h R/W-0h		R/W-0h		R/W-0h		R/W-0h		R/W-0h		

LEGEND: R/W = Read/Write

#### Table 45. INT\_EN\_CFG1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-22	IN11_EN	R/W	Oh	Oh = no interrupt generation for IN11  1h = interrupt generation on rising edge above THRESx for IN11  2h = interrupt generation on falling edge below THRESx for IN11  3h = interrupt generation on falling and rising edge of THRESx for IN11
21-20	IN10_EN	R/W	Oh	0h = no interrupt generation for IN10 1h = interrupt generation on rising edge above THRESx for IN10 2h = interrupt generation on falling edge below THRESx for IN10 3h = interrupt generation on falling and rising edge of THRESx for IN10
19-18	IN9_EN	R/W	Oh	Oh = no interrupt generation for IN9  1h = interrupt generation on rising edge above THRESx for IN9  2h = interrupt generation on falling edge below THRESx for IN9  3h = interrupt generation on falling and rising edge of THRESx for IN9
17-16	IN8_EN	R/W	Oh	Oh = no interrupt generation for IN8  1h = interrupt generation on rising edge above THRESx for IN8  2h = interrupt generation on falling edge below THRESx for IN8  3h = interrupt generation on falling and rising edge of THRESx for IN8
15-14	IN7_EN	R/W	0h	0h = no interrupt generation for IN7 1h = interrupt generation on rising edge above THRESx for IN7 2h = interrupt generation on falling edge below THRESx for IN7 3h = interrupt generation on falling and rising edge of THRESx for IN7
13-12	IN6_EN	R/W	Oh	Oh = no interrupt generation for IN6  1h = interrupt generation on rising edge above THRESx for IN6  2h = interrupt generation on falling edge below THRESx for IN6  3h = interrupt generation on falling and rising edge of THRESx for IN6
11-10	IN5_EN	R/W	Oh	Oh = no interrupt generation for IN5  1h = interrupt generation on rising edge above THRESx for IN5  2h = interrupt generation on falling edge below THRESx for IN5  3h = interrupt generation on falling and rising edge of THRESx for IN5



# Table 45. INT\_EN\_CFG1 Register Field Descriptions (continued)

Bit	Field	Type	Reset	Description
		Туре		Description
9-8	IN4_EN	R/W	0h	0h = no interrupt generation for IN4
				1h = interrupt generation on rising edge above THRESx for IN4
				2h = interrupt generation on falling edge below THRESx for IN4
				3h = interrupt generation on falling and rising edge of THRESx for IN4
7-6	IN3_EN	R/W	0h	0h = no interrupt generation for IN3
				1h = interrupt generation on rising edge above THRESx for IN3
				2h = interrupt generation on falling edge below THRESx for IN3
				3h = interrupt generation on falling and rising edge of THRESx for IN3
5-4	IN2_EN	R/W	0h	0h = no interrupt generation for IN2
				1h = interrupt generation on rising edge above THRESx for IN2
				2h = interrupt generation on falling edge below THRESx for IN2
				3h = interrupt generation on falling and rising edge of THRESx for IN2
3-2	IN1_EN	R/W	0h	0h = no interrupt generation for IN1
				1h = interrupt generation on rising edge above THRESx for IN1
				2h = interrupt generation on falling edge below THRESx for IN1
				3h = interrupt generation on falling and rising edge of THRESx for IN1
1-0	IN0_EN	R/W	0h	0h = no interrupt generation for IN0
				1h = interrupt generation on rising edge above THRESx for IN0
				2h = interrupt generation on falling edge below THRESx for IN0
				3h = interrupt generation on falling and rising edge of THRESx for IN0



#### 8.6.35 INT\_EN\_CFG2 Register (Offset = 26h) [reset = 0h]

INT\_EN\_CFG2 is shown in Figure 69 and described in Table 46.

Return to Summary Table.

#### Figure 69. INT\_EN\_CFG2 Register

23	22	21	20	19	18	17	16	15	14	13	12	
	IN17	_EN			IN16	EN		IN15_EN				
	R/W-0h				R/W-0h				R/W-0h			
11	10	9	8	7 6 5 4 3 2 1 0					0			
	IN14_EN				IN13_EN				IN12_EN			
	R/W-0h				R/W-0h				R/W-0h			

LEGEND: R/W = Read/Write

### Table 46. INT\_EN\_CFG2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	IN17_EN	R/W	0h	xx00: no interrupt generation for IN17 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN17
				xx10: interrupt generation on falling edge below THRES2A for IN17
				xx11: interrupt generation on falling and rising edge of THRES2A for IN17
				00xx: no interrupt generation for IN17 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN17
				10xx: interrupt generation on falling edge below THRES2B for IN17
				11xx: interrupt generation on falling and rising edge of THRES2B for IN17
19-16	IN16_EN	R/W	0h	xx00: no interrupt generation for IN16 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN16
				xx10: interrupt generation on falling edge below THRES2A for IN16
				xx11: interrupt generation on falling and rising edge of THRES2A for IN16
				00xx: no interrupt generation for IN16 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN16
				10xx: interrupt generation on falling edge below THRES2B for IN16
				11xx: interrupt generation on falling and rising edge of THRES2B for IN16
15-12	IN15_EN	R/W	0h	xx00: no interrupt generation for IN15 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN15
				xx10: interrupt generation on falling edge below THRES2A for IN15
				xx11: interrupt generation on falling and rising edge of THRES2A for IN15
				00xx: no interrupt generation for IN15 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN15
				10xx: interrupt generation on falling edge below THRES2B for IN15
				11xx: interrupt generation on falling and rising edge of THRES2B for IN15



# Table 46. INT\_EN\_CFG2 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
11-8	IN14_EN	R/W	0h	· ·
				xx00: no interrupt generation for IN14 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN14
				xx10: interrupt generation on falling edge below THRES2A for IN14
				xx11: interrupt generation on falling and rising edge of THRES2A for IN14
				00xx: no interrupt generation for IN14 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN14
				10xx: interrupt generation on falling edge below THRES2B for IN14
				11xx: interrupt generation on falling and rising edge of THRES2B for IN14
7-4	IN13_EN	R/W	0h	xx00: no interrupt generation for IN13 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN13
				xx10: interrupt generation on falling edge below THRES2A for IN13
				xx11: interrupt generation on falling and rising edge of THRES2A for IN13
				00xx: no interrupt generation for IN13 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN13
				10xx: interrupt generation on falling edge below THRES2B for IN13
				11xx: interrupt generation on falling and rising edge of THRES2B for IN13
3-0	IN12_EN	R/W	0h	xx00: no interrupt generation for IN12 w.r.t. THRES2A
				xx01: interrupt generation on rising edge above THRES2A for IN12
				xx10: interrupt generation on falling edge below THRES2A for IN12
				xx11: interrupt generation on falling and rising edge of THRES2A for IN12
				00xx: no interrupt generation for IN12 w.r.t. THRES2B
				01xx: interrupt generation on rising edge above THRES2B for IN12
				10xx: interrupt generation on falling edge below THRES2B for IN12
				11xx: interrupt generation on falling and rising edge of THRES2B for IN12

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#### 8.6.36 INT\_EN\_CFG3 Register (Offset = 27h) [reset = 0h]

INT\_EN\_CFG3 is shown in Figure 70 and described in Table 47.

