



AL8807Q

# HIGH EFFICIENCY LOW 30V 1.3A AUTOMOTIVE COMPLIANT BUCK LED DRIVER

### Description

The AL8807Q is a step-down DC/DC converter designed to drive LEDs with a constant current. Depending on the forward voltage of the LEDs, the device can drive up to nine LEDs in series from a voltage source of 6V to 30V. Series connection of the LEDs provides identical LED currents resulting in uniform brightness and eliminating the requirement for ballast resistors. The AL8807Q switches at frequency up to 1MHz with controlled rise and fall times to reduce EMI. This allows the use of small size external components, hence minimizing the PCB area needed.

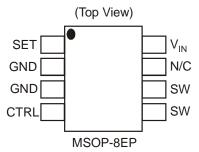
Maximum output current of AL8807Q is set via an external resistor connected between the  $V_{\text{IN}}$  and SET input pins. Dimming is achieved by applying either a DC voltage or a PWM signal at the CTRL input pin. An input voltage of 0.4V or lower at CTRL switches off the output MOSFET simplifying PWM dimming.

The AL8807Q has been qualified to AEC-Q100 Grade 1 and is automotive compliant supporting PPAP documentation.

### **Features**

- LED Driving Current up to 1.3A
- Better than 5% Accuracy
- High Efficiency up to 96%
- Optimally Controlled Switching Speeds
- Operating Input Voltage from 6V to 30V
- PWM/DC Input for Dimming Control
- Built-in Output Open-Circuit Protection
- Automotive Grade with AEC-Q100 Qualification
- MSOP-8EP: Available in "Green" Molding Compound (No Br, Sb)
- Totally Lead-Free & Fully RoHS Compliant (Notes 1 & 2)
- Halogen and Antimony Free. "Green" Device (Note 3)
- Qualified to AEC-Q100 Standards for High Reliability
- PPAP Capable (Note 4)

# **Pin Assignments**



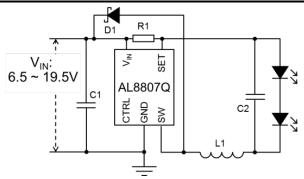
### **Applications**

- Automotive Interior LED Lamps
- Automotive Exterior LED Lamps

Notes:

- 1. No purposely added lead. Fully EU Directive 2002/95/EC (RoHS), 2011/65/EU (RoHS 2) & 2015/863/EU (RoHS 3) compliant.
- 2. See https://www.diodes.com/quality/lead-free/ for more information about Diodes Incorporated's definitions of Halogen- and Antimony-free, "Green" and Lead-free.
- 3. Haloger- and Antimony-free "Green" products are defined as those which contain <900ppm bromine, <900ppm chlorine (<1500ppm total Br + Cl) and <1000ppm antimony compounds.
- 4. Automotive products are AEC-Q101 qualified and are PPAP capable. Refer to https://www.diodes.com/quality/.

# **Typical Applications Circuit**

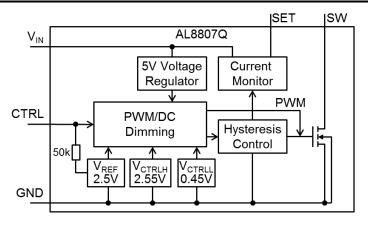




# **Pin Descriptions**

Pin Name	Pin Number	Functions	
SET	1	Set Nominal Output Current Pin. Configure the output current of the device.	
GND	2, 3	GND Pin	
CTRL	4	Dimming and On/Off Control Input.  Leave floating for normal operation (V <sub>CTRL</sub> = V <sub>REF</sub> = 2.5V giving nominal average output current I <sub>OUTnom</sub> = 0.1/R <sub>S</sub> )  Drive to voltage below 0.4V to turn off output current  Drive with DC voltage (0.5V < V <sub>CTRL</sub> < 2.5V) to adjust output current from 20% to 100% of I <sub>OUTnom</sub> A PWM signal (low level ≤ 0.4V and high level > 2.6; transition times less than 1µs) allows the output current to be adjusted below the level set by the resistor connected to SET input pin	
SW	5, 6	Switch Pin. Connect inductor/freewheeling diode here, minimizing track length at this pin to reduce EMI.	
N/C	7	No Connection	
V <sub>IN</sub>	8	Input Supply Pin. Must be locally decoupled to GND with $\geq 2.2 \mu F$ X7R ceramic capacitor—see applications section for more information.	
EP	EP	Exposed pad/TAB connect to GND and thermal mass for enhanced thermal impedance. Should not be us electrical ground conduction path.	

