

# MP2340 24V, 2A, 1MHz Synchronous Step-Down LED Driver

# The Future of Analog IC Technology

# PRELIMINARY SPECIFICATIONS SUBJECT TO CHANGE

# DESCRIPTION

The MP2340 is a 24V monolithic synchronous step-down white LED driver with a built-in power MOSFET and rectifier. It achieves up to 2A continue output current with excellent load and line regulation. Peak current mode operation provides fast transient response and eases loop stabilization.

The MP2340 incorporates both analog and PWM dimming onto a single control pin. The chip can implement deep analog dimming and PWM dimming.

Fault condition protection includes cycle-by-cycle peak current limiting, output short circuit protection, open LED protection and thermal shutdown.

The MP2340 requires a minimum number of readily available standard external components and is available in TSOT23-6 package.

# **FEATURES**

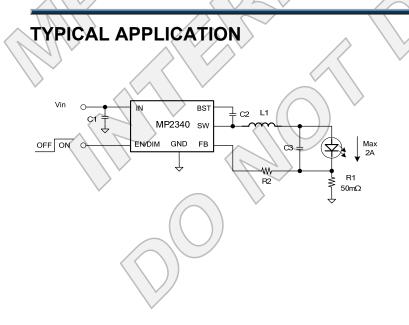
- 4.2V to 24V Wide Input Range
- Synchronous Step-Down Converter
- 100mΩ Internal High-side Power MOSFET
- 80mΩ Internal Low-side Synchronous Rectifier
- Peak Current Mode Control
- Up to 2A Continue Output Current
- 100mV Feedback Voltage
- Up to 97% Efficiency
- Fixed 1MHz Switching Frequency
- Analog & PWM Dimming
- Cycle-by-Cycle Current Limit
- Inherent LED Open Protection
- Output Short Circuit Protection
- Thermal Shutdown
- Auto-Restart Function
- Available in TSOT23-6 Package

# APPLICATIONS

- Infrared LED Driver
- General LED Driver
- Flashlight
- Handheld Computers Backlight

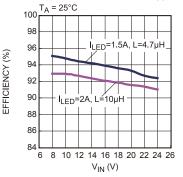
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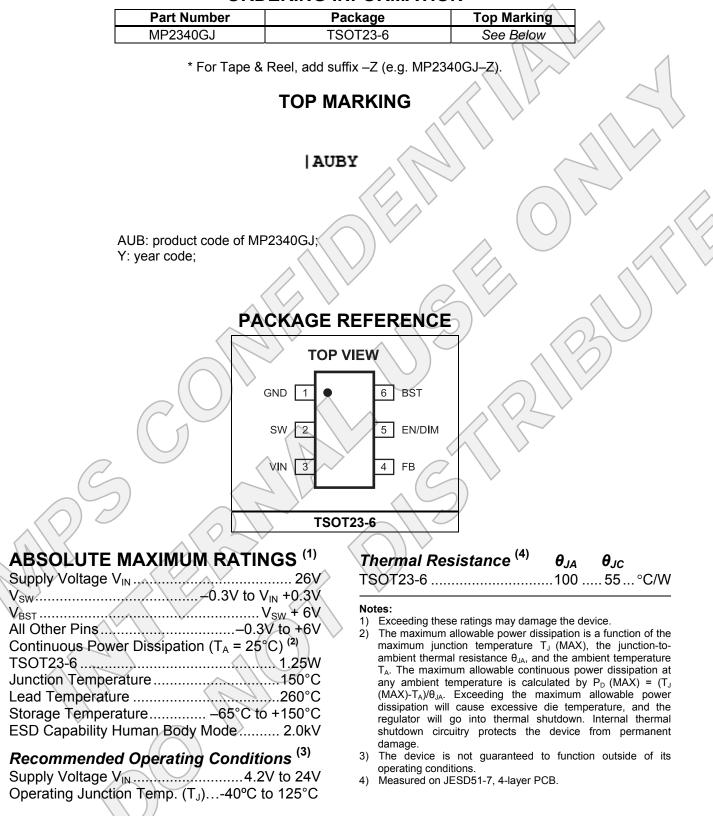
# Efficiency vs. V<sub>IN</sub>

 $V_{IN}$ =12V, 2 WLEDs in series,  $V_{OUT}$ =5.9V,





# **ORDERING INFORMATION**





# **ELECTRICAL CHARACTERISTICS**

Typical values are  $V_{IN}$  = 12V,  $T_J$  = 25°C, unless otherwise noted.