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#### Figure 70. INT\_EN\_CFG3 Register

23	22	21	20	19	18	17	16	15	14	13	12		
		IN21	_EN		IN20_EN								
		R/W	/-0h		R/W-0h								
11	10	9	8	7	6	5	4	3	2	1	0		
	IN19_EN							IN18_EN					
	R/W-0h							R/W-0h					

LEGEND: R/W = Read/Write

#### Table 47. INT\_EN\_CFG3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-18	IN21_EN	R/W	0h	xxxx00: no interrupt generation for IN21 w.r.t. THRES3A
				xxxx01: interrupt generation on rising edge above THRES3A for IN21
				xxxx10: interrupt generation on falling edge below THRES3A for IN21
				xxxx11: interrupt generation on falling and rising edge of THRES3A for IN21
				xx00xx: no interrupt generation for IN21 w.r.t. THRES3B
				xx01xx: interrupt generation on rising edge above THRES3B for IN21
				xx10xx: interrupt generation on falling edge below THRES3B for IN21
				xx11xx: interrupt generation on falling and rising edge of THRES3B for IN21
				00xxxx: no interrupt generation for IN21 w.r.t. THRES3C
				01xxxx: interrupt generation on rising edge above THRES3C for IN21
				10xxxx: interrupt generation on falling edge below THRES3C for IN21
				11xxxx: interrupt generation on falling and rising edge of THRES3C for IN21
17-12	IN20_EN	R/W	0h	xxxx00: no interrupt generation for IN20 w.r.t. THRES3A
				xxxx01: interrupt generation on rising edge above THRES3A for IN20
				xxxx10: interrupt generation on falling edge below THRES3A for IN20
				xxxx11: interrupt generation on falling and rising edge of THRES3A for IN20
				xx00xx: no interrupt generation for IN20 w.r.t. THRES3B
				xx01xx: interrupt generation on rising edge above THRES3B for IN20
				xx10xx: interrupt generation on falling edge below THRES3B for IN20
				xx11xx: interrupt generation on falling and rising edge of THRES3B for IN20
				00xxxx: no interrupt generation for IN20 w.r.t. THRES3C
				01xxxx: interrupt generation on rising edge above THRES3C for IN20
				10xxxx: interrupt generation on falling edge below THRES3C for IN20
				11xxxx: interrupt generation on falling and rising edge of THRES3C for IN20



## Table 47. INT\_EN\_CFG3 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
11-6	IN19_EN	R/W	0h	xxxx00: no interrupt generation for IN19 w.r.t. THRES3A
				xxxx01: interrupt generation on rising edge above THRES3A for IN19
				xxxx10: interrupt generation on falling edge below THRES3A for IN19
				xxxx11: interrupt generation on falling and rising edge of THRES3A for IN19
				xx00xx: no interrupt generation for IN19 w.r.t. THRES3B
				xx01xx: interrupt generation on rising edge above THRES3B for IN19
				xx10xx: interrupt generation on falling edge below THRES3B for IN19
				xx11xx: interrupt generation on falling and rising edge of THRES3B for IN19
				00xxxx: no interrupt generation for IN19 w.r.t. THRES3C
				01xxxx: interrupt generation on rising edge above THRES3C for IN19
				10xxxx: interrupt generation on falling edge below THRES3C for IN19
				11xxxx: interrupt generation on falling and rising edge of THRES3C for IN19
5-0	IN18_EN	R/W	0h	xxxx00: no interrupt generation for IN18 w.r.t. THRES3A
				xxxx01: interrupt generation on rising edge above THRES3A for IN18
				xxxx10: interrupt generation on falling edge below THRES3A for IN18
				xxxx11: interrupt generation on falling and rising edge of THRES3A for IN18
				xx00xx: no interrupt generation for IN18 w.r.t. THRES3B
				xx01xx: interrupt generation on rising edge above THRES3B for IN18
				xx10xx: interrupt generation on falling edge below THRES3B for IN18
				xx11xx: interrupt generation on falling and rising edge of THRES3B for IN18
				00xxxx: no interrupt generation for IN18 w.r.t. THRES3C
				01xxxx: interrupt generation on rising edge above THRES3C for IN18
				10xxxx: interrupt generation on falling edge below THRES3C for IN18
				11xxxx: interrupt generation on falling and rising edge of THRES3C for IN18



#### 8.6.37 INT\_EN\_CFG4 Register (Offset = 28h) [reset = 0h]

INT\_EN\_CFG4 is shown in Figure 71 and described in Table 48.

Return to Summary Table.

#### Figure 71. INT\_EN\_CFG4 Register

23	22	21	20	19	18	17	16	15	14	13	12	
	VS_TH	H1_EN			VS_TH	HO_EN		IN23_EN				
	R/W-0h				R/W	/-0h		R/W-0h				
11	10	9	8	7	6	5	4	3	2	1	0	
	IN23_EN						IN22_EN					
		R/W	/-0h					R/W	V-0h			

LEGEND: R/W = Read/Write

#### Table 48. INT\_EN\_CFG4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	VS_TH1_EN	R/W	0h	xx00: no interrupt generation for V <sub>S</sub> w.r.t. VS1_THRES2A
				xx01: interrupt generation on rising edge above VS1_THRES2A for $\ensuremath{\text{V}_{\text{S}}}$
				xx10: interrupt generation on falling edge below VS1_THRES2A for $\rm V_{\rm S}$
				xx11: interrupt generation on falling and rising edge of VS1_THRES2A for $\rm V_S$
				00xx: no interrupt generation for V <sub>S</sub> w.r.t. VS1_THRES2B
				01xx: interrupt generation on rising edge above VS1_THRES2B for $\ensuremath{\text{V}_{\text{S}}}$
				10xx: interrupt generation on falling edge below VS1_THRES2B for $\rm V_{S}$
				11xx: interrupt generation on falling and rising edge of VS1_THRES2B for $\rm V_S$
19-16	VS_TH0_EN	R/W	0h	xx00: no interrupt generation for V <sub>S</sub> w.r.t. VS0_THRES2A
				xx01: interrupt generation on rising edge above VS0_THRES2A for $\rm V_{\rm S}$
				xx10: interrupt generation on falling edge below VS0_THRES2A for $\rm V_{\rm S}$
				xx11: interrupt generation on falling and rising edge of VS0_THRES2A for VS
				00xx: no interrupt generation for V <sub>S</sub> w.r.t. VS0_THRES2B
				01xx: interrupt generation on rising edge above VS0_THRES2B for $\ensuremath{\text{V}_{\text{S}}}$
				10xx: interrupt generation on falling edge below VS0_THRES2B for $\rm V_{\rm S}$
				11xx: interrupt generation on falling and rising edge of VS0_THRES2B for $\mathrm{V}_{\mathrm{S}}$



