

International
IR Rectifier

Integrated Power Hybrid IC for
Appliance Motor Drive Applications.

IRAMX16UP60A
iMOTION™ Series
16A, 600V

Description

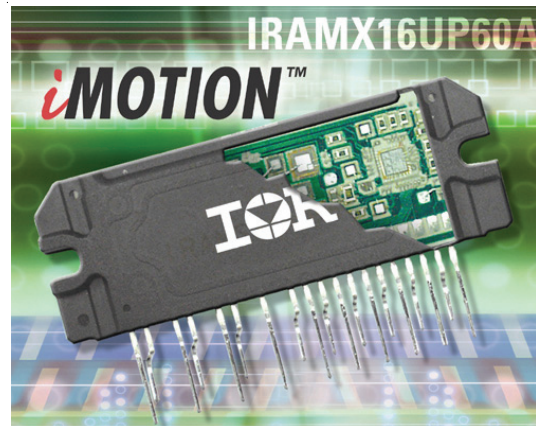
International Rectifier's IRAMX16UP60A is an Integrated Power Module developed and optimized for electronic motor control in appliance applications such as washing machines and variable speed compressor drives for in-room air-conditioning systems and commercial refrigerators. Plug N Drive technology offers an extremely compact, high performance AC motor-driver in a single isolated package for a very simple design. An open emitter configuration of the low side IGBT switches offer easy current feedback and overcurrent monitor for high precision and reliable control.

A built-in temperature monitor and over-current protection, along with the short-circuit rated IGBTs and integrated under-voltage lockout function, deliver high level of protection and fail-safe operation.

The integration of the bootstrap diodes for the high-side driver section, and the single polarity power supply required to drive the internal circuitry, simplify the utilization of the module and deliver further cost reduction advantages.

Features

- Integrated Gate Drivers and Bootstrap Diodes.
- Temperature Monitor
- Temperature and Overcurrent shutdown
- Fully Isolated Package.
- Low VCE (on) Non Punch Through IGBT Technology.
- Undervoltage lockout for all channels
- Matched propagation delay for all channels
- Low side IGBT emitter pins for current control
- Schmitt-triggered input logic
- Cross-conduction prevention logic
- Lower di/dt gate driver for better noise immunity
- Motor Power range 0.75~2kW / 85~253 Vac
- Isolation 2000V_{RMS} min



Absolute Maximum Ratings

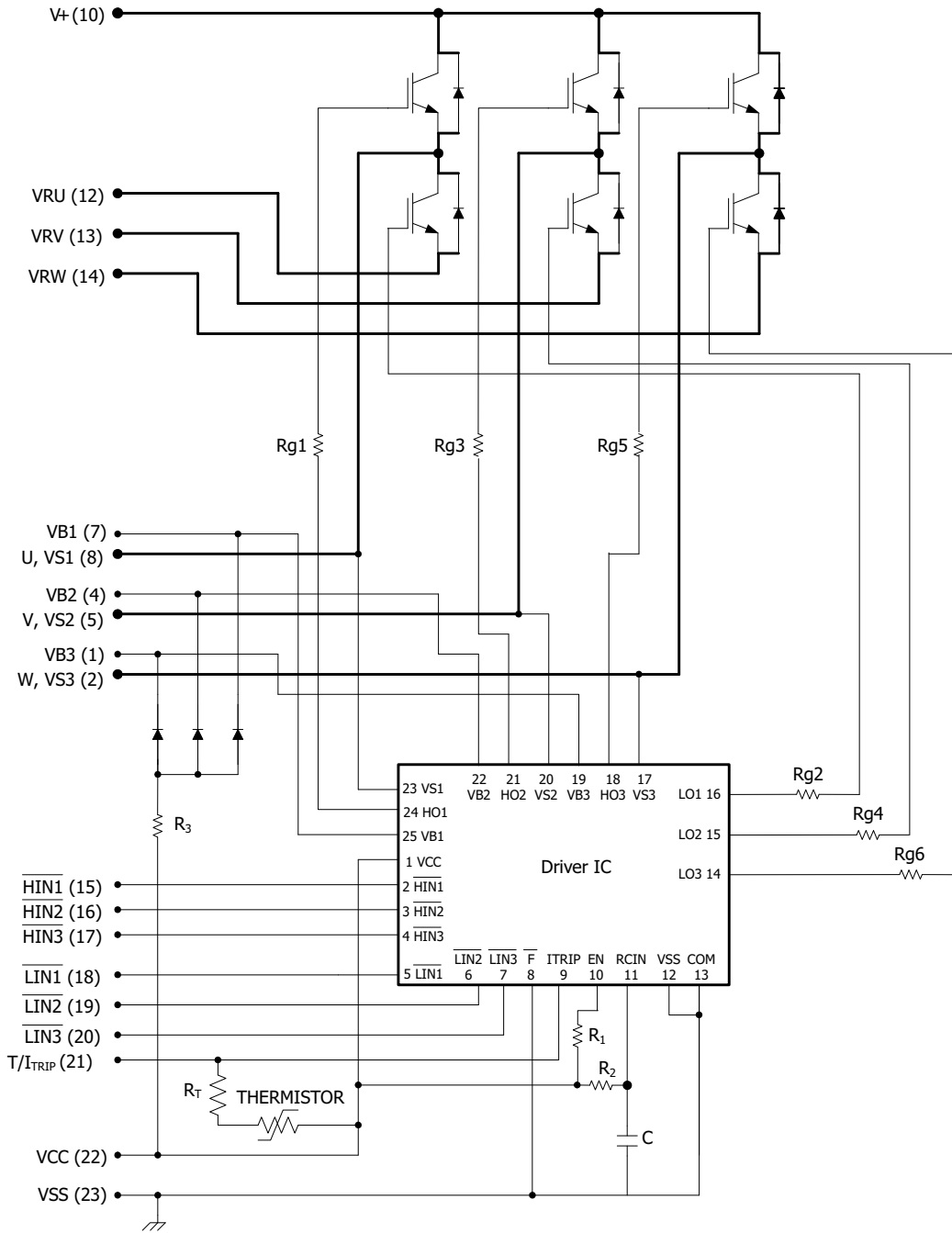
| Parameter | Description | Value | Units |
|-------------------------|---|-------------|------------------|
| V_{CES} / V_{RRM} | IGBT/Diode Blocking Voltage | 600 | V |
| V^+ | Positive Bus Input Voltage | 450 | |
| $I_O @ T_C=25^\circ C$ | RMS Phase Current (Note 1) | 16 | A |
| $I_O @ T_C=100^\circ C$ | RMS Phase Current (Note 1) | 8 | |
| I_O | Pulsed RMS Phase Current (Note 2) | 30 | |
| F_{PWM} | PWM Carrier Frequency | 20 | kHz |
| P_D | Power dissipation per IGBT @ $T_C = 25^\circ C$ | 31 | W |
| V_{ISO} | Isolation Voltage (1min) | 2000 | V _{RMS} |
| T_J (IGBT & Diodes) | Operating Junction temperature Range | -40 to +150 | °C |
| T_J (Driver IC) | Operating Junction temperature Range | -40 to +150 | |
| T | Mounting torque Range (M3 screw) | 0.5 to 1.0 | Nm |

Note 1: Sinusoidal Modulation at $V^+=400V$, $T_J=150^\circ C$, $F_{PWM}=16kHz$, Modulation Depth=0.8, PF=0.6, See Figure 3.