# **Functional Block Diagram**



### Absolute Maximum Ratings (@TA = +25°C, unless otherwise specified.)

Symbol	Parameter	Ratings	Unit
ESD HBM	Human Body Model ESD Protection	4000	V
ESD MM	Machine Model ESD Protection	300	V
ESD CDM	Charged Device Model ESD Protection	1000	V
V <sub>IN</sub>	Continuous V <sub>IN</sub> Pin Voltage Relative to GND	-0.3 to +40	٧
V <sub>SW</sub>	SW Voltage Relative to GND	-0.3 to +40	V
V <sub>CTRL</sub>	CTRL Pin Input Voltage	-0.3 to +6	V
I <sub>SW-RMS</sub>	DC or RMS Switch Current	1.6	Α
I <sub>SW-PK</sub>	Peak Switch Current (<10%)	2.5	Α
$T_J$	Junction Temperature	+150	°C
T <sub>LEAD</sub>	Lead Temperature Soldering	+300	°C
T <sub>ST</sub>	Storage Temperature Range	-65 to +150	°C

Caution:

Stresses greater than the 'Absolute Maximum Ratings' specified above, may cause permanent damage to the device. These are stress ratings only; functional operation of the device at these or any other conditions exceeding those indicated in this specification is not implied. Device reliability may be affected by exposure to absolute maximum rating conditions for extended periods of time.

Semiconductor devices are ESD sensitive and may be damaged by exposure to ESD events. Suitable ESD precautions should be taken when handling and transporting these devices.



# Recommended Operating Conditions (@T<sub>A</sub> = +25°C, unless otherwise specified.)

Symbol	Parameter		Max	Unit
$V_{IN}$	Operating Input Voltage Relative to GND		30	V
V <sub>CTRLH</sub>	Voltage High for PWM Dimming Relative to GND		5.5	V
V <sub>CTRLDC</sub>	Voltage range for 20% to 100% DC Dimming Relative to GND	0.5	2.5	V
V <sub>CTRLL</sub>	Voltage Low for PWM Dimming Relative to GND	0	0.4	V
fsw	Maximum Switching Frequency	_	1	MHz
Isw	Continuous Switch Current	_	1.3	Α
TJ	Junction Temperature Range	-40	125	°C

# **Electrical Characteristics** (@ $V_{IN} = 12V$ , $T_A = +25$ °C, unless otherwise specified.)

Symbol	Parameter	Conditions	Min	Тур	Max	Unit
V <sub>INSU</sub>	Internal Regulator Start-up Threshold	V <sub>IN</sub> Rising	_	_	5.9	٧
Vinsh	Internal Regulator Hysteresis Threshold	V <sub>IN</sub> Falling	100	_	300	mV
IQ	Quiescent Current	Output Not Switching (Note 5)	_	_	350	μΑ
Is	Input Supply Current	CTRL Pin Floating f = 250kHz	_	1.8	5	mA
$V_{TH}$	Set current Threshold Voltage	_	95	100	105	mV
V <sub>TH-H</sub>	Set threshold Hysteresis	_	_	±20	_	mV
I <sub>SET</sub>	SET Pin Input Current	V <sub>SET</sub> = V <sub>IN</sub> -0.1	_	16	22	μA
R <sub>CTRL</sub>	CTRL Pin Input Resistance	Referred to Internal Reference	_	50	_	kΩ
$V_{REF}$	Internal Reference Voltage	_	_	2.5	_	V
R <sub>DS(on)</sub>	On Resistance of SW MOSFET	I <sub>SW</sub> = 1A	_	0.25	0.4	Ω
t <sub>R</sub>	SW Rise Time	V <sub>SENSE</sub> = 100±20mV, f <sub>SW</sub> = 250kHz	_	12	_	ns
t <sub>F</sub>	SW Fall Time	$V_{SW} = 0.1V \sim 12V \sim 0.1V$ $C_L = 15pF$	_	20	_	ns
I <sub>SW_Leakage</sub>	Switch Leakage Current	V <sub>IN</sub> =30V	_	_	0.5	μA
ӨЈА	Thermal Resistance Junction-to- Ambient (Note 6)	(Note 7)	_	69	_	°C/W
Өлс	Thermal Resistance Junction-to-Case (Note 8)	(Note 7)	_	4.3	_	_

Notes:

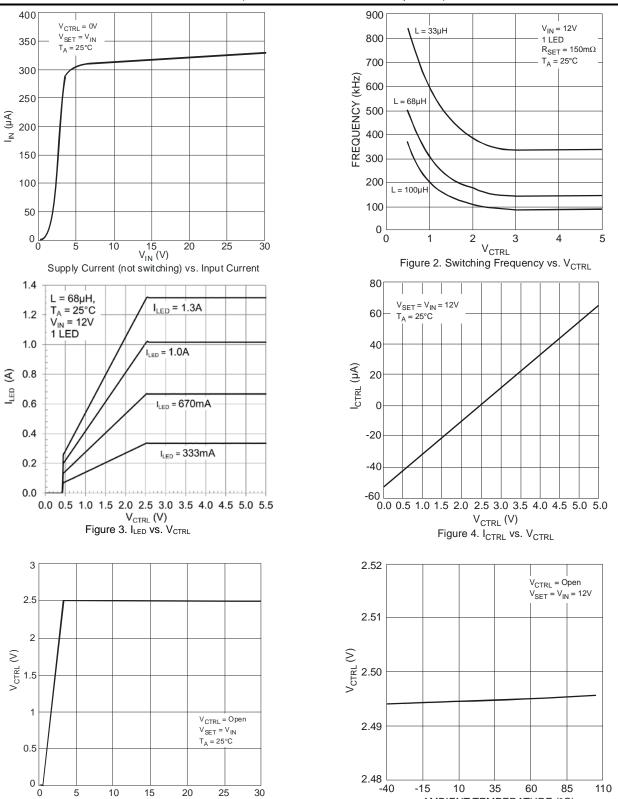
<sup>5.</sup> AL8807Q does not have a low power standby mode but current consumption is reduced when output switch is inhibited:  $V_{SENSE} = 0V$ . Parameter is tested

<sup>6.</sup> Refer to Figure 35 for the device derating curve.
7. Test condition for MSOP-8EP: Device mounted on FR-4 PCB (51mm × 51mm 2oz copper, minimum recommended pad layout on top layer and thermal vias to bottom layer with maximum area ground plane). For better thermal performance, larger copper pad for heat-sink is required.

8. Dominant conduction path via exposed pad.



# Typical Performance Characteristics (@T<sub>A</sub> = +25°C, unless otherwise specified.)



0

0

5

15

 $V_{IN}(V)$ V<sub>CTRL</sub> vs. Input Voltage (CTRL pin open circuit) 30

10

35

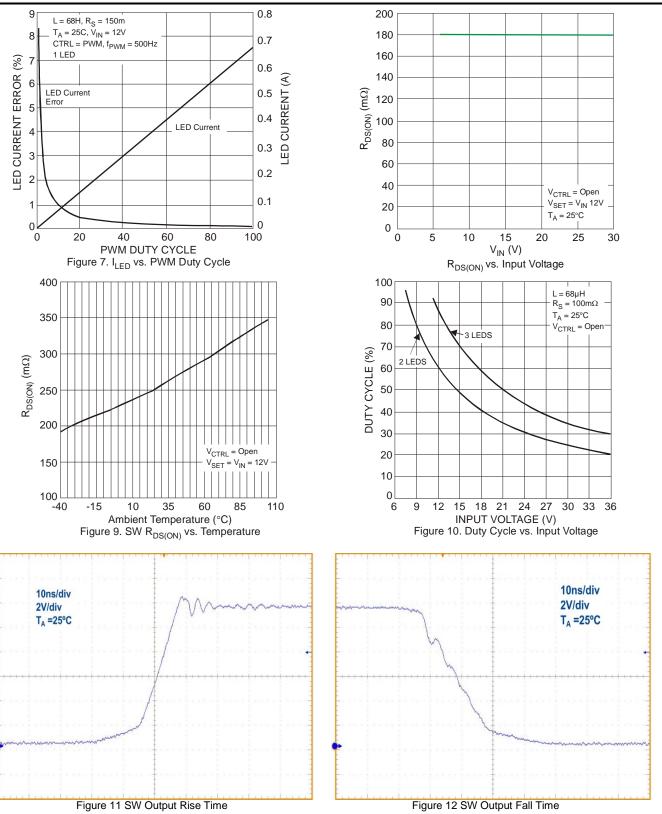
AMBIENT TEMPERATURE (°C) Figure 6.  $V_{CTRL}$  VS. TEMPERATURE