## Table 48. INT\_EN\_CFG4 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
15-6	IN23_EN	R/W	0h	xxxxxxxx00: no interrupt generation for IN23 w.r.t. THRES3A
				xxxxxxxxx01: interrupt generation on rising edge above THRES3A for IN23
				xxxxxxxx10: interrupt generation on falling edge below THRES3A for IN23
				xxxxxxxx11: interrupt generation on falling and rising edge of THRES3A for IN23
				xxxxxx00xx: no interrupt generation for IN23 w.r.t. THRES3B
				xxxxxx01xx: interrupt generation on rising edge above THRES3B for IN23
				xxxxxx10xx: interrupt generation on falling edge below THRES3B for IN23
				xxxxxx11xx: interrupt generation on falling and rising edge of THRES3B for IN23
				xxxx00xxxx: no interrupt generation for IN23 w.r.t. THRES3C
				xxxx01xxxx: interrupt generation on rising edge above THRES3C for IN23
				xxxx10xxxx: interrupt generation on falling edge below THRES3C for IN23
				xxxx11xxxx: interrupt generation on falling and rising edge of THRES3C for IN23
				xx00xxxxxx: no interrupt generation for IN23 w.r.t. THRES8
				xx01xxxxxx: interrupt generation on rising edge above THRES8 for IN23
				xx10xxxxxx: interrupt generation on falling edge below THRES8 for IN23
				xx11xxxxxx: interrupt generation on falling and rising edge of THRES8 for IN23
				00xxxxxxxx: no interrupt generation for IN23 w.r.t. THRES9
				01xxxxxxxx: interrupt generation on rising edge above THRES9 for IN23
				10xxxxxxxx: interrupt generation on falling edge below THRES9 for IN23
				11xxxxxxxx: interrupt generation on falling and rising edge of THRES9 for IN23
5-0	IN22_EN	R/W	0h	xxxx00: no interrupt generation for IN22 w.r.t. THRES3A
				xxxx01: interrupt generation on rising edge above THRES3A for IN22
				xxxx10: interrupt generation on falling edge below THRES3A for IN22
				xxxx11: interrupt generation on falling and rising edge of THRES3A for IN22
				xx00xx: no interrupt generation for IN22 w.r.t. THRES3B
				xx01xx: interrupt generation on rising edge above THRES3B for IN22
				xx10xx: interrupt generation on falling edge below THRES3B for IN22
				xx11xx: interrupt generation on falling and rising edge of THRES3B for IN22
				00xxxx: no interrupt generation for IN22 w.r.t. THRES3C
				01xxxx: interrupt generation on rising edge above THRES3C for IN22
				10xxxx: interrupt generation on falling edge below THRES3C for IN22
				11xxxx: interrupt generation on falling and rising edge of THRES3C for IN22

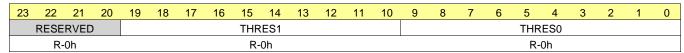


#### 8.6.38 THRES\_CFG0 Register (Offset = 29h) [reset = 0h]

THRES\_CFG0 is shown in Figure 72 and described in Table 49.

Return to Summary Table.

### Figure 72. THRES\_CFG0 Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 49. THRES\_CFG0 Register Field Descriptions

Bit	Field	Туре	Reset	Description	
31-20	RESERVED	R	0h	Reserved	
19-10	THRES1	R/W	Oh	10-bits value of threshold 1: Bit10: LSB Bit19: MSB	
9-0	THRES0	R/W	Oh	10-bits value of threshold 0 Bit0: LSB Bit9: MSB	



## 8.6.39 THRES\_CFG1 Register (Offset = 2Ah) [reset = 0h]

THRES\_CFG1 is shown in Figure 73 and described in Table 50.

Return to Summary Table.

## Figure 73. THRES\_CFG1 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED	)		THRES3								THRES2										
	R-	0h			R-0h												R-	0h					

LEGEND: R/W = Read/Write; R = Read only

## Table 50. THRES\_CFG1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	THRES3	R/W	0h	10-bits value of threshold 3: Bit10: LSB Bit19: MSB
9-0	THRES2	R/W	0h	10-bits value of threshold 2 Bit0: LSB Bit9: MSB

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## 8.6.40 THRES\_CFG2 Register (Offset = 2Bh) [reset = 0h]

THRES\_CFG2 is shown in Figure 74 and described in Table 51.

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## Figure 74. THRES\_CFG2 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED	)		THRES5								THRES4										
	R-	0h			R-0h								R-0h										

LEGEND: R/W = Read/Write; R = Read only

## Table 51. THRES\_CFG2 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-20	RESERVED	R	0h	Reserved
19-10	THRES5	R/W	Oh	10-bits value of threshold 5: Bit10: LSB Bit19: MSB
10-1	THRES4	R/W	0h	10-bits value of threshold 4: Bit0: LSB Bit9: MSB



## 8.6.41 THRES\_CFG3 Register (Offset = 2Ch) [reset = X]

THRES\_CFG3 is shown in Figure 75 and described in Table 52.

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## Figure 75. THRES\_CFG3 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED	)		THRES6								THRES7										
	R-	0h			R-0h								R-0h										

LEGEND: R/W = Read/Write; R = Read only

## Table 52. THRES\_CFG3 Register Field Descriptions

Bit	Field	Туре	Reset	Description
31-20	RESERVED	R	0h	Reserved
19-10	THRES7	R/W	Oh	10-bits value of threshold 7: Bit10: LSB Bit19: MSB
9-0	THRES6	R/W	Oh	10-bits value of threshold 6: Bit0: LSB Bit9: MSB

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## 8.6.42 THRES\_CFG4 Register (Offset = 2Dh) [reset = X]

THRES\_CFG4 is shown in Figure 76 and described in Table 53.

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## Figure 76. THRES\_CFG4 Register

23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
	RESE	RVED	)		THRES9									THRES8									
	R-	0h			R-0h													R-	0h				

LEGEND: R/W = Read/Write; R = Read only

## Table 53. THRES\_CFG4 Register Field Descriptions

Bit	Field	Туре	Reset	Description
31-20	RESERVED	R	0h	Reserved
19-10	THRES9	R/W	Oh	10-bits value of threshold 9: Bit10: LSB Bit19: MSB
9-0	THRES8	R/W	Oh	10-bits value of threshold 8: Bit0: LSB Bit9: MSB

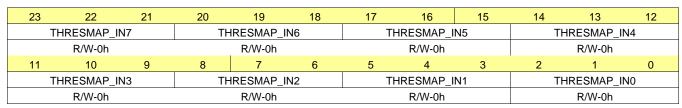
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# 8.6.43 THRESMAP\_CFG0 Register (Offset = 2Eh) [reset = 0h]

THRESMAP\_CFG0 is shown in Figure 77 and described in Table 54.

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## Figure 77. THRESMAP\_CFG0 Register



LEGEND: R/W = Read/Write

#### Table 54. THRESMAP\_CFG0 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-21	THRESMAP_IN7	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
20-18	THRESMAP_IN6	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
17-15	THRESMAP_IN5	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
14-12	THRESMAP_IN4	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7

# Table 54. THRESMAP\_CFG0 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
11-9	THRESMAP_IN3	R/W	Oh	0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6
8-6	THRESMAP_IN2	R/W	Oh	7h = THRES7  0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4
5-3	THRESMAP_IN1	R/W	0h	5h = THRES5 6h = THRES6 7h = THRES7 0h = THRES0
				1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6 7h = THRES7
2-0	THRESMAP_IN0	R/W	Oh	0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6 7h = THRES7

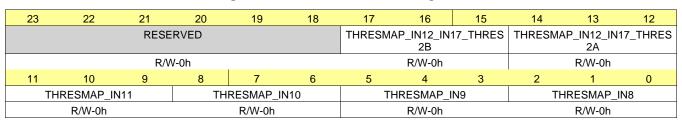
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## 8.6.44 THRESMAP\_CFG1 Register (Offset = 2Fh) [reset = 0h]

THRESMAP\_CFG1 is shown in Figure 78 and described in Table 55.