Note 2: $t_p < 100ms$; $T_C=25^\circ C$; $F_{PWM}=16kHz$. Limited by $I_{BUS-ITRIP}$, see Table "Inverter Section Electrical Characteristics"

IRAMX16UP60A

Internal Electrical Schematic - IRAMX16UP60A



Absolute Maximum Ratings (Continued)

All voltages are absolute referenced to COM

| Symbol | Parameter | Min | Max | Units | Conditions |
|-----------------------|--|-------------------|--|-------|--|
| I_{BDF} | Bootstrap Diode Peak Forward Current | --- | 4.5 | A | $t_p = 10\text{ms}$, $T_J = 150^\circ\text{C}$, $T_C = 100^\circ\text{C}$ |
| $P_{BR \text{ Peak}}$ | Bootstrap Resistor Peak Power (Single Pulse) | --- | 25.0 | W | $t_p = 100\mu\text{s}$, $T_C = 100^\circ\text{C}$ ESR / ERJ series |
| $V_{S1,2,3}$ | High side floating supply offset voltage | $V_{B1,2,3} - 25$ | $V_{B1,2,3} + 0.3$ | V | |
| $V_{B1,2,3}$ | High side floating supply voltage | -0.3 | 600 | V | |
| V_{CC} | Low Side and logic fixed supply voltage | -0.3 | 20 | V | |
| V_{IN}, V_{EN} | Input voltage LIN, HIN, EN | -0.3 | Lower of ($V_{SS} + 15\text{V}$) or $V_{CC} + 0.3\text{V}$ | V | |

Inverter Section Electrical Characteristics @ $T_J = 25^\circ\text{C}$

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|---------------------------------|---|-----|------|---------|---------------------|---|
| $V_{(BR)CES}$ | Collector-to-Emitter Breakdown Voltage | 600 | --- | --- | V | $V_{IN} = 5\text{V}$, $I_C = 250\mu\text{A}$ |
| $\Delta V_{(BR)CES} / \Delta T$ | Temperature Coeff. Of Breakdown Voltage | --- | 0.3 | --- | V/ $^\circ\text{C}$ | $V_{IN} = 5\text{V}$, $I_C = 1.0\text{mA}$ ($25^\circ\text{C} - 150^\circ\text{C}$) |
| $V_{CE(ON)}$ | Collector-to-Emitter Saturation Voltage | --- | 1.55 | 1.85 | V | $I_C = 8\text{A}$, $V_{CC} = 15\text{V}$ |
| | | --- | 1.80 | 2.10 | | $I_C = 8\text{A}$, $V_{CC} = 15\text{V}$, $T_J = 150^\circ\text{C}$ |
| I_{CES} | Zero Gate Voltage Collector Current | --- | 5 | 80 | μA | $V_{IN} = 5\text{V}$, $V^+ = 600\text{V}$ |
| | | --- | 165 | --- | | $V_{IN} = 5\text{V}$, $V^+ = 600\text{V}$, $T_J = 150^\circ\text{C}$ |
| V_{FM} | Diode Forward Voltage Drop | --- | 2.0 | 2.4 | V | $I_C = 8\text{A}$ |
| | | --- | 1.4 | 1.9 | | $I_C = 8\text{A}$, $T_J = 150^\circ\text{C}$ |
| V_{BDFM} | Bootstrap Diode Forward Voltage Drop | -- | -- | 1.25 | V | $I_F = 1\text{A}$ |
| | | --- | --- | 1.10 | | $I_F = 1\text{A}$, $T_J = 125^\circ\text{C}$ |
| R_{BR} | Bootstrap Resistor Value | --- | 22 | --- | Ω | $T_J = 25^\circ\text{C}$ |
| $\Delta R_{BR}/R_{BR}$ | Bootstrap Resistor Tolerance | --- | --- | ± 5 | % | $T_J = 25^\circ\text{C}$ |

Inverter Section Switching Characteristics @ $T_J = 25^\circ\text{C}$

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|-----------|-----------------------------------|-------------|-----|------|---------------|--|
| E_{ON} | Turn-On Switching Loss | --- | 315 | 435 | μJ | $I_C=8\text{A}$, $V^+=400\text{V}$ $V_{CC}=15\text{V}$, $L=2\text{mH}$ Energy losses include "tail" and diode reverse recovery |
| E_{OFF} | Turn-Off Switching Loss | --- | 150 | 180 | | |
| E_{TOT} | Total Switching Loss | --- | 465 | 615 | | |
| E_{REC} | Diode Reverse Recovery energy | --- | 30 | 60 | | |
| t_{RR} | Diode Reverse Recovery time | --- | 70 | 90 | ns | See CT1 |
| E_{ON} | Turn-on Switching Loss | --- | 500 | 700 | μJ | $I_C=8\text{A}$, $V^+=400\text{V}$ $V_{CC}=15\text{V}$, $L=2\text{mH}$, $T_J=150^\circ\text{C}$ Energy losses include "tail" and diode reverse recovery |
| E_{OFF} | Turn-off Switching Loss | --- | 270 | 335 | | |
| E_{TOT} | Total Switching Loss | --- | 770 | 1035 | | |
| E_{REC} | Diode Reverse Recovery energy | --- | 60 | 100 | | |
| t_{RR} | Diode Reverse Recovery time | --- | 120 | 150 | ns | See CT1 |
| Q_G | Turn-On IGBT Gate Charge | --- | 56 | 84 | nC | $I_C=15\text{A}$, $V^+=400\text{V}$, $V_{GE}=15\text{V}$ |
| RBSOA | Reverse Bias Safe Operating Area | FULL SQUARE | | | | $T_J=150^\circ\text{C}$, $I_C=45\text{A}$, $V_P=600\text{V}$ $V^+=450\text{V}$ $V_{CC}=+15\text{V}$ to 0V See CT3 |
| SCSOA | Short Circuit Safe Operating Area | 10 | --- | --- | μs | $T_J=150^\circ\text{C}$, $V_P=600\text{V}$, $V^+=360\text{V}$, $V_{CC}=+15\text{V}$ to 0V See CT2 |
| I_{CSC} | Short Circuit Collector Current | --- | 140 | --- | A | $T_J=150^\circ\text{C}$, $V_P=600\text{V}$, $t_{SC}<10\mu\text{s}$ $V^+=360\text{V}$, $V_{GE}=15\text{V}$ $V_{CC}=+15\text{V}$ to 0V See CT2 |