Minimum and maximum values are at  $V_{IN}$  = 12V,  $T_J$  = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

guaranteed by characterization	I.		$\land$	$\sim$		
Parameters	Symbol	Condition	Min	Тур	Max	Units
Supply Voltage				V		
Operating Range	V <sub>IN</sub>	After turn on	4.2		24	V
Turn On Threshold	$V_{IN_{ON}}$	V <sub>IN</sub> rising edge	3.5	3.7	4	X
Hysteretic Voltage	V <sub>IN_HYS</sub>		0.08	0.12	0.24	V
Supply Current					$\sim$	
Shutdown Current	I <sub>SD</sub>	V <sub>EN</sub> = 0V		10	50	μA
Quiescent Current	Ι <sub>Q</sub>	$V_{EN} = 2V, V_{FB} = 200mV$		0.9	1.1	mA
Enable & Dimming			$\wedge$			
EN/DIM OFF Threshold	V <sub>EN_OFF</sub>	VEN/DIM falling edge	0.27	0.31	0.35	V
EN/DIM ON Threshold	V <sub>EN_ON</sub>	V <sub>EN/DIM</sub> rising edge	0.55	0.59	0.63	V
Turn Off Delay Time			16	22	28	ms
EN/DIM Pull-Up Current	I <sub>EN/DIM</sub>	V <sub>EN</sub> = 0V	2.8	3.8	5.3	μA
Max Analog Dimming Threshold		Theoretically, V <sub>FB</sub> = 100mV	1.31	1.44	1.57	V
Min Analog Dimming Threshold	VADIM_MIN	V <sub>FB</sub> = 5mV	0.63	0.7	0.78	V
Feedback	)	$\wedge$				
Feedback Voltage	V <sub>FB</sub>	$4.2V \le V_{IN} \le 24V$	93	100	107	mV
Burst Mode Allowable Threshold	V <sub>FB_BURST_AL</sub>		$\left( \right)$	112	126	mV
Burst Mode Recovery Hysteresis (5)	V <sub>FB_BURST_HYS</sub>			10		mV
Feedback Current	I <sub>FB</sub>	V <sub>FB</sub> = 150mV	-65		65	nA
Power Switch						
High-Side MOSFET On-	R	V <sub>IN</sub> = 5.0V		100	170	mΩ
Resistance	R <sub>DS(ON)_</sub> H	V <sub>IN</sub> = 4.2V		110	180	mΩ
Low-Side Sync-Rectifier Switch	R <sub>DS(ON)_L</sub>	V <sub>IN</sub> = 5.0V		80	140	mΩ
On-Resistance		$\mathcal{N}_{\rm IN} = 4.2 V$		90	150	mΩ
Switch Leakage	I <sub>SW_LKG</sub>	$V_{EN} = 0V, V_{SW} = 0V$			1	μA
High-Side Current Limit		When high-side switch turn-on	3.5	5	6.6	A
Low-Side Current Limit		When low-side switch turn-on	-950	-600	-350	mA
OCP Current Threshold	I <sub>OCP</sub>	Both for high-side & low- side	3.5	5.5	7	Α
Oscillator Frequency	f <sub>sw</sub>	V <sub>FB</sub> = 80mV	0.8	1	1.2	MHz
Maximum Duty Cycle D <sub>MAX</sub>		V <sub>FB</sub> = 80mV	90	94		%
Minimum On-Time	t <sub>ON_MIN</sub>			70		ns
Restart Timer		1	1	ıI		
Hiccup Timer at Fault Condition	t <sub>start</sub>			2.4		ms