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## Figure 78. THRESMAP\_CFG1 Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 55. THRESMAP\_CFG1 Register Field Descriptions

Bit	Field	Туре	Reset	Description
23-18	RESERVED	R	0h	Reserved
17-15	THRESMAP_IN12_IN17_ THRES2B	R/W	Oh	0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5
14-12	THRESMAP_IN12_IN17_ THRES2A	R/W	0h	6h = THRES6 7h = THRES7 0h = THRES0 1h = THRES1
				2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6 7h = THRES7
11-9	THRESMAP_IN11	R/W	Oh	0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6 7h = THRES7
8-6	THRESMAP_IN10	R/W	Oh	0h = THRES0 1h = THRES1 2h = THRES2 3h = THRES3 4h = THRES4 5h = THRES5 6h = THRES6 7h = THRES7

# Table 55. THRESMAP\_CFG1 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
5-3	THRESMAP_IN9	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
2-0	THRESMAP_IN8	R/W	0h	0h = THRES0
				1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7

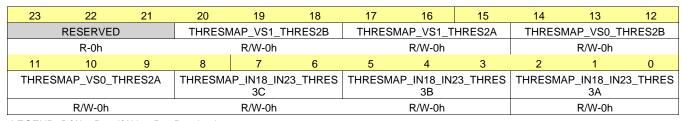
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## 8.6.45 THRESMAP\_CFG2 Register (Offset = 30h) [reset = 0h]

THRESMAP\_CFG2 is shown in Figure 79 and described in Table 56.

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## Figure 79. THRESMAP\_CFG2 Register



LEGEND: R/W = Read/Write; R = Read only

#### Table 56. THRESMAP\_CFG2 Register Field Descriptions

23-21 RESERVED R Oh Reserved	
20 40 TUDECMAD VC4 TUDE DAM OF	
20-18 THRESMAP_VS1_THRE R/W 0h 0h = THRES0	
S2B 1h = THRES1	
2h = THRES2	
3h = THRES3	
4h = THRES4	
5h = THRES5	
6h = THRES6	
7h = THRES7	
17-15 THRESMAP_VS1_THRE R/W 0h 0h = THRES0	
S2A 1h = THRES1	
2h = THRES2	
3h = THRES3	
4h = THRES4	
5h = THRES5	
6h = THRES6	
7h = THRES7	
14-12 THRESMAP_VS0_THRE R/W 0h 0h = THRES0	
S2B 1h = THRES1	
2h = THRES2	
3h = THRES3	
4h = THRES4	
5h = THRES5	
6h = THRES6	
7h = THRES7	
11-9 THRESMAP_VS0_THRE R/W 0h 0h = THRES0	
S2A 1h = THRES1	
2h = THRES2	
3h = THRES3	
4h = THRES4	
5h = THRES5	
6h = THRES6	
7h = THRES7	

# Table 56. THRESMAP\_CFG2 Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
8-6	THRESMAP_IN18_IN23_	R/W	0h	0h = THRES0
	THRES3C			1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
5-3	THRESMAP_IN18_IN23_	R/W	0h	0h = THRES0
	THRES3B			1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7
2-0	THRESMAP_IN18_IN23_	R/W	0h	0h = THRES0
	THRES3A			1h = THRES1
				2h = THRES2
				3h = THRES3
				4h = THRES4
				5h = THRES5
				6h = THRES6
				7h = THRES7

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# 8.6.46 Matrix Register (Offset = 31h) [reset = 0h]

Matrix is shown in Figure 80 and described in Table 57.

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#### Figure 80. Matrix Register

23	22	21	20	19	18	17	16	15	14	13	12
RESERVED						IN_CC	M_EN	Т	HRES_COM	И	
			R-0h				R/W	/-0h		R/W-0h	
11	10	9	8	7	6	5	4	3	2	1	0
THRES_COM						MAT	RIX	POL	L_ACT_TIM	E_M	
R/W-0h						R/W	/-0h		R/W-0h		

LEGEND: R/W = Read/Write; R = Read only

## **Table 57. Matrix Register Field Descriptions**

Bit	Field	Туре	Reset	Description
23-17	RESERVED	R	0h	Reserved
16-15	IN_COM_EN	R/W	0h	0h = no interrupt generation for w.r.t. threshold THRES_COM
				1h = interrupt generation on rising edge above threshold THRES_COM
				2h = interrupt generation on falling edge below threshold THRES_COM
				3h = interrupt generation on falling and rising edge of threshold THRES_COM
14-5	THRES_COM	R/W	0h	10-bits value of threshold THRES_COM:
				Bit5: LSB
				Bit14: MSB
4-3	MATRIX	R/W	0h	0h = no matrix, regular inputs only
				1h = 4x4 matrix
				2h = 5x5 matrix
				3h = 6x6 matrix
2-0	POLL_ACT_TIME_M	R/W	0h	Polling active time setting for the matrix inputs:
				$0h = 64\mu s$
				$1h = 128\mu s$
				$2h = 256\mu s$
				$3h = 384 \mu s$
				4h = 512μs
				5h = 768µs
				6h = 1024μs
				$7h = 1360 \mu s$

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# INSTRUMENTS

# 8.6.47 Mode Register (Offset = 32h) [reset = 0h]

Mode is shown in Figure 81 and described in Table 58.

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## Figure 81. Mode Register

23	22	21	20	19	18	17	16	15	14	13	12
M_IN23	M_IN22	M_IN21	M_IN20	M_IN19	M_IN18	M_IN17	M_IN16	M_IN15	M_IN14	M_IN13	M_IN12
R/W-0h											
11	10	9	8	7	6	5	4	3	2	1	0
M_IN11	M_IN10	M_IN9	M_IN8	M_IN7	M_IN6	M_IN5	M_IN4	M_IN3	M_IN2	M_IN1	M_IN0
R/W-0h											

LEGEND: R/W = Read/Write

## **Table 58. Mode Register Field Descriptions**

Bit	Field	Туре	Reset	Description
23	M_IN23	R/W	0h	0h = comparator mode for IN23 1h = ADC mode for IN23
22	M_IN22	R/W	0h	0h = comparator mode for IN22 1h = ADC mode for IN22
21	M_IN21	R/W	0h	0h = comparator mode for IN21 1h = ADC mode for IN21
20	M_IN20	R/W	0h	0h = comparator mode for IN20 1h = ADC mode for IN20
19	M_IN19	R/W	0h	0h = comparator mode for IN19 1h = ADC mode for IN19
18	M_IN18	R/W	0h	0h = comparator mode for IN18 1h = ADC mode for IN18
17	M_IN17	R/W	0h	0h = comparator mode for IN17 1h = ADC mode for IN17
16	M_IN16	R/W	0h	0h = comparator mode for IN16 1h = ADC mode for IN16
15	M_IN15	R/W	0h	0h = comparator mode for IN15 1h = ADC mode for IN15
14	M_IN14	R/W	0h	0h = comparator mode for IN14 1h = ADC mode for IN14
13	M_IN13	R/W	0h	0h = comparator mode for IN13 1h = ADC mode for IN13
12	M_IN12	R/W	0h	0h = comparator mode for IN12 1h = ADC mode for IN12
11	M_IN11	R/W	0h	0h = comparator mode for IN11 1h = ADC mode for IN11
10	M_IN10	R/W	0h	0h = comparator mode for IN10 1h = ADC mode for IN10
9	M_IN9	R/W	0h	0h = comparator mode for IN9 1h = ADC mode for IN9
8	M_IN8	R/W	0h	0h = comparator mode for IN8 1h = ADC mode for IN8