Recommended Operating Conditions Driver Function

The Input/Output logic timing diagram is shown in Figure 1. For proper operation the device should be used within the recommended conditions. All voltages are absolute referenced to COM. The V_S offset is tested with all supplies biased at 15V differential (Note 3)

| Symbol | Definition | Min | Max | Units |
|---------------|--|----------|------------|-------|
| $V_{B1,2,3}$ | High side floating supply voltage | V_S+12 | V_S+20 | V |
| $V_{S1,2,3}$ | High side floating supply offset voltage | Note 4 | 450 | |
| V_{CC} | Low side and logic fixed supply voltage | 12 | 20 | V |
| $V_{T/ITRIP}$ | T/I_{TRIP} input voltage | V_{SS} | $V_{SS}+5$ | |
| V_{IN} | Logic input voltage LIN, HIN | V_{SS} | $V_{SS}+5$ | V |

Note 3: For more details, see IR21365 data sheet

Note 4: Logic operational for V_S from COM-5V to COM+600V. Logic state held for V_S from COM-5V to COM- V_{BS} . (please refer to DT97-3 for more details)

Static Electrical Characteristics Driver Function

V_{BIAS} (V_{CC} , $V_{BS1,2,3}$)=15V, unless otherwise specified. The V_{IN} and I_{IN} parameters are referenced to COM and are applicable to all six channels. (Note 3)

| Symbol | Definition | Min | Typ | Max | Units |
|---------------------------|---|------|------|------|---------|
| V_{IH} | Logic "0" input voltage | 3.0 | --- | --- | V |
| V_{IL} | Logic "1" input voltage | --- | --- | 0.8 | V |
| V_{CCUV+} , V_{BSUV+} | V_{CC} and V_{BS} supply undervoltage Positive going threshold | 10.6 | 11.1 | 11.6 | V |
| V_{CCUV-} , V_{BSUV-} | V_{CC} and V_{BS} supply undervoltage Negative going threshold | 10.4 | 10.9 | 11.4 | V |
| V_{CCUVH} , V_{BSUVH} | V_{CC} and V_{BS} supply undervoltage lock-out hysteresis | --- | 0.2 | --- | V |
| $V_{IN, Clamp}$ | Input Clamp Voltage (HIN, LIN, T/I _{TRIP}) $I_{IN}=10\mu A$ | 4.9 | 5.2 | 5.5 | V |
| I_{QBS} | Quiescent V_{BS} supply current $V_{IN}=0V$ | --- | --- | 165 | μA |
| I_{QCC} | Quiescent V_{CC} supply current $V_{IN}=0V$ | --- | --- | 3.35 | mA |
| I_{LK} | Offset Supply Leakage Current | --- | --- | 60 | μA |
| I_{IN+} | Input bias current $V_{IN}=5V$ | --- | 200 | 300 | μA |
| I_{IN-} | Input bias current $V_{IN}=0V$ | --- | 100 | 220 | μA |
| T/I_{TRIP+} | T/I _{TRIP} bias current $V_{ITRIP}=5V$ | --- | 30 | 100 | μA |
| T/I_{TRIP-} | T/I _{TRIP} bias current $V_{ITRIP}=0V$ | --- | 0 | 1 | μA |
| $V(T/I_{TRIP})$ | T/I _{TRIP} threshold Voltage | 3.85 | 4.30 | 4.75 | V |
| $V(T/I_{TRIP}, HYS)$ | T/I _{TRIP} Input Hysteresis | --- | 0.07 | --- | V |

Dynamic Electrical Characteristics

Driver only timing unless otherwise specified.

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|----------------|---|-----|-----|------|---------|--|
| T_{ON} | Input to Output propagation turn-on delay time (see fig.11) | --- | 590 | --- | ns | $V_{CC}=V_{BS}= 15V$, $I_C=8A$, $V^+=400V$ |
| T_{OFF} | Input to Output propagation turn-off delay time (see fig. 11) | --- | 660 | --- | ns | |
| T_{FLIN} | Input Filter time (HIN, LIN) | 100 | 200 | --- | ns | $V_{IN}=0$ & $V_{IN}=5V$ |
| $T_{BLT-Trip}$ | I_{TRIP} Blanking Time | 100 | 150 | --- | ns | $V_{IN}=0$ & $V_{IN}=5V$ |
| D_T | Dead Time ($V_{BS}=V_{DD}=15V$) | 220 | 290 | 360 | ns | $V_{BS}=V_{CC}=15V$ |
| M_T | Matching Propagation Delay Time (On & Off) | --- | 40 | 75 | ns | $V_{CC}= V_{BS}= 15V$, external dead time > 400ns |
| T_{ITrip} | I_{Trip} to six switch to turn-off propagation delay (see fig. 2) | --- | --- | 1.75 | μs | $V_{CC}=V_{BS}= 15V$, $I_C=8A$, $V^+=400V$ |
| $T_{FLT-CLR}$ | Post I_{Trip} to six switch to turn-off clear time (see fig. 2) | --- | 7.7 | --- | ms | $T_C = 25^\circ C$ |
| | | --- | 6.7 | --- | | $T_C = 100^\circ C$ |

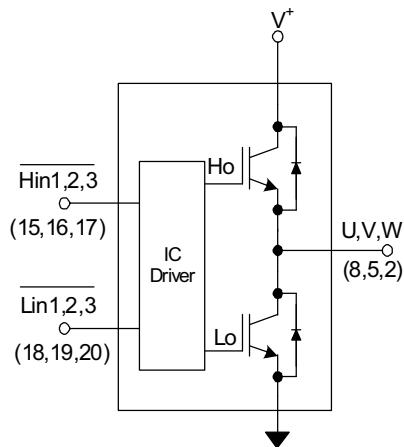
Thermal and Mechanical Characteristics

| Symbol | Parameter | Min | Typ | Max | Units | Conditions |
|---------------|-------------------------------|-----|-----|-----|-------|---|
| $R_{th(J-C)}$ | Thermal resistance, per IGBT | --- | 3.5 | 4.0 | °C/W | Flat, greased surface. Heatsink compound thermal conductivity 1W/mK |
| $R_{th(J-C)}$ | Thermal resistance, per Diode | --- | 5.0 | 5.5 | | |
| $R_{th(C-S)}$ | Thermal resistance, C-S | --- | 0.1 | --- | | |
| C_D | Creepage Distance | 3.2 | --- | --- | mm | See outline Drawings |