60

110



# Typical Performance Characteristics (continued) (@T<sub>A</sub> = +25°C, unless otherwise specified.)





### Typical Performance Characteristics 670mA LED Current (continued) (@TA = +25°C, unless otherwise specified.)

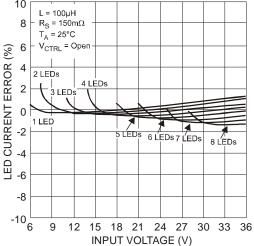


Figure 13. LED Current Deviation vs. Input Voltage

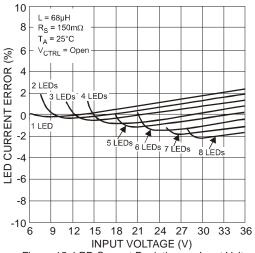


Figure 15. LED Current Deviation vs. Input Voltage

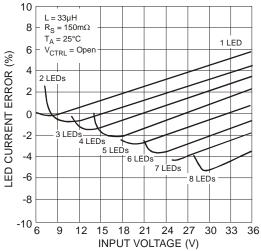


Figure 17. LED Current Deviation vs. Input Voltage

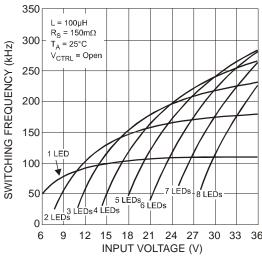


Figure 14. Switching Frequency vs. Input Voltage

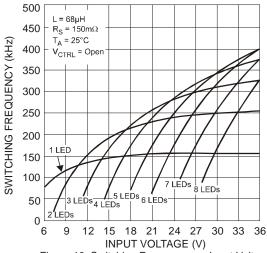


Figure 16. Switching Frequency vs. Input Voltage

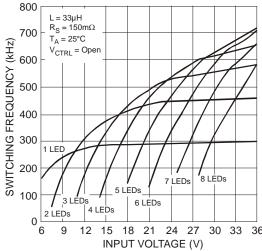


Figure 18. Switching Frequency vs. Input Voltage



# Typical Performance Characteristics 1A LED Current (continued) (@T<sub>A</sub> = +25°C, unless otherwise specified.)

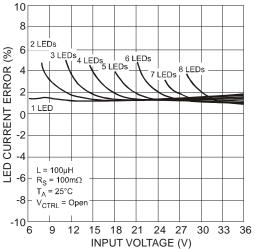


Figure 19. LED Current Deviation vs. Input Voltage

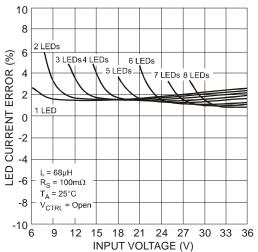


Figure 21. LED Current Deviation vs. Input Voltage

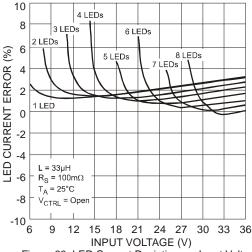


Figure 23. LED Current Deviation vs. Input Voltage

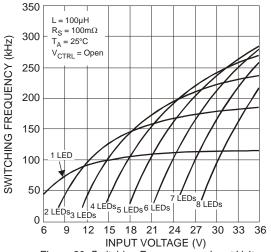


Figure 20. Switching Frequency vs. Input Voltage

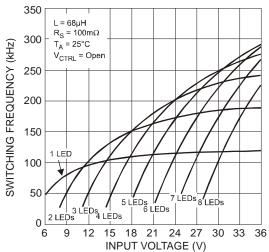


Figure 22. Switching Frequency vs. Input Voltage

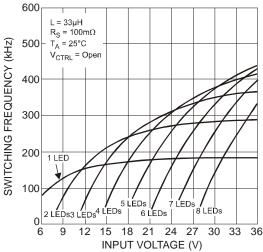


Figure 24. Switching Frequency vs. Input Voltage



# Typical Performance Characteristics 1.3A LED Current (continued) (@T<sub>A</sub> = +25°C, unless otherwise specified.)

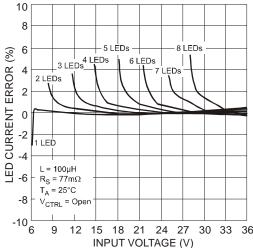


Figure 25. LED Current Deviation vs. Input Voltage

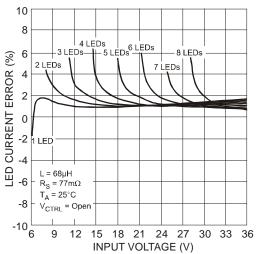


Figure 27. LED Current Deviation vs. Input Voltage

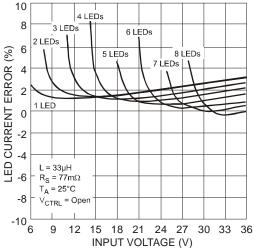


Figure 29. LED Current Deviation vs. Input Voltage

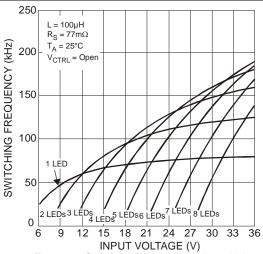


Figure 26. Switching Frequency vs. Input Voltage

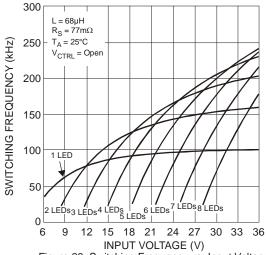


Figure 28. Switching Frequency vs. Input Voltage

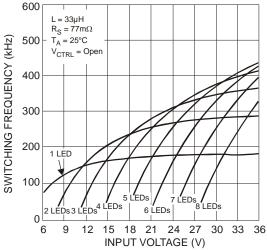


Figure 30. Switching Frequency vs. Input Voltage



## **Application Information**

The AL8807Q is a hysteretic (also known as equal ripple) LED driver with integrated power switch. It is available in two packages that provide a PCB area-power dissipation capability compromise. It is recommended that at higher LED currents/smaller PCBs that the MSOP-8EP version is used to maximize the allowable LED current over a wider ambient temperature range.