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#### Table 58. Mode Register Field Descriptions (continued)

Bit	Field	Туре	Reset	Description
7	M_IN7	R/W	0h	0h = comparator mode for IN7 1h = ADC mode for IN7
6	M_IN6	R/W	0h	0h = comparator mode for IN6 1h = ADC mode for IN6
5	M_IN5	R/W	0h	0h = comparator mode for IN5 1h = ADC mode for IN5
4	M_IN4	R/W	0h	0h = comparator mode for IN4 1h = ADC mode for IN4
3	M_IN3	R/W	0h	0h = comparator mode for IN3 1h = ADC mode for IN1
2	M_IN2	R/W	0h	0h = comparator mode for IN2 1h = ADC mode for IN0
1	M_IN1	R/W	0h	0h = comparator mode for IN1 1h = ADC mode for IN1
0	M_INO	R/W	0h	0h = comparator mode for IN0 1h = ADC mode for IN0

# 8.7 Programming Guidelines

When configuring the TIC12400, it is critical to follow the programming guideline summarized below (see Table 59) to ensure proper behavior of the device.

## Table 59. TIC12400 Programming Guidelines

Category	Programming requirement
Threshold setup:     Continuous mode     Regular polling mode     Matrix mode (non-matrix inputs)	<ul> <li>THRES2B ≥ THRES2A (for IN12 to IN17)</li> <li>THRES3C ≥ THRES3B ≥ THRES3A (for IN18 to IN22)</li> <li>THRES9 ≥ THRES8 ≥ THRES3C ≥ THRES3B ≥ THRES3A (for IN23)</li> </ul>
Threshold setup:  V <sub>S</sub> measurement	<ul><li>VS0_THRES2B &gt; VS0_THRES2A</li><li>VS1_THRES2B &gt; VS1_THRES2A</li></ul>
4x4 matrix mode (MATRIX [4:3] = 2'b01)	<ul> <li>POLL_EN=1</li> <li>IN_EN[7:4]=4'b1111; IN_EN[13:10]= 4'b1111</li> <li>MODE[7:4] = 4'b0000; MODE[13:10] = 4'b0000</li> <li>CS_SELECT[7:4]= 4'b1111; CS_SELECT[13:10]= 4'b0000</li> <li>IWETT(CSI) &gt; IWETT (CSO):</li></ul>



#### **Programming Guidelines (continued)**

## Table 59. TIC12400 Programming Guidelines (continued)

Tubic 00:	TIC 12400 Programming Guidennes (continued)
Category	Programming requirement
5x5 matrix mode (MATRIX [4:3] = 2'b10)	<ul> <li>POLL_EN=1</li> <li>IN_EN[8:4]= 4'b1111; IN_EN[14:10]= 4'b1111</li> <li>MODE[8:4] = 4'b0000; MODE[14:10] = 4'b0000</li> <li>CS_SELECT[8:4]= 4'b1111; CS_SELECT[14:10]= 4'b0000</li> <li>IWETT(CSI) &gt; IWETT (CSO):</li></ul>
6x6 Matrix Mode (MATRIX [4:3]= 2'b11)	<ul> <li>POLL_EN=1</li> <li>IN_EN[9:4]= 4'b1111; IN_EN[15:10]= 4'b1111</li> <li>MODE[9:4] = 4'b0000; MODE[15:10] = 4'b0000</li> <li>CS_SELECT[9:4]= 4'b1111; CS_SELECT[15:10]= 4'b0000</li> <li>IWETT(CSI) &gt; IWETT (CSO):         <ol> <li>WC_CFG0[20:18] &gt; WC_CFG0[8:6]</li> <li>WC_CFG0[23:21] &gt; WC_CFG0[11:9]</li> <li>WC_CFG1[2:0] &gt; WC_CFG0[14:12]</li> <li>WC_CFG1[5:3] &gt; WC_CFG0[17:15]</li> </ol> </li> <li>If TW event is expected, CSO can only be set to 1mA or 2mA:             <ol> <li>If WC_CFG0[8:6]= 3'b001: WC_CFG0[20:18]= 3'b010, 3'b011, 3'b100, 3'b110, 3'b110, or 3'b111; If WC_CFG0[8:6]= 3'b010: WC_CFG0[20:18]= 3'b011</li> <li>If WC_CFG0[11:9]= 3'b001: WC_CFG0[23:21]= 3'b010, 3'b011, 3'b100, 3'b110, or 3'b111; If WC_CFG0[11:9]= 3'b010: WC_CFG0[23:21]= 3'b011</li> </ol> </li> <li>If WC_CFG1[2:0]= 3'b001: WC_CFG0[14:12]= 3'b010, 3'b011, 3'b100, 3'b101, 3'b110, or 3'b111; If WC_CFG1[2:0]= 3'b010: WC_CFG0[14:12]= 3'b011</li> <li>If WC_CFG1[5:3]= 3'b001: WC_CFG0[17:15]= 3'b010, 3'b011, 3'b100, 3'b101, 3'b110, or 3'b111; If WC_CFG1[5:3]= 3'b010: WC_CFG0[17:15]= 3'b011</li> </ul>
Clean Current Polling (if CCP_INx= 1 in the CCP_CFG1 register)	At least one input (standard or matrix) or the VS measurement has to be enabled: IN_EN_x= 1 in the IN_EN register or CONFIG [16]= 1'b1 (1)
Wetting current auto-scaling (if WC_CFG1 [22:21] != 2b'11)	<ul> <li>The wetting current auto-scaling feature is only activated in the continuous mode: POLL_EN= 0 (2)</li> <li>The wetting current auto-scaling only applies to 10mA or 15mA wetting currents: WC_INx bits = 3'b100, 3'b101, 3'b110, or 3'b111 in the WC_CFG0 and WC_CFG1 registers. (2)</li> </ul>
Wetting current diagnostic (If CONFIG [21:18] != 4b'0000)	<ul> <li>At least one channel has to be enabled from IN0 to IN3 (IN_EN[3:0] != 4b'0000)</li> <li>Inputs IN0 to IN3 need to be configured to ADC input mode: MODE[3:0] = 4'b1111</li> <li>Inputs IN0 and IN1 need to be configured to CSO: CS SELECT [1:0]= 2b'00</li> <li>Inputs IN2 and IN3 need to be configured to CSI: CS SELECT [3:2]= 2b'11</li> </ul>
<ul><li>Continuous mode</li><li>Standard polling mode</li></ul>	t <sub>POLL_TIME</sub> and t <sub>POLL_ACT_TIME</sub> settings have to meet the below requirement: t <sub>POLL_TIME</sub> ≥ 1.3 ×[ t <sub>POLL_ACT_TIME</sub> + n × 24μs + 10 μs] <sup>(3)(4)</sup> • n: the number of enabled channels configured in register IN_EN • t <sub>POLL_TIME</sub> : timing setting configured in CONFIG[4:1] • t <sub>POLL_ACT_TIME</sub> : timing setting configured in CONFIG[8:5]

<sup>(1)</sup> This is a soft requirement to take advantage of the clean current polling feature. The feature takes no effect otherwise.