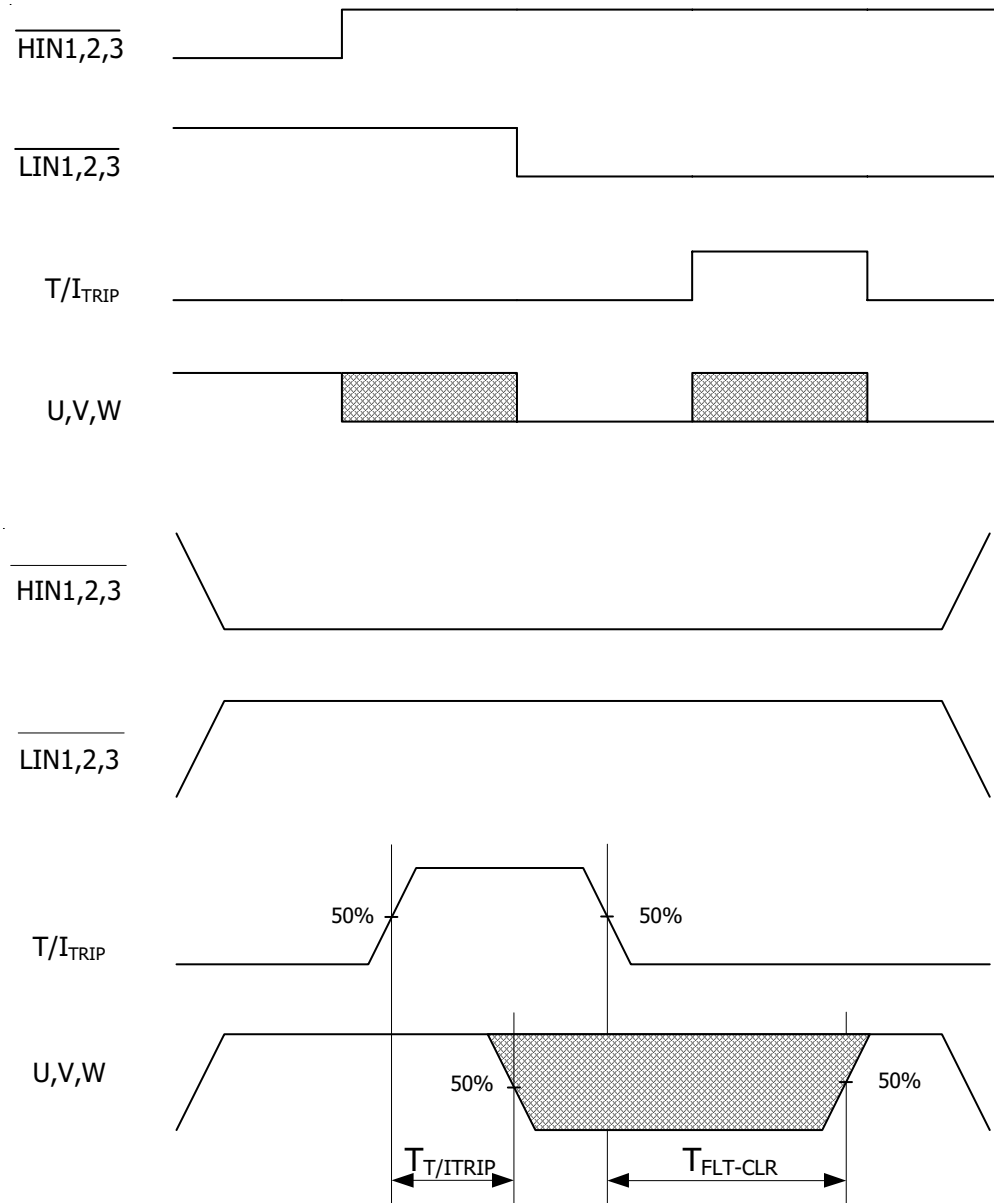
Internal NTC - Thermistor Characteristics

| Parameter | Definition | Min | Typ | Max | Units | Conditions |
|---------------------------|----------------------|------|------|------|------------|------------------------------------|
| R_{25} | Resistance | 97 | 100 | 103 | k Ω | $T_C = 25^\circ\text{C}$ |
| R_{125} | Resistance | 2.25 | 2.52 | 2.80 | k Ω | $T_C = 125^\circ\text{C}$ |
| B | B-constant (25-50°C) | 4165 | 4250 | 4335 | k | $R_2 = R_1 e^{[B(1/T_2 - 1/T_1)]}$ |
| Temperature Range | | -40 | | 125 | °C | |
| Typ. Dissipation constant | | | 1 | | mW/°C | $T_C = 25^\circ\text{C}$ |

Input-Output Logic Level Table



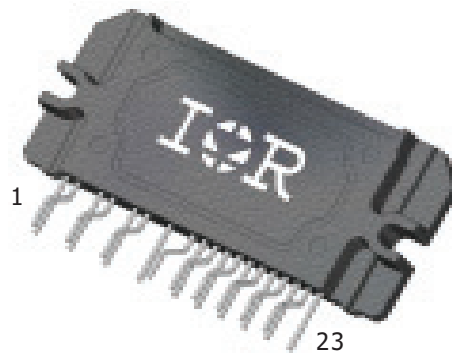
| FLT- EN | I_{TRIP} | $\overline{HIN1,2,3}$ | $\overline{LIN1,2,3}$ | U,V,W |
|---------|------------|-----------------------|-----------------------|-------|
| 1 | 0 | 0 | 1 | V^+ |
| 1 | 0 | 1 | 0 | 0 |
| 1 | 0 | 1 | 1 | Off |
| 1 | 1 | X | X | Off |
| 0 | X | X | X | Off |



Note 5: The shaded area indicates that both high-side and low-side switches are off and therefore the half-bridge output voltage would be determined by the direction of current flow in the load.

Module Pin-Out Description

| Pin | Name | Description |
|-----|----------------------|---|
| 1 | V_{B3} | High Side Floating Supply Voltage 3 |
| 2 | W, V_{S3} | Output 3 - High Side Floating Supply Offset Voltage |
| 3 | NA | none |
| 4 | V_{B2} | High Side Floating Supply voltage 2 |
| 5 | V, V_{S2} | Output 2 - High Side Floating Supply Offset Voltage |
| 6 | NA | none |
| 7 | V_{B1} | High Side Floating Supply voltage 1 |
| 8 | U, V_{S1} | Output 1 - High Side Floating Supply Offset Voltage |
| 9 | NA | none |
| 10 | V^+ | Positive Bus Input Voltage |
| 11 | NA | none |
| 12 | L_{E1} | Low Side Emitter Connection - Phase 1 |
| 13 | L_{E2} | Low Side Emitter Connection - Phase 2 |
| 14 | L_{E3} | Low Side Emitter Connection - Phase 3 |
| 15 | \overline{H}_{IN1} | Logic Input High Side Gate Driver - Phase 1 |
| 16 | \overline{H}_{IN2} | Logic Input High Side Gate Driver - Phase 2 |
| 17 | \overline{H}_{IN3} | Logic Input High Side Gate Driver - Phase 3 |
| 18 | \overline{L}_{IN1} | Logic Input Low Side Gate Driver - Phase 1 |
| 19 | \overline{L}_{IN2} | Logic Input Low Side Gate Driver - Phase 2 |
| 20 | \overline{L}_{IN3} | Logic Input Low Side Gate Driver - Phase 3 |
| 21 | T/I_{TRIP} | Temperature Monitor and Shut-down Pin |
| 22 | V_{CC} | +15V Main Supply |
| 23 | V_{SS} | Negative Main Supply |