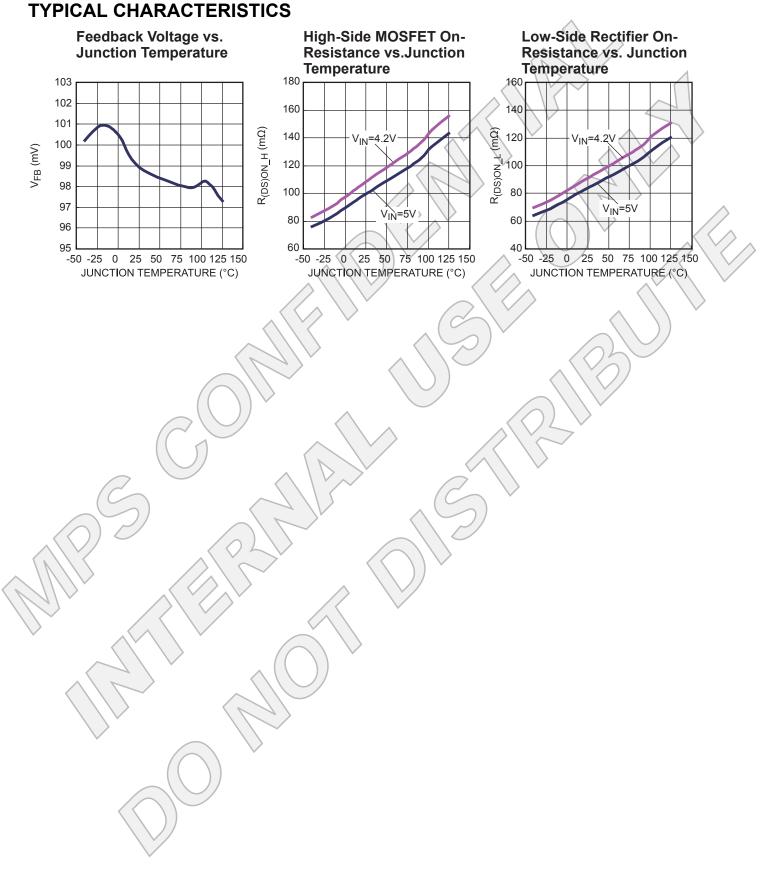
# ELECTRICAL CHARACTERISTICS (continued)

Typical values are  $V_{IN}$  = 12V,  $T_J$  = 25°C, unless otherwise noted.

Minimum and maximum values are at  $V_{IN}$  = 12V,  $T_J$  = -40°C to +125°C, unless otherwise noted, guaranteed by characterization.

Parameters	Symbol	Condition	Min Typ	Max	Units
Bootstrap	-,				
Bias Voltage for High-Side Driver	V <sub>BST</sub> -V <sub>SW</sub>	5.5V≤V <sub>IN</sub> ≤24V	4.8 5.1	5.5	V
		V <sub>IN</sub> =4.2V	3.6		V
Fhermal Shutdown					
Thermal Shutdown Threshold <sup>(6)</sup>	T <sub>SD</sub>		150		°C
Thermal Shutdown Hysteresis <sup>(6)</sup>	T <sub>HYS</sub>		60		°C
Notes: a) Guaranteed by design. b) Guaranteed by characterization. CONTRACTOR CONTRACTOR CONTRAC					