<sup>(2)</sup> These are soft requirements to take advantage of the wetting current auto-scaling feature. The feature takes no effect otherwise.

<sup>(3)</sup> If WCD is enable, add additional 96µs

<sup>(4)</sup> If CCP is enabled, add t<sub>CCP\_TRAN</sub> + t<sub>CCP\_TIME</sub>, where t<sub>CCP\_TIME</sub> is the timing setting configured in CCP\_CFG0[6:4]

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# **Programming Guidelines (continued)**

# Table 59. TIC12400 Programming Guidelines (continued)

Category	Programming requirement
	t <sub>POLL_TIME</sub> ,t <sub>POLL_ACT_TIME</sub> , and t <sub>POLL_ACT_TIME_M</sub> settings have to meet the below requirement:
Matrix polling mode	t <sub>POLL_TIME</sub> > 1.3 x [ m x t <sub>POLL_ACT_TIME_M</sub> + t <sub>POLL_ACT_TIME</sub> + n x 24μs + 10 μs] (3) (4)  • n: the number of enabled channels configured in register IN_EN  • m: 16 for 4x4 matrix; 25 for 5x5 matrix; 36 for 6x6 matrix
	<ul> <li>t<sub>POLL_TIME</sub>: timing setting configured in CONFIG[4:1]</li> <li>t<sub>POLL_ACT_TIME_M</sub>: timing setting configured in MATRIX[2:0]</li> </ul>
	tpoll_ACT_TIME_M. timing setting configured in MATRIX[2.0]     tpoll_ACT_TIME: timing setting configured in CONFIG[8:5]

#### 9 Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### 9.1 Application Information

The TIC12400 is an advanced 24-input Multiple Switch Detection Interface (MSDI) device designed to detect external switch status and voltage levels by acting as an interface between the switches and the low-voltage microcontroller. The device offers a number of unique features to replace systems implemented with discrete components, providing board space savings and reduced bill of material (BOM). The device can also be configured into low-power polling mode, which provides significant savings on system power consumption. The TIC12400 is also suitable for many types of data acquisition systems with its integrated ADC, serialization, and digital communication capabilities.

#### 9.2 Digital IO Switches and Analog Voltage Monitoring

The input stage of the TIC12400 is designed so that for an input resistance of 400  $\Omega$  on the IN0 - IN9 pins, the 10 mA current sink setting can be used for IEC61131-2 Type1, Type 2, and Type 3 switches.

Figure 82 depicts how the TIC12400 is used in a multiple purpose application with Digital IO Switches an analog sensor inputs using both the internal comparator and the ADC.

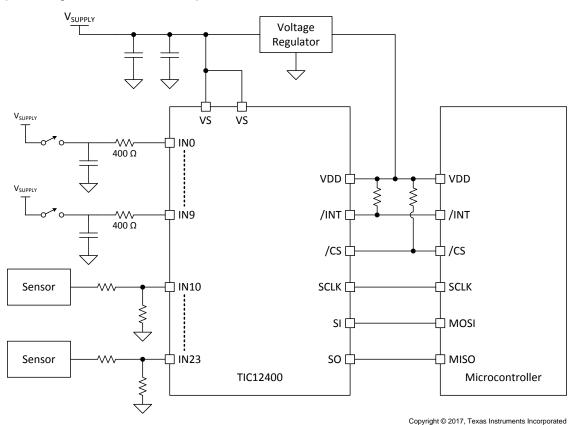


Figure 82. Using TIC12400 to Monitor digital IO switches and analog sensor inputs

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#### Digital IO Switches and Analog Voltage Monitoring (continued)

#### 9.2.1 Design Requirements

Table 60. Example Digital IO Switch Specification

	Specification	Min	Max
V <sub>SUPPLY</sub>	6.5 V ≤ V <sub>SUPPLY</sub> ≤ 18 V	6.5 V	18 V
R <sub>IN</sub>	400 Ω ± 10%	360 Ω	440 Ω
I <sub>SINK</sub>	10 mA	9.2 mA	13.4 mA

#### 9.2.2 Detailed Design Procedure

For digital I/O applications, the inputs must be connected to the IN0 - IN9 pins as these are the only inputs that have the current sink necessary to facilitate these type of switches. The external resistor must be sized so that the pin voltage  $V_{\text{INX}}$  remains below the max comparator threshold of 4.7 V until the current sink is saturated by the pin voltage. This ensures a low will always be considered a low as the external system voltage  $V_{\text{IN}}$  continues to increase. Lower comparator voltages can be used if the external components are sized to ensure that until the current sink is saturated, the voltage remains below the comparator threshold.

To select the resistor for a digital I/O application, ensure the voltage on the IN $_{\rm X}$  pin (IN0 - IN9) remains below the comparator threshold until the input voltage V $_{\rm IN}$  is above the OFF region defined by the IEC standard. With a 400- $\Omega$  resistor and worst case current of 9.2 mA, a 3.68 V voltage drop is observer across the resistor. This keeps the V $_{\rm INX}$  3.68 V below the system input V $_{\rm IN}$ , ensuring that comparator does not detect a high until V $_{\rm IN}$  is out of the OFF region and in the ON region.

The second use case for TIC12400 is to monitor analog input voltages from external sensors. These sensors could be a high or low type sensor that has a 1 or 0 representation of the output. In this case, the comparator mode of the input can be used. To ensure correct operation, a voltage divider may be necessary to scale the incoming voltage so that a low will be below the chosen comparator threshold. For reference the available comparator thresholds are 2 V, 2.7 V, 3 V, and 4 V.

For multi level sensor outputs the TIC12400 internal ADC can be used to set to monitor analog input voltages. The following procedure can be used to setup the TIC12400 ADC inputs

- 1. The first step is to set any input that will be used in a pure analog ADC mode to the 0 mA current setting.
- 2. The second step is to estimate the voltage output of the sensor. The full-scale range of the 10-bit ADC is from 0 V to 6 V, with 6 V corresponding to the max code of 1023. A resistor divider can be used to scale the input voltage to meet this requirement by using V<sub>IN</sub> = V<sub>SENSOR OUTPUT</sub> x R1/(R1+ R2) = 6 V max.
- 3. The next step is to determine if a wake up feature is needed that uses the ADC thresholds. This could be used to wake up the system in the case that a temperature sensor has indicated a potentially damaging temperature that requires system interaction to fix. The TIC12400 can handle two input states on inputs IN0 IN11, three input states on inputs IN12 IN17, 4 input states on IN18 IN22 and 6 input states on IN 23. Every threshold crossing can trigger an interrupt if required by the system. If no interrupt triggers are needed move on to step three.
- 4. After the measurement is taken, the raw ADC code will be stored in the ANA\_STAT registers to be read by the host for interpretation.