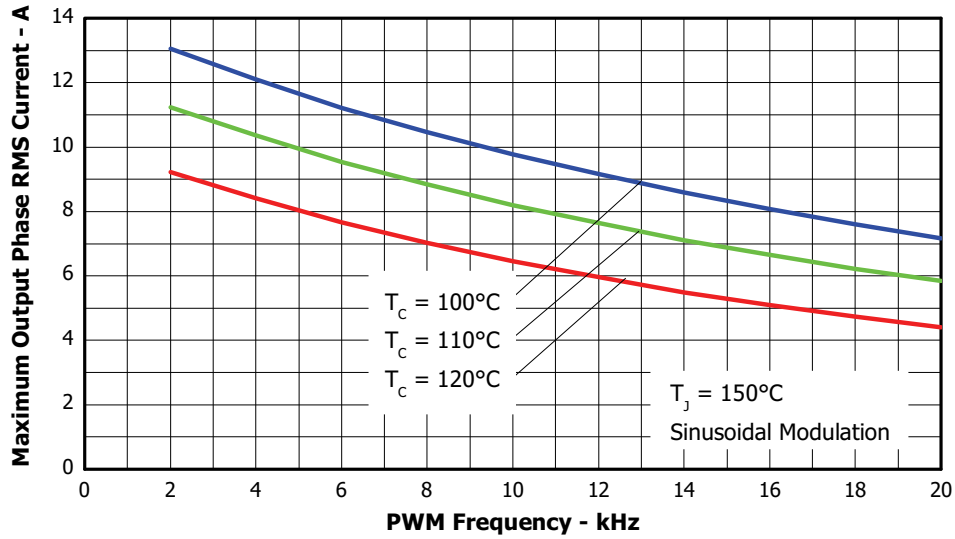


Figure 3. Maximum Sinusoidal Phase Current vs. PWM Switching Frequency
 $V^+ = 400\text{V}$, $T_j = 150^\circ\text{C}$, Modulation Depth=0.8, PF=0.6

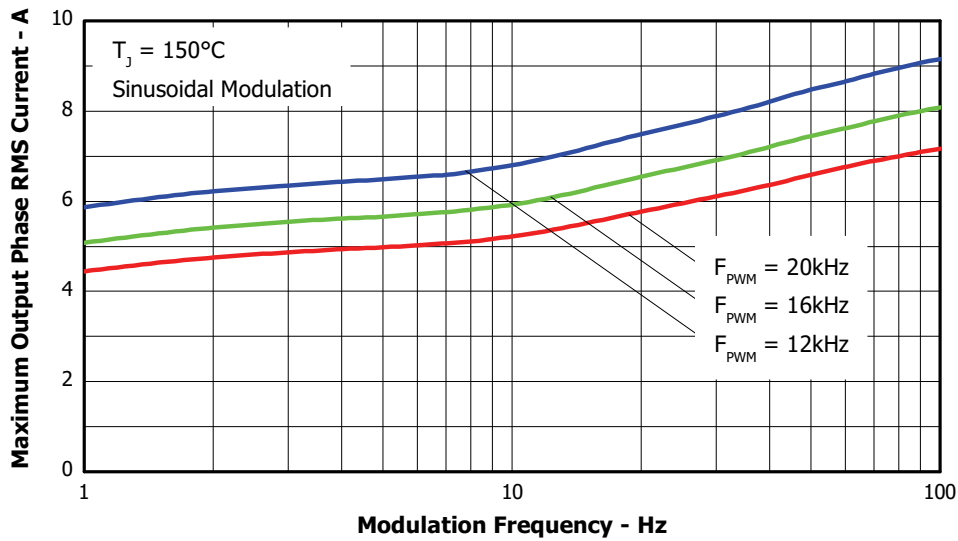


Figure 4. Maximum Sinusoidal Phase Current vs. Modulation Frequency
 $V^+ = 400\text{V}$, $T_j = 150^\circ\text{C}$, $T_c = 100^\circ\text{C}$, Modulation Depth=0.8, PF=0.6

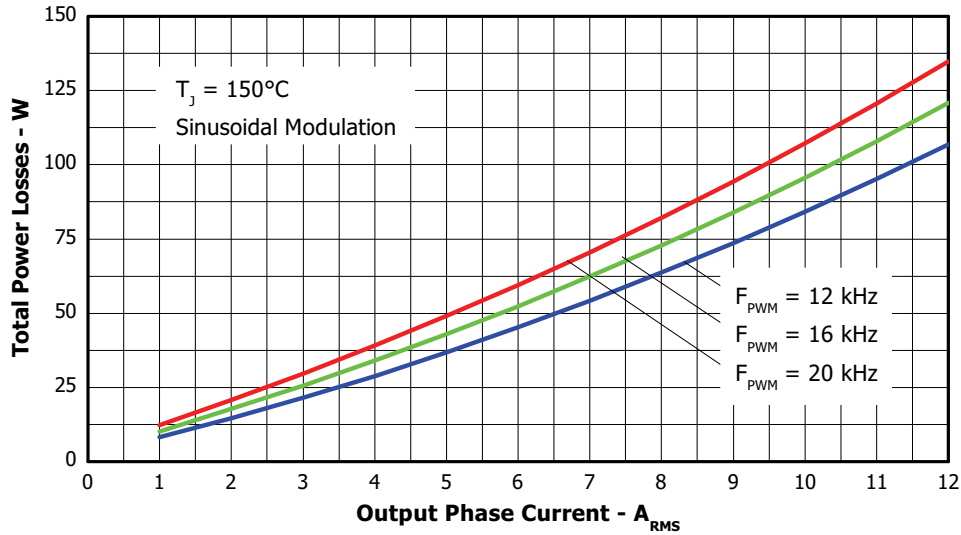


Figure 5. Total Power Losses vs. PWM Switching Frequency, Sinusoidal modulation
 $V^+ = 400V$, $T_J = 150^\circ C$, Modulation Depth=0.8, PF=0.6