#### AL8807Q Operation

In normal operation when voltage is applied at +V<sub>IN</sub>, the AL8807Q internal switch is turned on. Current starts to flow through sense resistor R<sub>1</sub>, inductor L1, and the LEDs. The current ramps up linearly, and the ramp rate is determined by the input voltage +Vin and the inductor L1.

This rising current produces a voltage ramp across R<sub>1</sub>. The internal circuit of the AL8807Q senses the voltage across R<sub>1</sub> and applies a proportional voltage to the input of the internal comparator.

When this voltage reaches an internally set upper threshold, the internal switch is turned off. The inductor current continues to flow through R<sub>1</sub>, L<sub>1</sub>, the LEDs, and the Schottky diode D1, and back to the supply rail, but it decays with the rate of decay determined by the forward voltage drop of the LEDs and the Schottky diode.

This decaying current produces a falling voltage at R<sub>1</sub>, which is sensed by the AL8807Q. A voltage proportional to the sense voltage across R<sub>1</sub> is applied at the input of the internal comparator. When this voltage falls to the internally set lower threshold, the internal switch is turned on again. This switch-on-and-off cycle continues to provide the average LED current set by the sense resistor R<sub>1</sub>.

#### **LED Current Control**

The LED current is controlled by the resistor R1 in Figure 30.

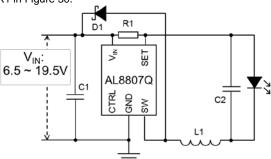


Figure 30 Typical Application Circuit

Connected between VIN and SET, the nominal average output current in the LED(s) is defined as:

$$I_{LED} = \frac{V_{THD}}{R1}$$

For example for a desired LED current of 660mA and a default voltage VCTRL=2.5V, the resulting resistor is:  $R1 = \frac{V_{THD}}{I_{LED}} = \frac{0.1}{0.66} \approx 150 m\Omega$ 

$$R1 = \frac{V_{THD}}{I_{LED}} = \frac{0.1}{0.66} \approx 150 \text{m}\Omega$$

#### Analog Dimming

Further control of the LED current can be achieved by driving the CTRL pin with an external voltage (between 0.4V and 2.5V). The average LED current becomes:

$$I_{LED} = \frac{V_{CTRL}}{V_{REF}} \frac{V_{THD}}{R_{SET}}$$

With 0.5V ≤ V<sub>CTRL</sub> ≤ 2.5V the LED current varies linearly with V<sub>CTRL</sub>, as in Figure 2. If the CTRL pin is brought higher than 2.5V, the LED current clamps to approximately 100% and follows  $I_{LED} = \frac{V_{THD}}{R_{SET}}$ 

When the CTRL voltage falls below the threshold, 0.4V, the output switch turns off, which allows PWM dimming.



#### **PWM Dimming**

LED current can be adjusted digitally by applying a low frequency pulse width modulated (PWM) logic signal to the CTRL pin to turn the device on and off. This produces an average output current proportional to the duty cycle of the control signal. In particular, a PWM signal with a maximum resolution of 10bit can be applied to the CTRL pin to change the output current to a value below the nominal average value set by resistor R<sub>SET</sub>. To achieve this resolution the PWM frequency must be lower than 500Hz; however, higher dimming frequencies can be used at the expense of dimming dynamic range and accuracy.

Typically, for a PWM frequency of 500Hz the accuracy is better than 1% for PWM ranging from 1% to 100%.

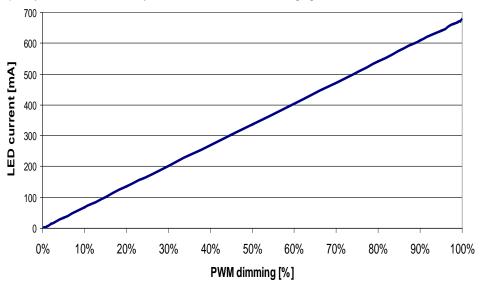


Figure 31 PWM Dimming at 500Hz

Zooming in at duty cycles below 10% shows:

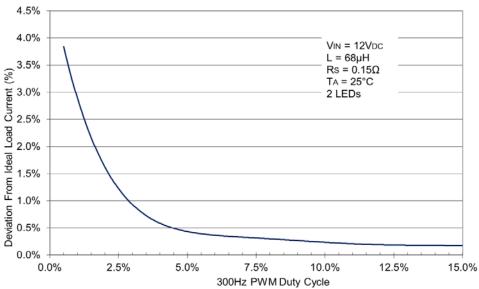


Figure 32 Low Duty Cycle PWM Dimming at 300Hz

The accuracy of the low duty cycle dimming is affected by both the PWM frequency and also the switching frequency of the AL8807Q. For best accuracy/resolution the switching frequency should be increased while the PWM frequency should be reduced.