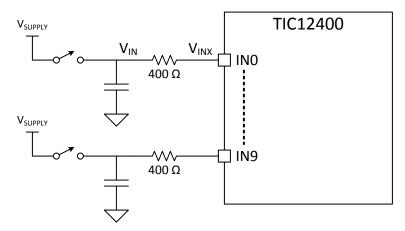


Figure 83. Digital IO Switch Input Example

# 9.2.3 Application Curves

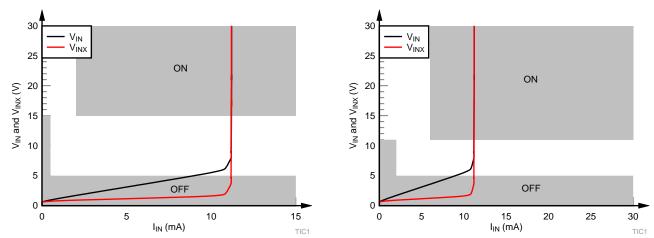


Figure 84. Type-1 Switch with 400- $\Omega$  Input Resistor Figure 85. Type-2 Switch with 400- $\Omega$  Input Resistor

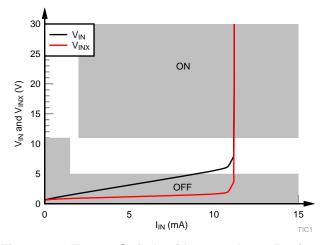


Figure 86. Type-3 Switch with 400- $\Omega$  Input Resistor

## 10 Power Supply Recommendations

There are two supply input pins for the TIC12400:  $V_S$  and  $V_{DD}$ .  $V_S$  is the main power supply for the entire chip and is essential for all critical functions of the device. The TIC12400 is designed to operate with  $V_S$  ranging from 6.5 V to 35 V. The  $V_{DD}$  supply is used to determine the logic level on the SPI communication interface, source the current for the SO driver, and sets the pull-up voltage for the  $\overline{CS}$  pin. It can also be used as a possible external pull-up supply for the /INT pinas an alternative to the  $V_S$  supply and it shall be connected to a 3 V to 5.5 V logic supply. Removing  $V_{DD}$  from the device disables SPI communications, but does not impact normal operation of the device.

To improve stability of the supply inputs, some decoupling capacitors are recommended on the PCB. Figure 87 shows an example on the on-board power supply decoupling scheme. The supply voltage ( $V_{SUPPLY}$ ) is decoupled on the Electronic Control Unit (ECU) board using a large decoupling capacitor ( $C_{BUFF}$ ). The diode is installed to prevent damage to the internal system under reversed supply condition.  $C_{VS}$  shall be installed closed to the TIC12400 for best decoupling performance. The voltage regulator provides a regulated voltage for the digital potion of the device and for the local microcontroller and its output is decoupled with  $C_{DECOUPLE}$ . Table 61 lists recommended values for each individual decoupling capacitor shown in the system diagram.

**Table 61. Decoupling Capacitor Recommendations** 

Component	Value
C <sub>BUFF</sub>	100 μF, 50V rated, ±20%
C <sub>VSUPPLY</sub>	100 nF, 50 V rated, ±10%; X7R
C <sub>VS</sub>	100 nF, 50 V rated
C <sub>DECOUPLE</sub>	100 nF ~ 1 μF

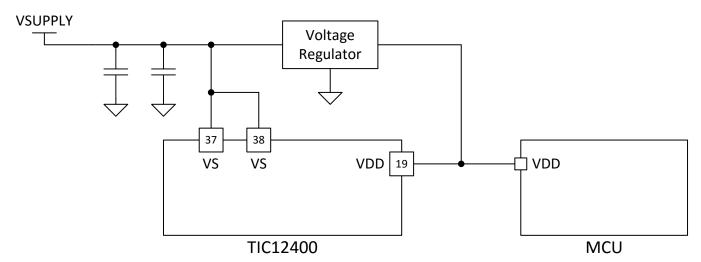


Figure 87. Recommended Power Supply Decoupling

# TEXAS INSTRUMENTS

#### 11 Layout

#### 11.1 Layout Guidelines

Figure 88 illustrates an example of a PCB layout with the TIC12400. Some key considerations are:

- 1. Decouple the  $V_S$  and  $V_{DD}$  pins with capacitor using recommended values from section Power Supply Recommendations , and place them as close to the pin as possible. Make sure that the capacitor voltage rating is sufficient for the  $V_S$  and  $V_{DD}$  supplies.
- 2. Keep the input lines as short as possible.
- 3. Use a solid ground plane to help distribute heat and reduce electromagnetic interference (EMI) noise pickup.
- 4. Do not run sensitive analog traces in parallel with digital traces. Avoid crossing digital and analog traces if possible, and only make perpendicular crossings when necessary
- 5. To achieve good thermal performance, the exposed thermal pad underneath the device must be soldered to the board and flooded with VIAs to ground planes. For simple double-sided PCBs where there are no internal layers, the surface layers can be used to remove heat. For multilayer PCBs, internal ground plane can be used for heat removal.



#### 11.2 Layout Example

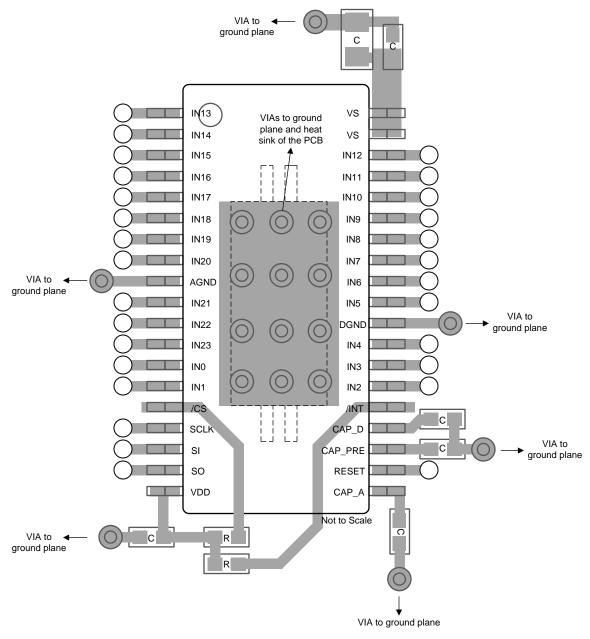


Figure 88. Example Layout

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# TEXAS INSTRUMENTS

#### 12 Device and Documentation Support

#### 12.1 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

#### 12.2 Community Resources

The following links connect to TI community resources. Linked contents are provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's Terms of Use.

TI E2E™ Online Community TI's Engineer-to-Engineer (E2E) Community. Created to foster collaboration among engineers. At e2e.ti.com, you can ask questions, share knowledge, explore ideas and help solve problems with fellow engineers.

**Design Support** *TI's Design Support* Quickly find helpful E2E forums along with design support tools and contact information for technical support.

#### 12.3 Trademarks

E2E is a trademark of Texas Instruments.