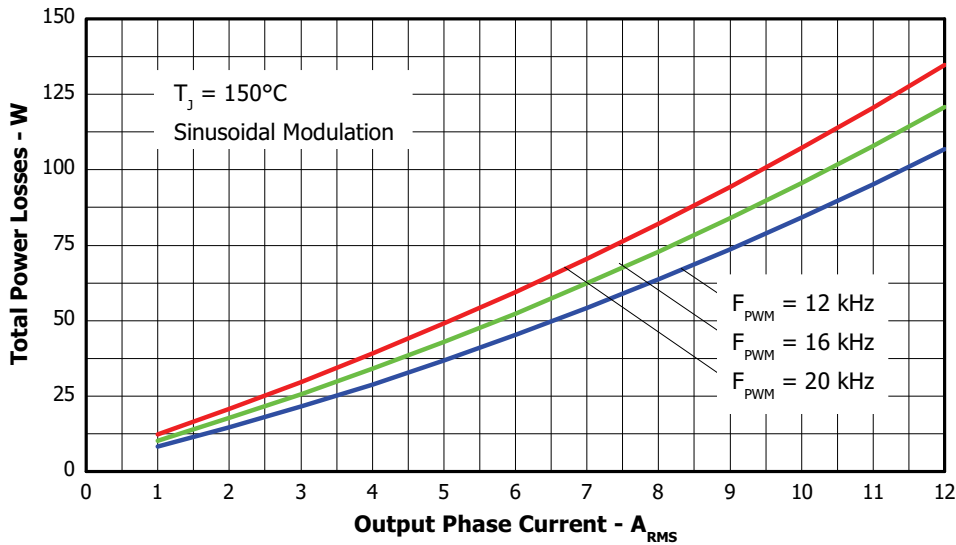


Figure 6. Total Power Losses vs. Output Phase Current, Sinusoidal modulation
 $V_{BUS} = 400V$, $T_J = 150^\circ C$, Modulation Depth=0.8, PF=0.6

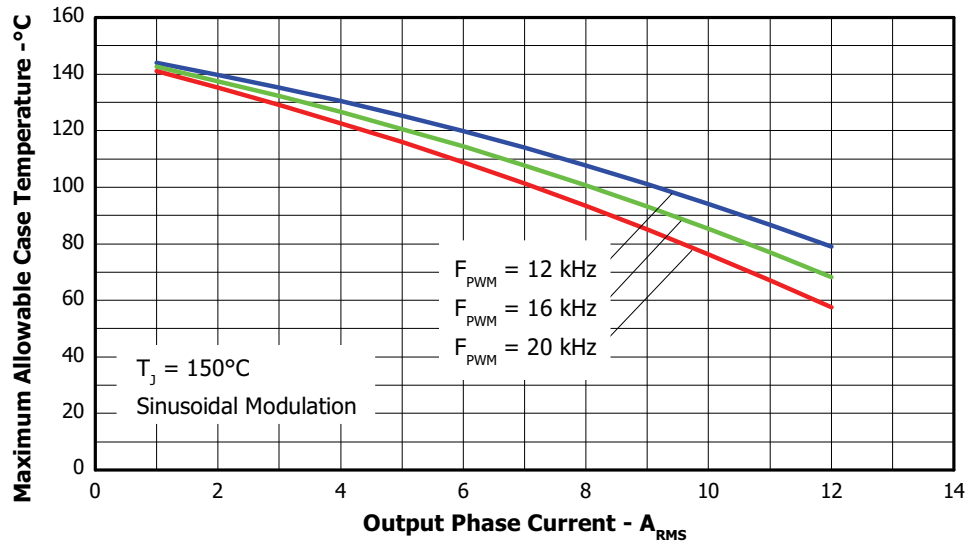


Figure 7. Maximum Allowable Case temperature vs. Output RMS Current per Phase

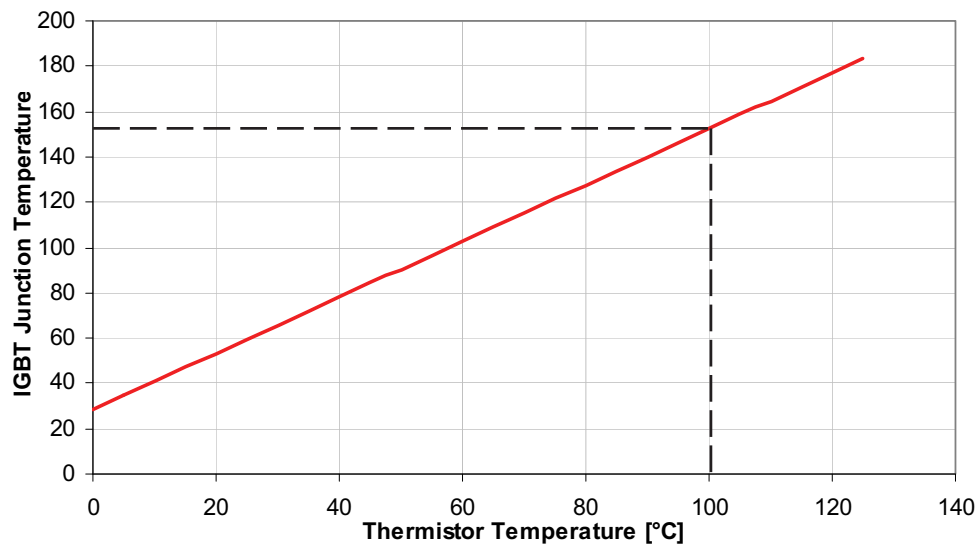


Figure 8. Estimated Maximum IGBT Junction Temperature vs. Thermistor Temperature

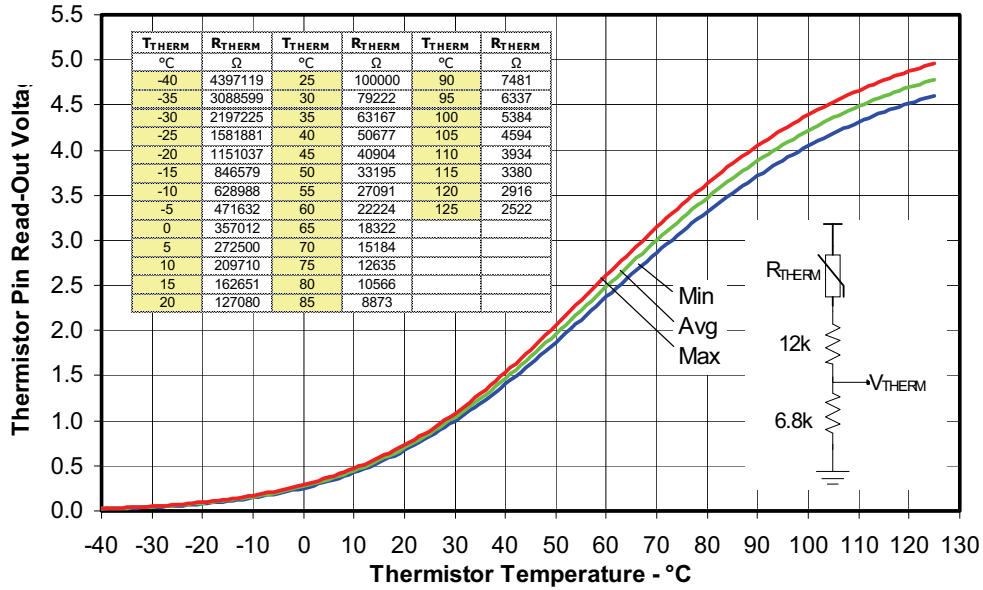


Figure 9. Thermistor Readout vs. Temperature (6.8kohm, 1% pull down resistor) and Nominal Thermistor Resistance values vs. Temperature Table.