The CTRL pin is designed to be driven by both 3.3V and 5V logic levels directly from a logic output with either an open drain output or push pull output stage.



#### Soft Start

The AL8807Q does not have built-in soft-start action—this provides very fast turn off of the output the stage improving PWM dimming accuracy; nonetheless, adding an external capacitor from the CTRL pin to ground provides a soft-start delay. This is achieved by increasing the time taken for the CTRL voltage to rise to the turn-on threshold and by slowing down the rate of rise of the control voltage at the input of the comparator. Adding a capacitor increases the time taken for the output to reach 90% of its final value. This delay is 0.1ms/nF but impacts on the PWM dimming accuracy depending on the delay introduced.

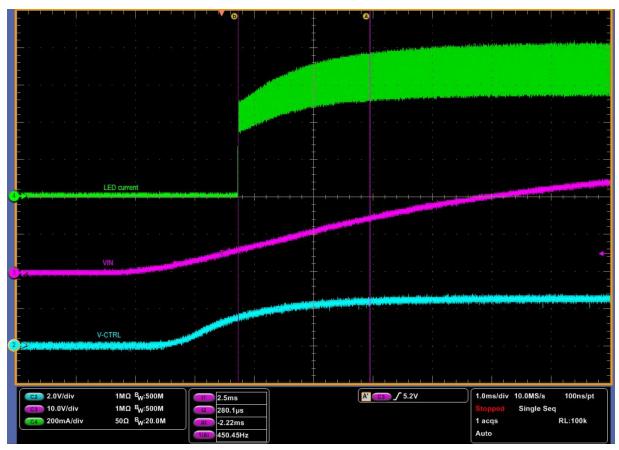


Figure 33 Soft Start with 22nF Capacitor on CTRL Pin (VIN = 30V, ILED = 667mA, 1 LED)

#### **Reducing Output Ripple**

Peak-to-peak ripple current in the LED(s) can be reduced, if required, by shunting a capacitor C2 across the LED(s) as shown already in the circuit schematic.

A value of 1µF reduces the supply ripple current by a factor three (approximately). Proportionally lower ripple can be achieved with higher capacitor values. Note that the capacitor does not affect operating frequency or efficiency, but it will increase start-up delay by reducing the rate of rise of LED voltage. By adding this capacitor the current waveform through the LED(s) changes from a triangular ramp to a more sinusoidal version without altering the mean current value.

#### Capacitor Selection

The small size of ceramic capacitors makes them ideal for AL8807Q applications. X5R and X7R types are recommended because they retain their capacitance over wider voltage and temperature ranges than other types such as Z5U.

A 2.2μF input capacitor is sufficient for most intended applications of AL8807Q; however a 4.7μF input capacitor is suggested for input voltages approaching 30V.



#### **Diode Selection**

For maximum efficiency and performance, the rectifier (D1) should be a fast low capacitance Schottky diode with low reverse leakage at the maximum operating voltage and temperature. The Schottky diode also provides better efficiency than silicon PN diodes due to a combination of lower forward voltage and reduced recovery time.

It is important to select parts with a peak current rating above the peak coil current and a continuous current rating higher than the maximum output load current. In particular, it is recommended to have a diode voltage rating at least 15% higher than the operating voltage to ensure safe operation during the switching and a current rating at least 10% higher than the average diode current. The power rating is verified by calculating the power loss through the diode.

Schottky diodes, e.g. B240 or B140, with their low forward voltage drop and fast reverse recovery, are the ideal choice for AL8807Q applications.

#### Inductor Selection

Recommended inductor values for the AL8807Q are in the range  $33\mu H$  to  $100\mu H$ .

Higher values of inductance are recommended at higher supply voltages in order to minimize errors due to switching delays, which result in increased ripple and lower efficiency. Higher values of inductance also result in a smaller change in output current over the supply voltage range. (see graphs).