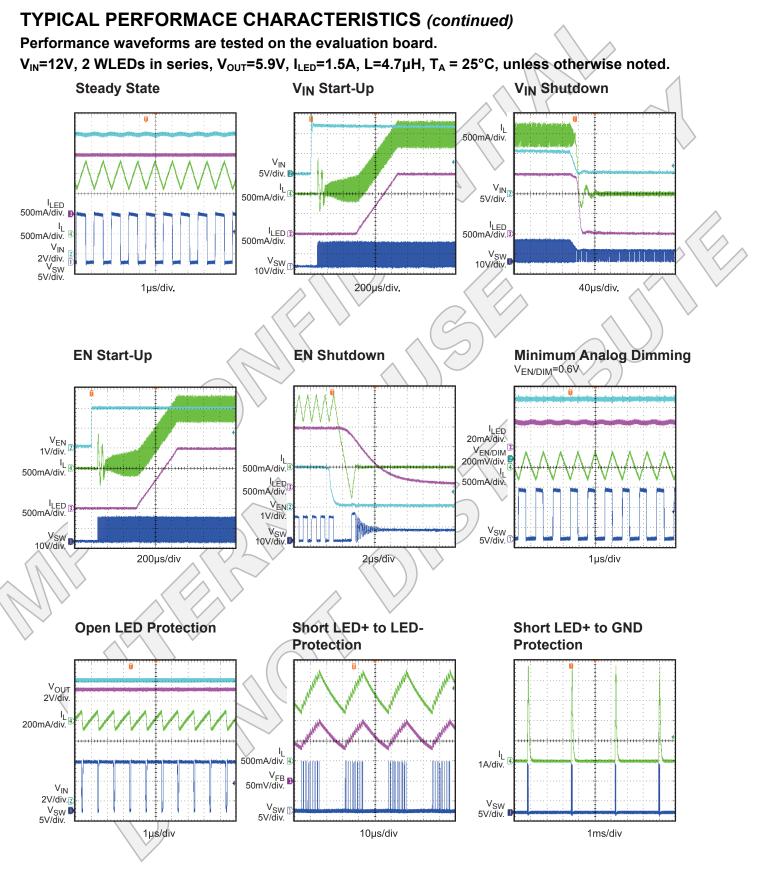
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#### PRELIMINARY SPECIFICATIONS SUBJECT TO CHANGE **TYPICAL PERFORMACE CHARACTERISTICS** Performance waveforms are tested on the evaluation board. V<sub>IN</sub>=12V, 2 WLEDs in series, V<sub>OUT</sub>=5.9V, I<sub>LED</sub>=1.5A, L=4.7µH, T<sub>A</sub> = 25°C, unless otherwise noted. Efficiency vs. VIN Efficiency vs. VOUT Line Regulation 2 WLEDs in series 2 WLEDs in series 1 to 7 IR LEDs in series, I<sub>LED</sub>=500mA, L=22µH 100 100 1.6 98 1.2 VIN=5V 97 $\wedge$ (%) I<sub>I FD</sub>=1.5A, L=4.7µH 96 0.8 I<sub>LED</sub>=1.5A, L=4.7µH 94 EFFICIENCY (%) EFFICIENCY (%) LINE REGULATION 0.4 94 91 0.0 92 88 V<sub>IN</sub>=12V 90 I<sub>LED</sub>=2A, L=10µH 85 -0.4 88 82 -0.8 -I<sub>LED</sub>=2Α, L=10μΗ 86 79 12 -1.6 84 76 6 8 10 12 14 16 18 20 22 24 26 8 9 10 11 6 8 10 12 14 16 18 20 22 24 26 0 1 2 3 4 5 6 7 $V_{IN}(V)$ V<sub>OUT</sub> (V) $V_{IN}(V)$ Analog Dimming Curve Load Regulation 1 to 7 IR LEDs in series. I<sub>LED</sub>=500mA, L=22µH 0.8 1.6 0.6 1.4 LOAD REGULATION (%) V<sub>IN</sub>=5V 1.2 V<sub>DIM</sub> Falling 0.4 0.2 1.0 € 0.8 0.0 LED -0.2 0.6 V<sub>IN</sub>=12V 0.4 V<sub>DIM</sub> Rising -0.4 -0.6 0.2 -0.8 0.0 2 3 4 5 6 7 8 9 10 11 0.2 0.4 0.6 0.8 1 1.2 1.4 1.6 0 V<sub>DIM</sub> ANALOG LEVEL (V) VOUT (V)