#### 12.4 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

#### 12.5 Glossary

SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

#### 13 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



## PACKAGE OPTION ADDENDUM

10-Dec-2020

#### PACKAGING INFORMATION

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Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan	Lead finish/ Ball material	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
TIC12400DCPR	ACTIVE	HTSSOP	DCP	38	2000	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-40 to 105	TIC12400	Samples

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) RoHS: TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

RoHS Exempt: TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

Green: TI defines "Green" to mean the content of Chlorine (CI) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

- (3) MSL, Peak Temp. The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.
- (4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.
- (5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.
- (6) Lead finish/Ball material Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

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#### OTHER QUALIFIED VERSIONS OF TIC12400:



# **PACKAGE OPTION ADDENDUM**

10-Dec-2020

• Automotive: TIC12400-Q1

NOTE: Qualified Version Definitions:

• Automotive - Q100 devices qualified for high-reliability automotive applications targeting zero defects

PACKAGE MATERIALS INFORMATION

www.ti.com 26-Feb-2019

## TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
В0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
TIC12400DCPR	HTSSOP	DCP	38	2000	330.0	16.4	6.9	10.2	1.8	12.0	16.0	Q1

www.ti.com 26-Feb-2019



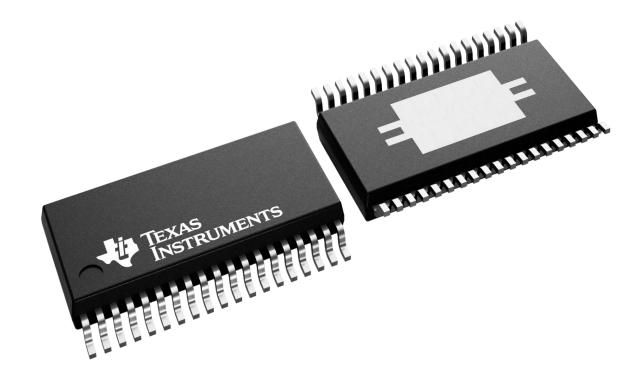
#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
TIC12400DCPR	HTSSOP	DCP	38	2000	350.0	350.0	43.0	

4.4 x 9.7, 0.5 mm pitch

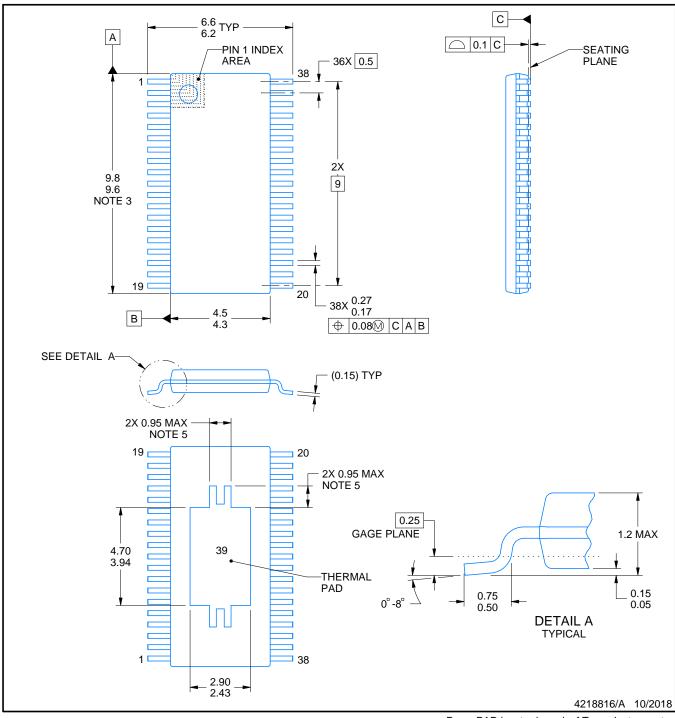
SMALL OUTLINE PACKAGE

This image is a representation of the package family, actual package may vary. Refer to the product data sheet for package details.



# PowerPAD<sup>™</sup> TSSOP - 1.2 mm max height

SMALL OUTLINE PACKAGE



#### NOTES:

PowerPAD is a trademark of Texas Instruments.

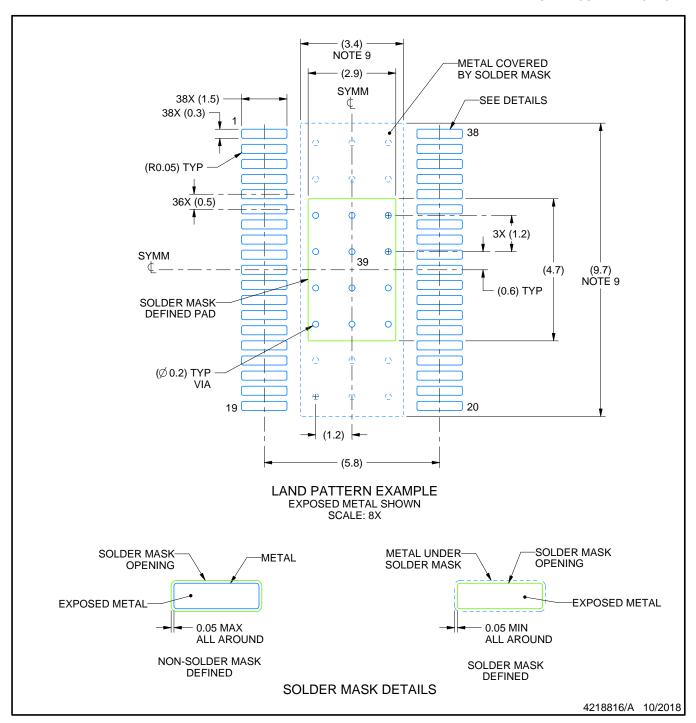
- 1. All linear dimensions are in millimeters. Any dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.

  2. This drawing is subject to change without notice.

  3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not
- exceed 0.15 mm per side.
  4. Reference JEDEC registration MO-153.
- 5. Features may differ or may not be present.



SMALL OUTLINE PACKAGE

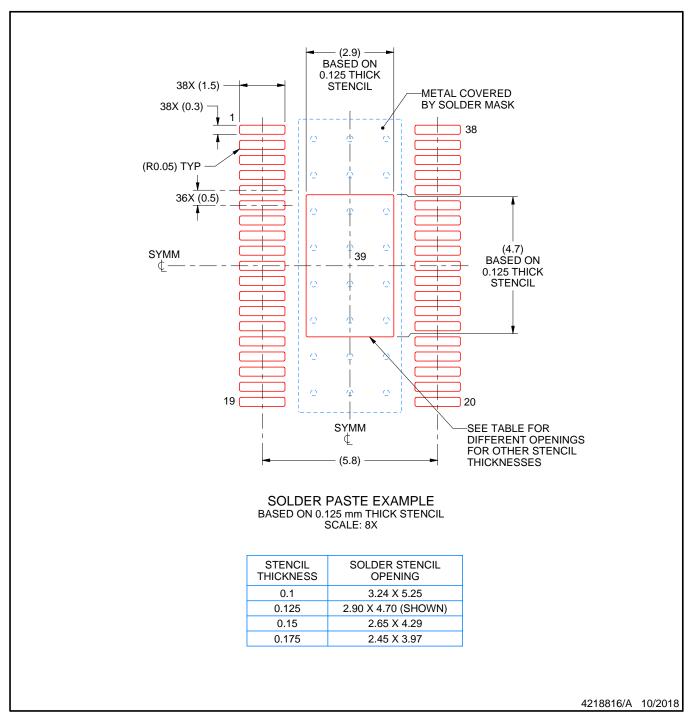


#### NOTES: (continued)

- 6. Publication IPC-7351 may have alternate designs.
- 7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.
- 8. This package is designed to be soldered to a thermal pad on the board. For more information, see Texas Instruments literature numbers SLMA002 (www.ti.com/lit/slma002) and SLMA004 (www.ti.com/lit/slma004).
- 9. Size of metal pad may vary due to creepage requirement.
- 10. Vias are optional depending on application, refer to device data sheet. It is recommended that vias under paste be filled, plugged or tented.



SMALL OUTLINE PACKAGE



NOTES: (continued)

- 11. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
- 12. Board assembly site may have different recommendations for stencil design.



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