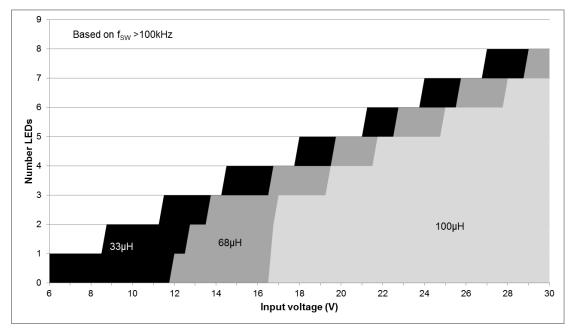


Figure 34 Inductor Value with Input Voltage and Number of LEDs

The inductor should be mounted as close to the device as possible with low resistance/stray inductance connections to the SW pin.

The chosen coil should have a saturation current higher than the peak output current and a continuous current rating above the required mean output current.

Suitable coils for use with the AL8807Q are listed in the table below:

Part No.	L (μΗ)	DCR (V)	I <sub>SAT</sub> (A)	Manufacturer	
MSS1038-333	33	0.093	2.3	CoilCraft www.coilcraft.com	
MSS1038-683	68	0.213	1.5	Colician www.colician.com	
NPIS64D330MTRF	33	0.124	1.1	NIC www.niccomp.com	

The inductor value should be chosen to maintain operating duty cycle and switch 'on'/off' times over the supply voltage and load current range.



#### Inductor Selection (continued)

The following equations can be used as a guide, with reference to Figure 1 - Operating waveforms.

$$t_{ON} = \frac{L\Delta I}{V_{IN} - V_{LED} - I_{AVG} x \left(R_S + r_L + R_{SW}\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{LED} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} + V_D + I_{AVG} x \left(R_S + r_L\right)} \\ t_{OFF} = \frac{L\Delta I}{V_{CD} +$$

#### Where:

- L is the coil inductance (H)
- $r_L$  is the coil resistance  $(\Omega)R_S$  is the current sense resistance  $(\Omega)$
- Iavg is the required LED current (A)
- ΔI is the coil peak-peak ripple current (A) {Internally set to 0.3 x I<sub>avg</sub>}
- V<sub>IN</sub> is the supply voltage (V)
- V<sub>LED</sub> is the total LED forward voltage (V)
- $R_{SW}$  is the switch resistance ( $\Omega$ ) {=0.5 $\Omega$  nominal}
- V<sub>D</sub> is the diode forward voltage at the required load current (V)

#### Thermal Considerations

For continuous conduction mode of operation, the absolute maximum junction temperature must not be exceeded. The maximum power dissipation depends on several factors: the thermal resistance of the IC package  $\Theta_{JA}$ , PCB layout, airflow surrounding the IC, and difference between junction and ambient temperature.

The maximum power dissipation can be calculated using the following formula:

$$P_{D(MAX)} = (T_{J(MAX)} - T_A) / \Theta_{JA}$$

#### Where:

- T<sub>J(MAX)</sub> is the maximum operating junction temperature
- T<sub>A</sub> is the ambient temperature
- $\Theta_{JA}$  is the junction to ambient thermal resistance

The recommended maximum operating junction temperature,  $T_{J}$ , is 125°C, and so maximum ambient temperature is determined by the AL8807Q's junction to ambient thermal resistance,  $\Theta_{JA}$ , and device power dissipation. To support high LED drive at higher ambient temperatures, the AL8807Q has been packaged in thermally enhanced MSOP-8EP package.

 $\Theta_{JA}$  is layout dependent, and the AL8806Q's  $\Theta_{JA}$  in MSOP-8EP on a 51mm x 51mm double layer PCB with 2oz copper standing in still air is approximately 69°C/W. Therefore the maximum power dissipation at  $T_A = 25^{\circ}$ C is:

$$P_{D(MAX)} = \frac{(125^{\circ}C - 25^{\circ}C)}{69^{\circ}C/W} = 1.45W$$

Figure 35 shows the power derating of the AL8807QMP on an FR4 51mm x 51mm PCB with 2oz copper standing in still air.

As the ambient temperature increases and/or the PCB area reduces the maximum allowable power dissipated by the AL8807Q decreases.

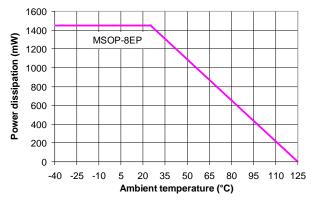


Figure 35 Derating Curve for Different PCB



#### **EMI and Layout Considerations**

The AL8807Q is a switching regulator with fast edges and measures small differential voltages. As a result of this care must be taken with decoupling and layout of the PCB.To help with these effects the AL8807Q is developed to minimise radiated emissions by controlling the switching speeds of the internal power MOSFET. The rise and fall times are controlled to get the right compromise between power dissipation due to switching losses and radiated EMI. The turn-on edge (falling edge) dominates the radiated EMI, which is due to an interaction between the Schottky diode (D1), switching MOSFET, and PCB tracks. After the Schottky diode reverse recovery time of around 5ns occurrs; the falling edge of the SW pin sees a resonant loop between the Schottky diode capacitance and the track inductance, LTRACK (see figure 36).