## MP2340 – 24V, 2A, 1MHZ SYNCHRONOUS STEP-DOWN LED DRIVER

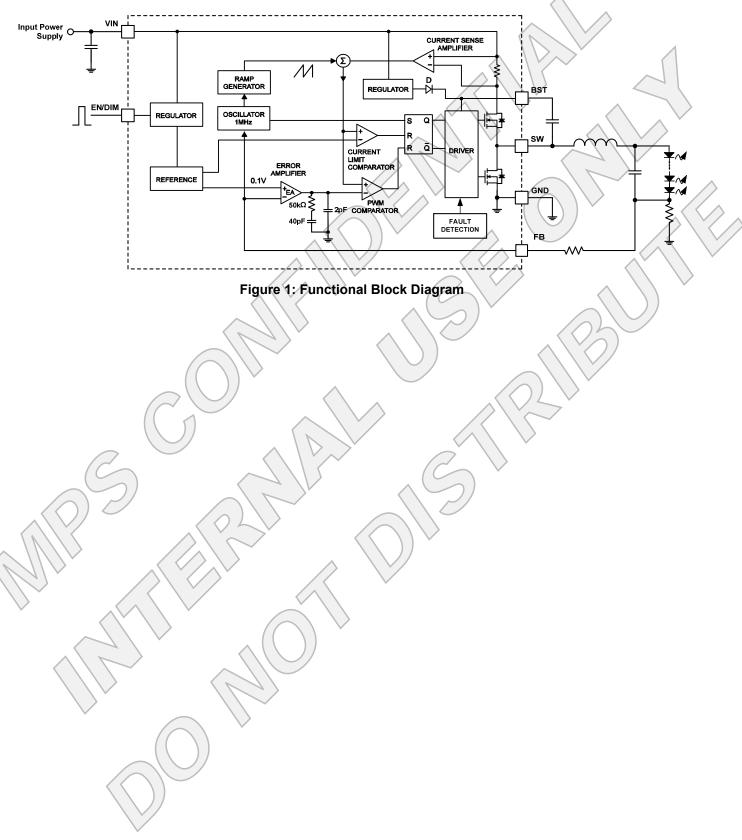
# PRELIMINARY SPECIFICATIONS SUBJECT TO CHANGE

# **PIN FUNCTIONS**

Pin #	Name	Description
1	GND	<b>Ground.</b> This pin is the voltage reference for the regulated output voltage. For this reason care must be taken in its layout.
2	SW	Switch Output.
3	VIN	<b>Supply Voltage.</b> The MP2340 operates from a 4.2V to 24V unregulated input. Input capacitor is needed to prevent large voltage spikes from appearing at the input.
4	FB	Current Sense Feedback Voltage. Its internal reference voltage is 0.1V.
5	EN/DIM	<b>On/Off Control Input &amp; Dimming Command Input.</b> Leave EN/DIM floating or a voltage higher than 0.59V on this pin turns on the chip. For analog dimming, when the EN/DIM voltage rises up from 0.7V to 1.44V, the output current changes from min value to the full-scale LED current. To apply PWM dimming, apply a 100Hz to 2kHz PWM signal with amplitude higher than 1.6V to this pin.
6	BST	<b>Bootstrap.</b> A capacitor is connected between SW and BST pins to form a floating supply across the power switch driver. This capacitor is needed to drive the power switch's gate above the supply voltage.



# FUNCTION BLOCK DIAGRAM





# **OPERATION**

The MP2340 is a high frequency synchronous rectified step-down switching mode LED driver with built-in internal power MOSFET and synchronous rectifier switch. It offers a very high performance solution to achieve up to 2A continuous output LED current over a wide input supply range with excellent load and line regulation.

The MP2340 operates in a fixed 1MHz frequency, peak current control mode to regulate the output current. A new switching cycle is initiated by the internal clock at the beginning of every switching cycle. The integrated high-side power MOSFET is turned on and the inductor current rises linearly to provide the energy to the load. The high-side power MOSFET remains on until its current hits the value of the COMP level which is the output of the internal error amplifier. The output voltage of error amplifier depends on the difference of output feedback and the internal high precision reference and it decides how much energy should be transferred to the load. The high-side power switch remains off until the next clock cycle starts. After the high-side switch is off, the low-side sync-switch is on and the inductor current flows through the low-side switch. In order to avoid shoot-through issue, the dead time is inserted to avoid the high-side and low-side FETs to turn on at the same time. By maximum duty cycle limit, when the duty cycle of one switching period reaches 94%, the current in the high-side power MOSFET does not reach the COMP set current value, the high-side power MOSFET is forced to turn off.