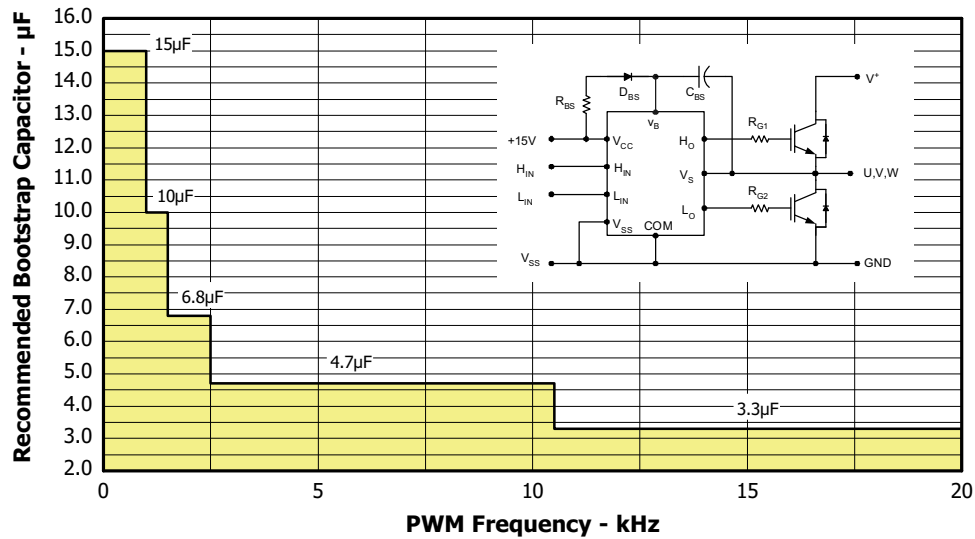


Figure 10. Recommended Bootstrap Capacitor Value vs. Switching Frequency

Figure 11. Switching Parameter Definitions

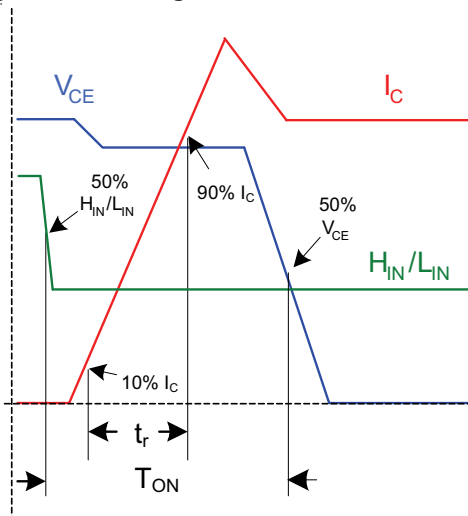


Figure 11a. Input to Output Propagation turn-on Delay Time

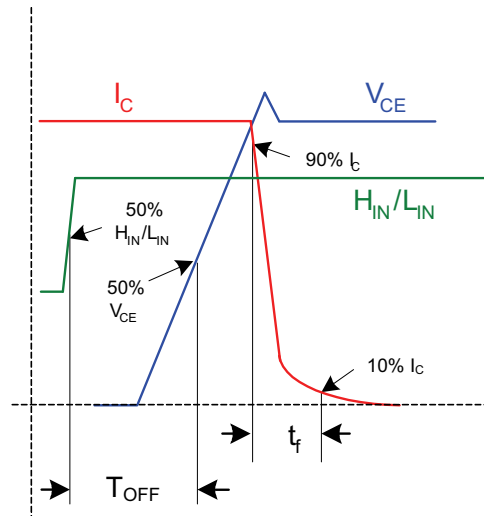


Figure 11b. Input to Output Propagation turn-off Delay Time

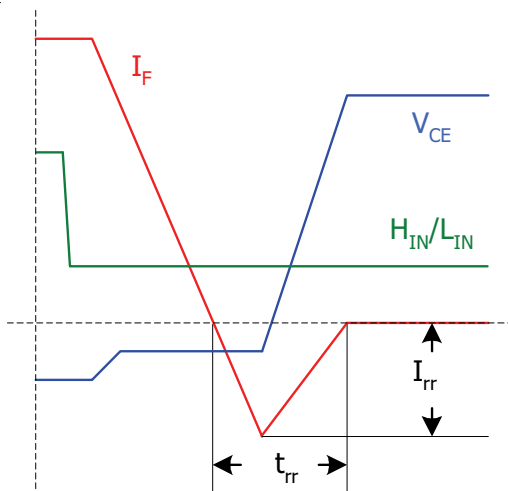


Figure 11c. Diode Reverse Recovery

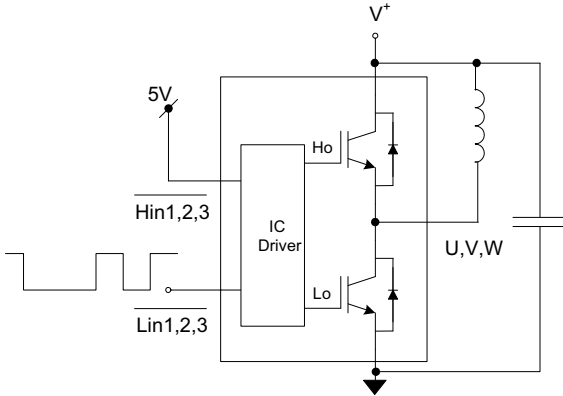


Figure CT1. Switching Loss Circuit

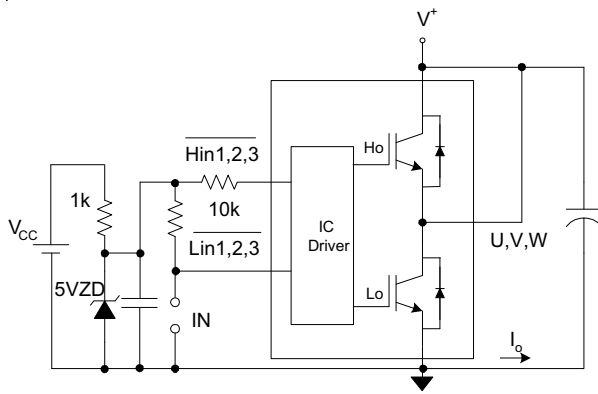
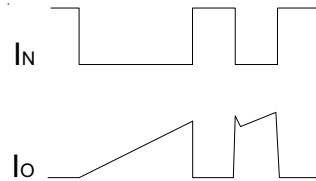