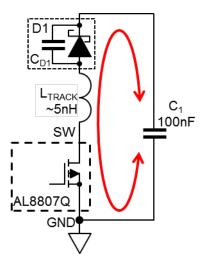


Figure 36 PCB Loop Resonance

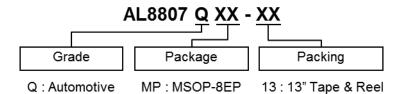
The tracks from the SW pin to the Anode of the Schottky diode, D1, and then from D1's cathode to the decoupling capacitors C1 should be as short as possible. There is an inductance internally in the AL8807Q, which can be assumed to be around 1nH. For PCB tracks a figure of 0.5nH per mm can be used to estimate the primary resonant frequency. If the track is capable of handling 1A increasing the thickness has a minor effect on the inductance and length dominates the size of the inductance. The resonant frequency of any oscillation is determined by the combined inductance in the track, and the effective capacitance of the Schottky diode.

Recommendations for minimising radiated EMI and other transients and thermal considerations are:

- 1. The decoupling capacitor (C1) must be placed as close as possible to the V<sub>IN</sub> pin and D1 Cathode.
- 2. The freewheeling diode's (D1) anode, the SW pin, and the inductor have to be placed as close as possible to each other to avoid ringing.
- 3. The Ground return path from C1 must be a low impedance path with the ground plane as large as possible.
- 4. The LED current sense resistor (R1) must be placed as close as possible to the V<sub>IN</sub> and SET pins.
- 5. The majority of the conducted heat from the AL8807Q is through the GND pin 2. A maximum earth plane with thermal vias into a second earth plane minimises self-heating
- 6. To reduce emissions via long leads on the supply input, and LEDs low RF impedance capacitors (C2 and C5) should be used at the point the wires are joined to the PCB.



### **Ordering Information**



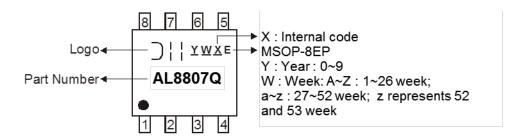
Part Number	Package Code	Packaging		Packing: 13" Tap	Qualification Grade	
Fait Number	Fackage Code	(Note 9)	Quantity	Tape Width	Part Number Suffix	(Note 10)
AL8807QMP-13	MP	MSOP-8EP	2500	12mm	-13	Automotive Compliant

Note:

- 9. Pad layout as shown on Diodes Inc. at http://www.diodes.com/package-outlines.html.
- 10. AL8807Q is qualified to AEC-Q100 grade 1 and is classified as Automotive Compliant, which supports PPAP documentation. See AL8807 datasheet for commercial qualified versions.

# **Marking Information**

### (1) MSOP-8EP



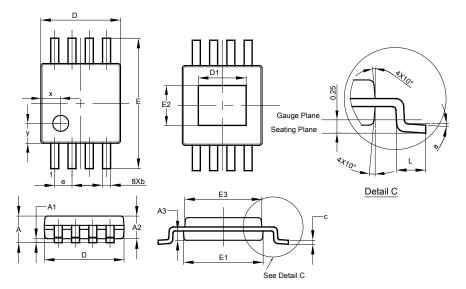
Part Number	Package	
AL8807QMP-13	MSOP-8EP	



# Package Outline Dimensions (All dimensions in mm.)

Please see http://www.diodes.com/package-outlines.html for the latest version.

#### MSOP-8EP

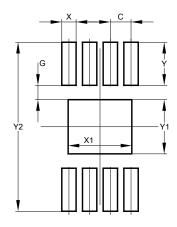


MSOP-8EP					
Dim	Min	Max	Тур		
Α	_	1.10	_		
A1	0.05	0.15	0.10		
A2	0.75	0.95	0.86		
<b>A3</b>	0.29	0.49	0.39		
b	0.22	0.38	0.30		
С	0.08	0.23	0.15		
D	2.90	3.10	3.00		
D1	1.60	2.00	1.80		
Е	4.70	5.10	4.90		
E1	2.90	3.10	3.00		
E2	1.30	1.70	1.50		
E3	2.85	3.05	2.95		
е		_	0.65		
L	0.40	0.80	0.60		
а	0°	8°	4°		
Х	_		0.750		
у			0.750		
All Dimensions in mm					

# Suggested Pad Layout

Please see http://www.diodes.com/package-outlines.html for the latest version.

#### MSOP8-EP



Dimensions	Value (in mm)	
С	0.650	
G	0.450	
Х	0.450	
X1	2.000	
Y	1.350	
Y1	1.700	
Y2	5.300	



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