## Under-Voltage Lockout (UVLO) & IC Startup/Shutdown Procedure

Under-voltage lockout (UVLO) is implemented to avoid the chip from operating at insufficient supply voltage. The MP2340 UVLO comparator monitors the output voltage of the internal regulator, which is supplied from  $V_{IN}$ .

If both  $V_{IN}$  and EN/DIM are higher than their appropriate thresholds, the chip starts. The reference block starts first to generate stable reference voltages and currents, then the internal regulator is enabled. The regulator provides stable supply for the remaining circuitries. Three events can shut down the chip: EN/DIM keeps low for more than  $t_{OFF\_DELAY}$ ,  $V_{IN}$  drops below UVLO and thermal shutdown. In shutdown procedure, the signaling path is first blocked to avoid any fault triggering. The COMP voltage and the internal supply rail are then pulled down.

# **Error Amplifier**

The internal low offset error amplifier compares the FB voltage with the internal 100mV reference and outputs COMP voltage, which is inside of the chip and used to control the high-side MOSFET peak current and then to regulate the output current.

# Internal Soft-Start

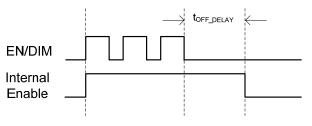
The soft start is implemented to prevent the converter output current from overshooting during start up. When the chip starts, the internal circuitry generates a soft-start voltage (SS) ramping up from 0V. The soft-start period lasts until the voltage on the soft-start capacitor exceeds the 0.1V reference voltage. At this point the reference voltage takes over.

# Floating Driver and Bootstrap Charging

The high-side floating power MOSFET driver is powered by an external bootstrap capacitor. The bootstrap capacitor voltage is regulated internally. At normal operation, a 5.1V bootstrap voltage is maintained between BST and SW.

# **Enable Control**

EN/DIM is a control pin that turns the regulator on/off and dims the output LED current. Leave this pin floating or drive it high to turn on the MP2340. After the pin is pulled down to low for  $t_{OFF_DELAY}$  (typical 22ms), the MP2340 is turned off. Figure 2 shows the control logic of the EN/DIM pin.





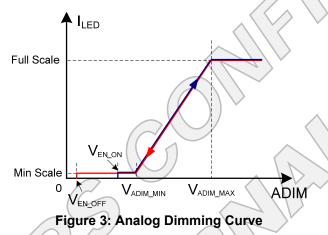




#### **Analog Dimming**

Apply DC signal on EN/DIM can dim the MP2340 on the analog dimming mode. When the voltage on EN/DIM is lower than  $V_{ADIM\_MIN}$ , the LED current is regulated to the minimal scale. When the voltage on EN/DIM is between  $V_{ADIM\_MIN}$  and  $V_{ADIM\_MAX}$ , the LED current changes from the minimal scale to the full scale of LED current. If the voltage on EN/DIM pin is higher than  $V_{ADIM\_MAX}$ , the maximum LED current is regulated.

Figure 3 shows the Analog Dimming Curve. Due to the hysteretic of EN/DIM ON/OFF Threshold, at  $V_{\text{EN/DIM}}$  falling edge, the chip maintains at minimal LED current longer until  $V_{\text{EN/DIM}}$  is lower than  $V_{\text{EN_OFF}}$ . The dimming curve is absolutely same in linear dimming range.



# **PWM** Dimming

Apply PWM signal on EN/DIM to implement PWM dimming mode. The dimming frequency is recommended in the range of 100Hz to 2kHz to achieve a good dimming linearity. The digital signal's amplitude must be higher than 1.6V.

# Open LED

If LED is open without feedback signal, the MP2340 works at the maximum duty cycle and

the output voltage rises up very close to the input voltage. Every power component operates at a safe state.

#### **LED Short Circuit Protection**

The MP2340 integrates the LED Short Circuit Protection circuitry. There are several features preventing the MP2340 from damage when the LED short circuit occurs.