Figure CT2. S.C.SOA Circuit

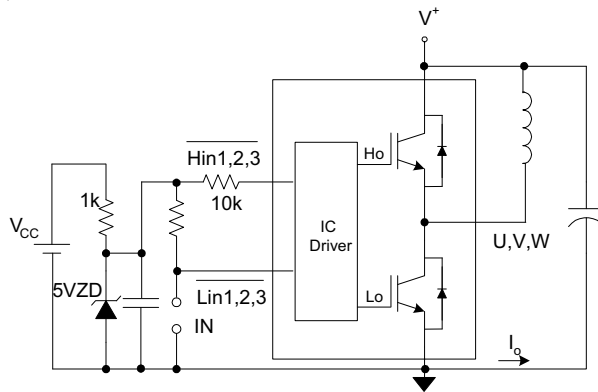
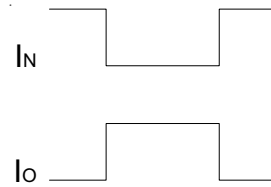
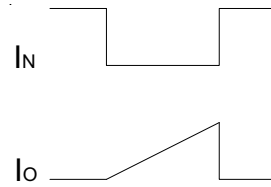


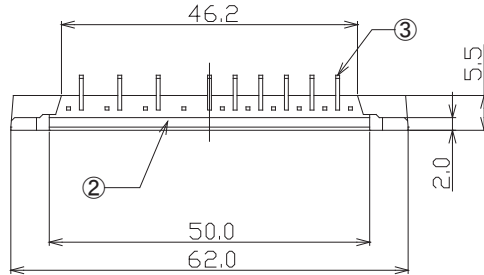
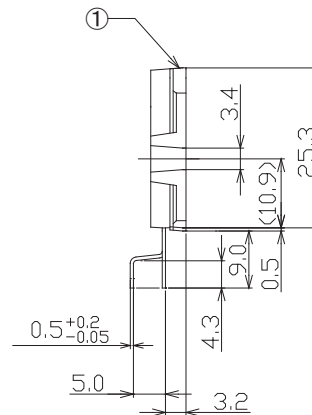
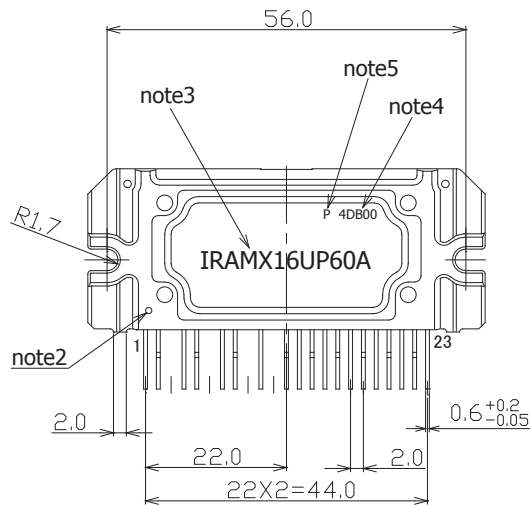
Figure CT3. R.B.SOA Circuit



IRAMX16UP60A

Package Outline IRAMX16UP60A

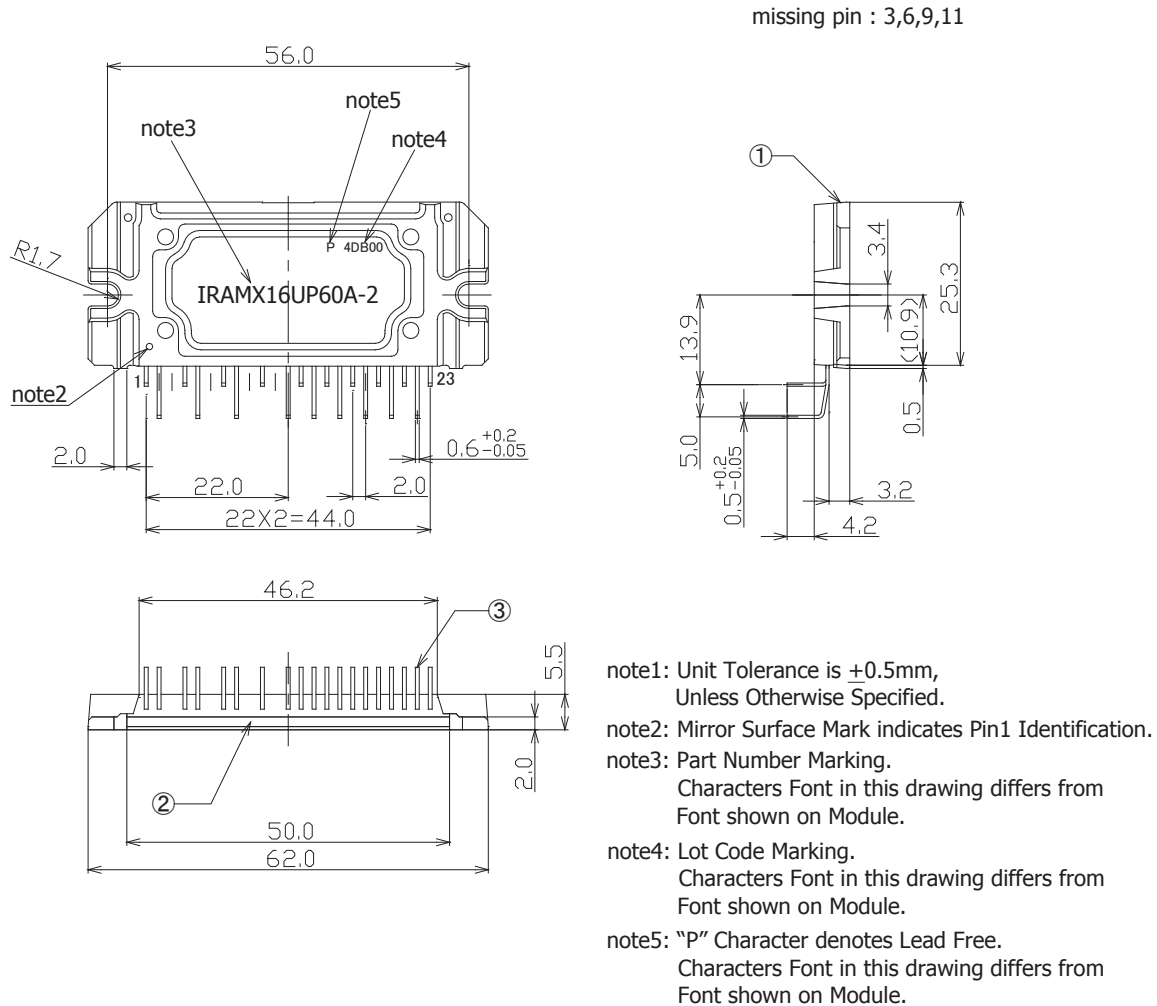
missing pin : 3,6,9,11



- note1: Unit Tolerance is ± 0.5 mm, Unless Otherwise Specified.
- note2: Mirror Surface Mark indicates Pin1 Identification.
- note3: Part Number Marking. Characters Font in this drawing differs from Font shown on Module.
- note4: Lot Code Marking. Characters Font in this drawing differs from Font shown on Module.
- note5: "P" Character denotes Lead Free. Characters Font in this drawing differs from Font shown on Module.

Dimensions in mm
 For mounting instruction see AN-1049

Package Outline IRAMX16UP60A-2



Dimensions in mm
 For mounting instruction see AN-1049