The MP2340 features a cycle-by-cycle current limit to restrict the maximum current of the inductor. And a protection mechanism monitors FB level though an internal RC filter. Once it rises up to hit  $V_{FB_BURST_AL}$ , the chip stops switching until FB level drops to a lower value, and the system works in burst mode.

In the worst case, LED Short Circuit to GND, if the cycle-by-cycle current limit function can not clamp the current overshoot sufficiently, the current (thru both the high-side and low-side FETs) is also monitored by over-current detector inside the chip. If it is higher than the short circuit threshold ( $I_{OCP}$ ), the MP2340 treats it as a short circuit condition.

When Over Current Condition or Short Circuit Condition is detected, the MP2340 turns off the high-side and low-side MOSFETs both for 2.4ms, then restart again. During this period, the COMP voltage is pulled down to ground, so the restart from the fault condition is also with soft-start.

#### **Thermal Shutdown**

Thermal shutdown is implemented to prevent the chip from operating at exceeding high temperature. When the silicon die temperature is higher than 150°C, the OTP shuts down the whole chip. When the temperature is lower than its lower threshold, typically 90°C, the chip restarts again.



# **APPLICATION INFORMATION**

#### Setting LED Current

The current sense resistor is inserted between the anode of LED and GND. The current sense resistor value is calculated as:

$$R_s = \frac{0.1V}{I_{LED}}$$

For 2A LED current output, choose  $R_s = 50m\Omega$ .

#### Selecting the Inductor

A <100 $\mu$ H inductor with a nominal DC current rating of at least 25% higher than the maximum load current is recommended for most applications. For highest efficiency, the inductor's DC resistance should be less than 100m $\Omega$ . For most designs, the required inductance value can be derived from the following equation.

$$L = \frac{V_{\text{OUT}} \times (V_{\text{IN}} - V_{\text{OUT}})}{V_{\text{IN}} \times \Delta I_{\text{I}} \times f_{\text{SW}}}$$

Where  $\Delta I_{L}$  is the inductor ripple current.

Choose the inductor ripple current to be 30% of the maximum load current. The maximum inductor peak current is calculated from:

 $I_{(MAX)} = I_{LED} +$ 

# Selecting the Input Capacitor

The input capacitor reduces the surge current drawn from the input supply and the switching noise from the device. The input capacitor impedance at the switching frequency should be less than the input output source impedance of the input source to prevent high frequency switching current from passing through the input. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR and small temperature coefficients. For most applications, a  $10\mu$ F capacitor is sufficient.

# Selecting the Output Capacitor

The output capacitor keeps the output current ripple small and ensures feedback loop stability. The output capacitor impedance should be low at the switching frequency. Ceramic capacitors with X5R or X7R dielectrics are recommended for their low ESR characteristics. For most applications, a  $10\mu$ F ceramic capacitor is sufficient.

# PC Board Layout

The high current paths (GND, VIN and SW) should be placed very close to the device with short, direct and wide traces. The input capacitor needs to be as close as possible to the VIN and GND pins. The external feedback resistors should be placed next to the FB pin. Keep the switch node traces short and away from the feedback network. Refer to EVB datasheet for more information.



# **TYPICAL APPLICATION CIRCUIT**

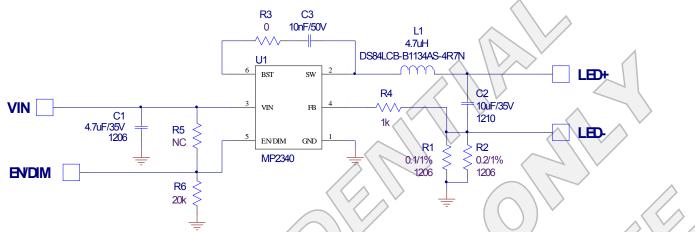


Figure 4: Typical Buck Converter Application, V<sub>IN</sub> =8V to 24V, V<sub>O</sub>=5.9V, I<sub>LED</sub>=1.5A



Preliminary Information -or- INITIAL RELEASE

# PACKAGE INFORMATION

